

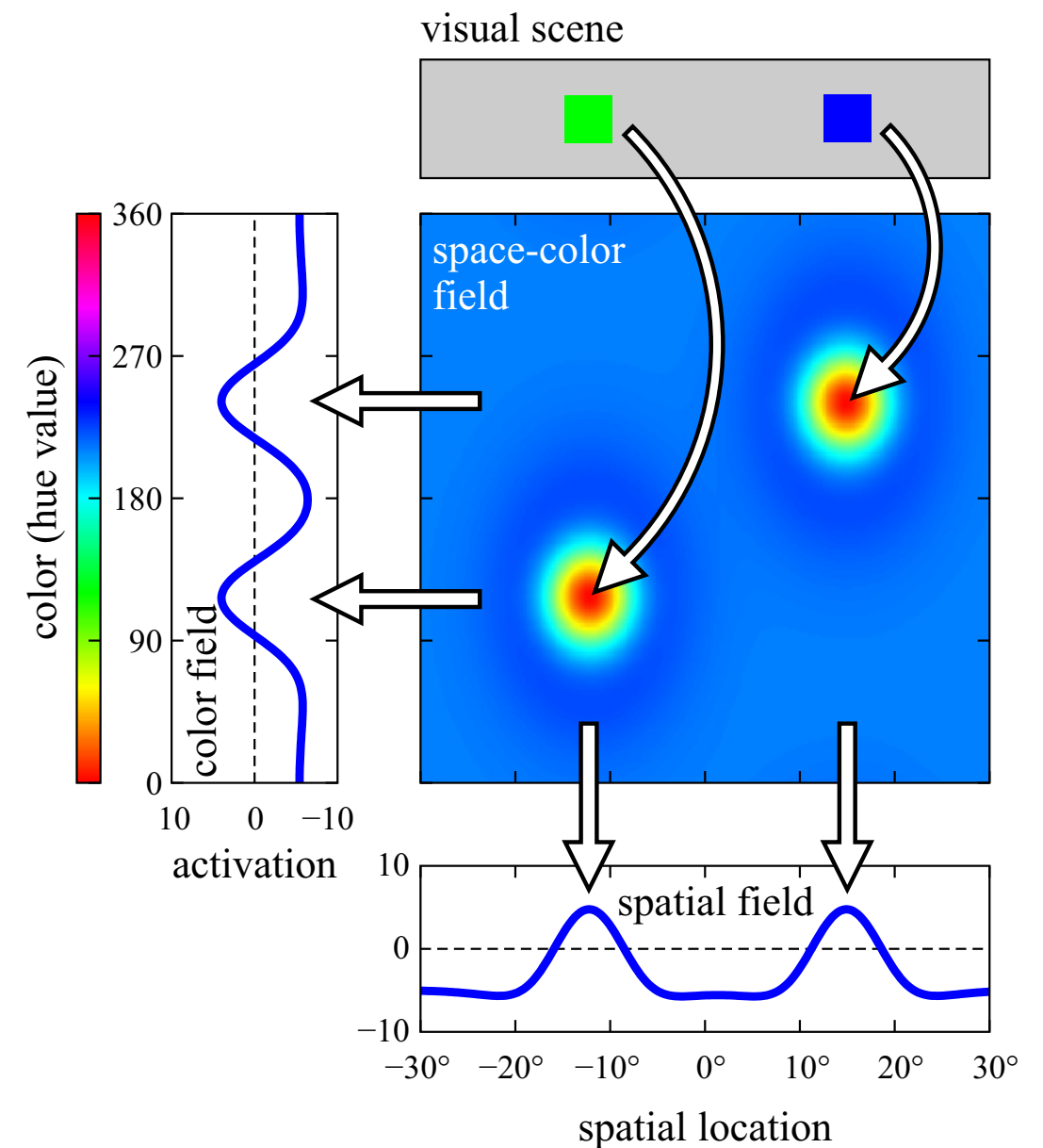
# Grounding Spatial Language:

A case study in Dynamic Field Theory as a  
framework for neurally grounded architectures for  
higher cognition

Gregor Schöner  
Institut für Neuroinformatik  
Ruhr-Universität Bochum, Germany  
[gregor.schoener@rub.de](mailto:gregor.schoener@rub.de)

# Previous lecture

- higher-dimensional neural fields enable new functions
- visual search... attentional selection
- coordinate transforms...
- binding different feature dimensions through space



# Previous lecture

■ => scene representation

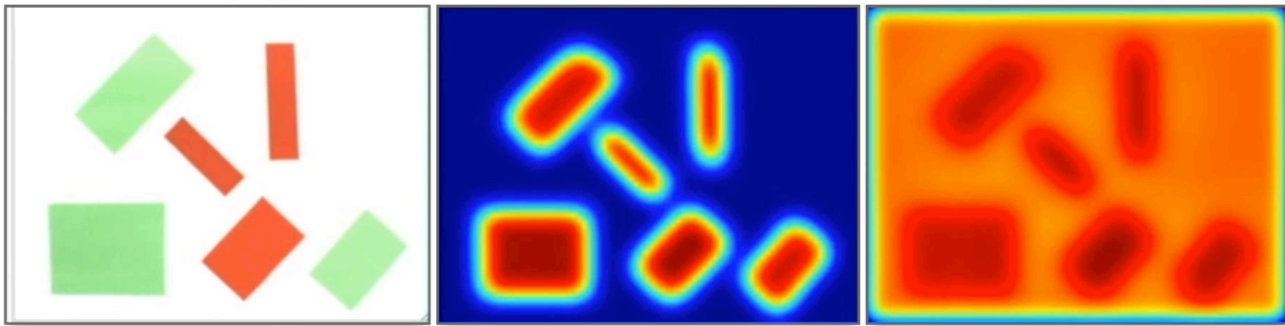
[ Grieben et al, (Attention, Perception, & Psychophysics, in press)]

SALIENCY MAP

CAMERA INPUT

FEED FORWARD SALIENCY MAP

SALIENCY BOOST

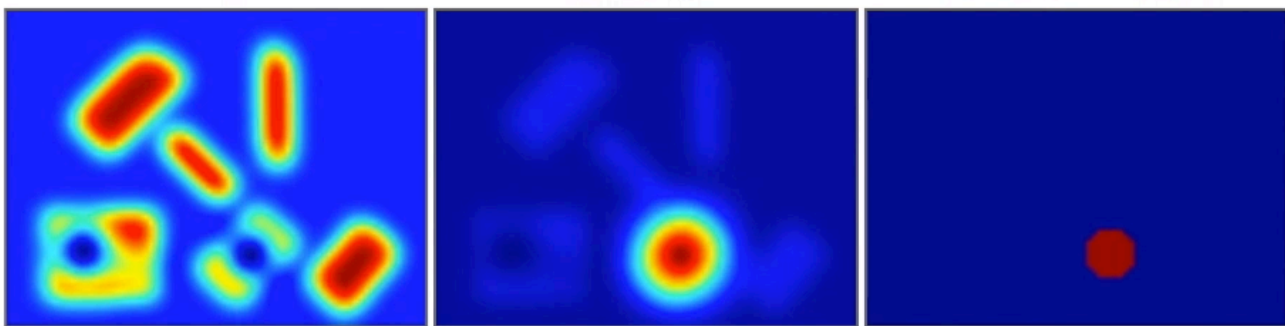


ATTENTION

INPUT

ACTIVATION

SIGMOIDED ACTIVATION



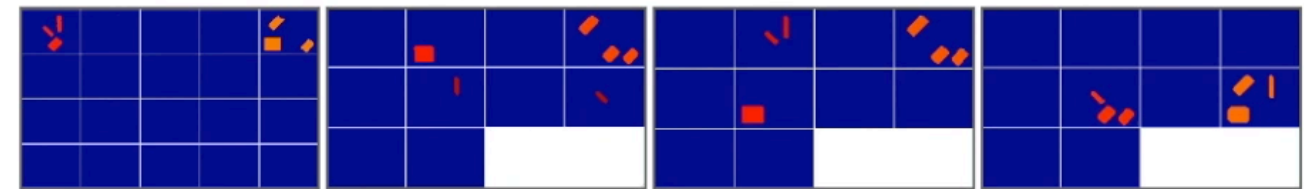
FEATURE MAPS

COLOR

ORIENTATION

WIDTH

LENGTH



FEATURE PROCESSING (ORIENTATION)

ATTENDED

REFERENCE

WORKING MEMORY

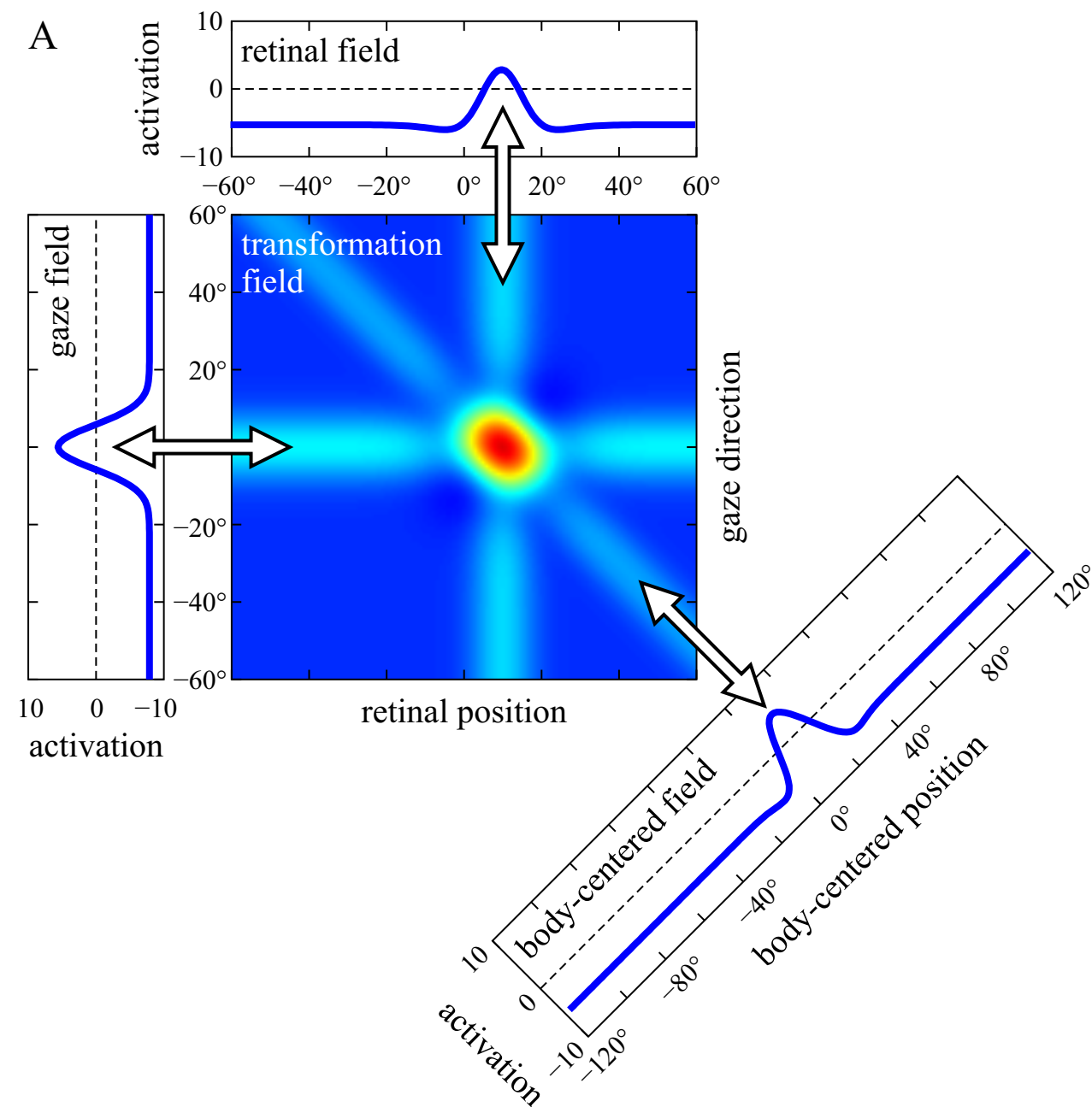
EXPECTED

CHANGE DETECTION



# Previous lecture

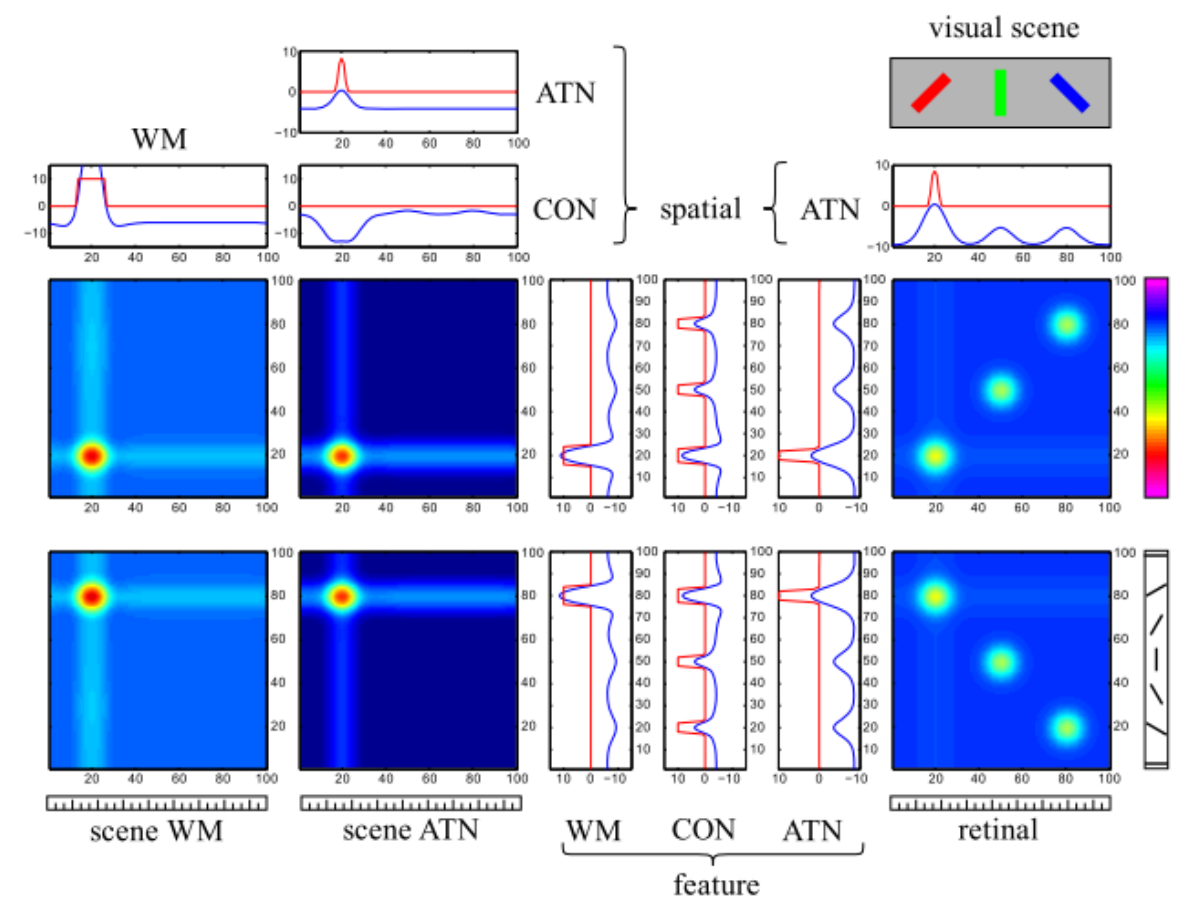
- higher-dimensional neural fields enable new functions
- visual search... attentional selectivity
- coordinate transforms...
- binding different feature dimensions through space





# Previous lecture

- higher-dimensional neural fields enable new functions
- visual search... attentional selection
- coordinate transforms...
- binding different feature dimensions through space

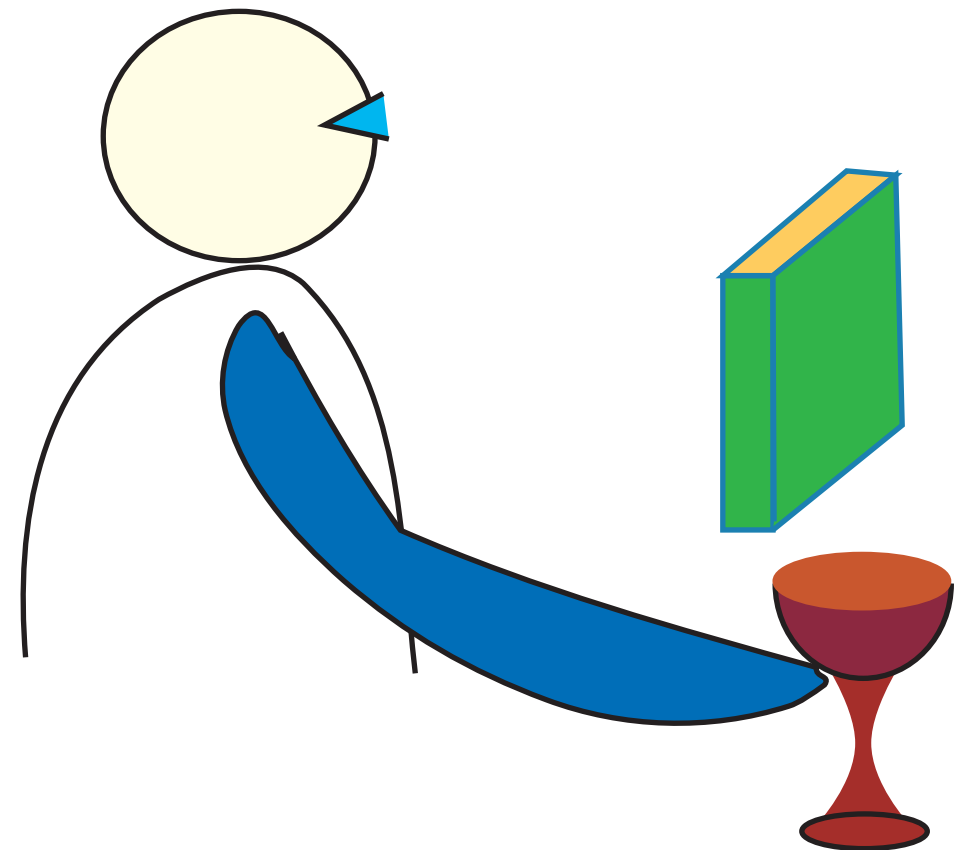


# Today

- illustrate how these functions support lifting neural dynamics to higher cognition
- in the context of the perceptual grounding of concepts/language/relations

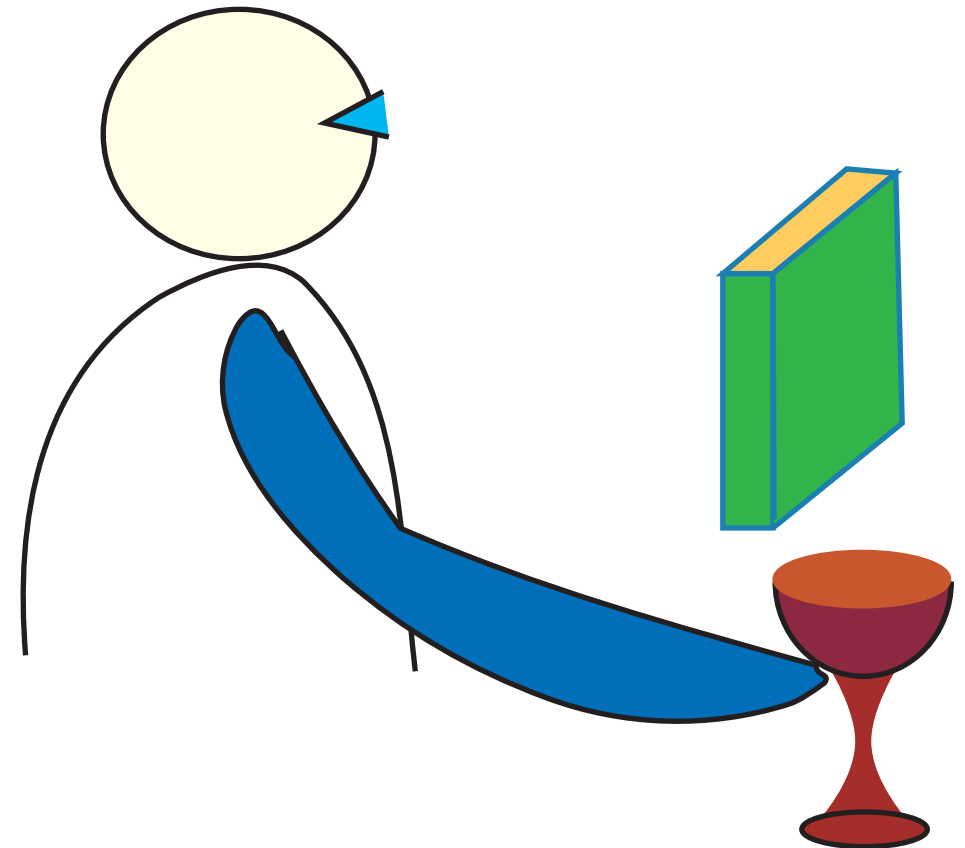
# Perceptually grounding language

- human communication in its simplest form is about things that are out there in our environment, perceivable, reachable by action
- e.g., this cup is brown



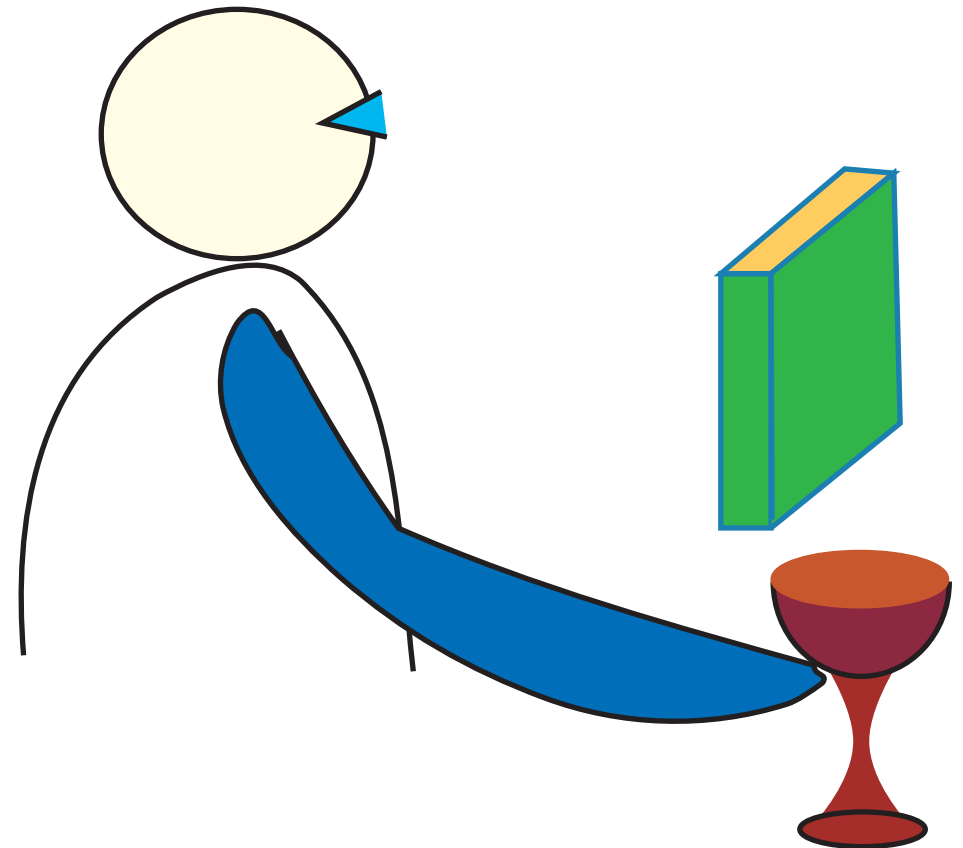
# Perceptually grounding language

- this could be based by both the speaker and the listener looking at the scene and grounding the word “cup” by bringing an object of that category into the foreground
- also called “targetting” (Talmy)



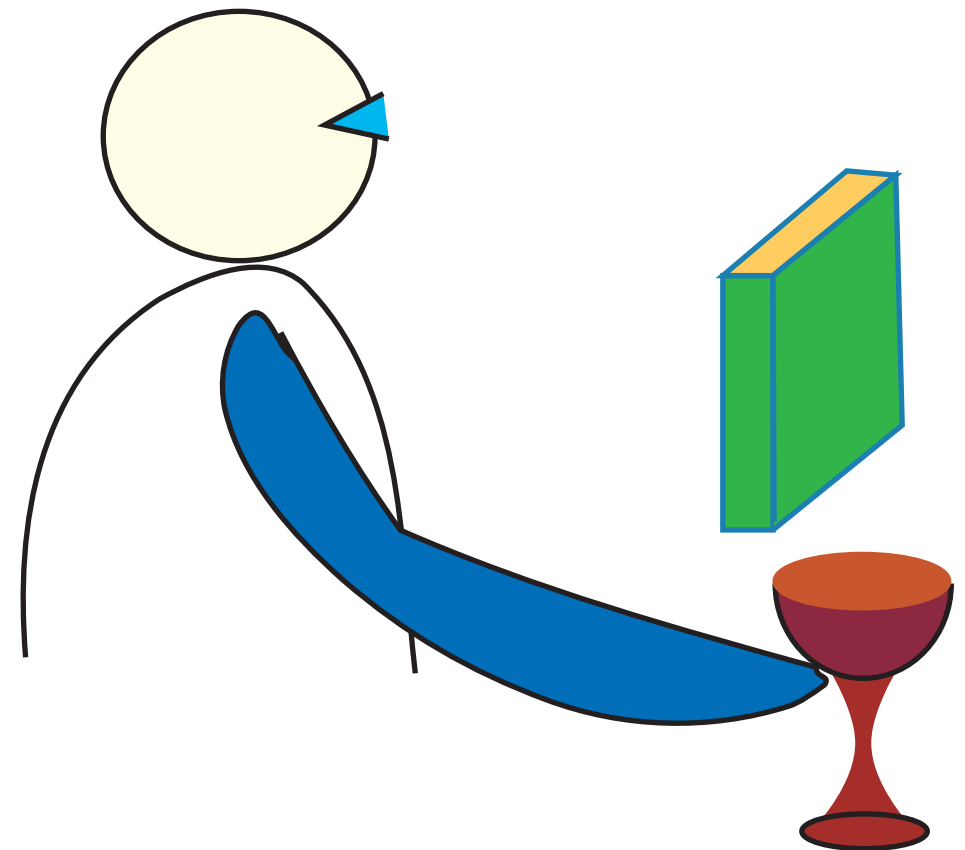
# Perceptually grounding language

- that process could be mediated by other forms of communication, e.g., pointing (deictic code)



# Perceptually grounding language

- that process could also be mediated by spatial language, e.g., “the cup to the right of the green book is brown” (**spatial language**)
- (which presupposes that the reference object “green book” is grounded for speaker and observer)



# Perceptually grounding language vs. describing

- Perceptual grounding: understanding phrases by finding in the visual array the objects to which the phrase refers
- Describing: producing phrases that describe an observed scene or event

“what is to the right of the green object”



# Spatial language

- such utterances as “to the left of”, “on top of”, “in”, “in front of”, “toward the south”, “in front of” etc.
- a part of language that deep: evolves slowly in languages, with profound differences between languages and cultures, that is particularly challenging for “grounding”



# Spatial language

## ■ Examples:

- some cultures use absolute directions “north”, “south” etc. even on a local scale (e.g., “the car north of the house” rather than “the car in front of the house”).
- others have special spatial language referring to geographical landmarks (e.g., islanders who have a word for “toward the beach” vs. “away from the beach, toward the inland”)
- “in front of” is used differently even in different indo-european languages

# Grounding spatial language

- involves necessarily reference frames... there are 4 basic and commonly used reference frames

# Grounding spatial language

- orientation relative to speaker, position centered in speaker

- “on my left”

- orientation relative to world/object, position centered in speaker:

- “north”, “south...” or “leeward”, “windward” ...

- orientation relative to speaker, position centered in object

- “the cup to the right of the bottle”

- orientation relative to object, position centered in object

- “leave the train on the right hand side”

# Grounding spatial language

- reference frames are subtle

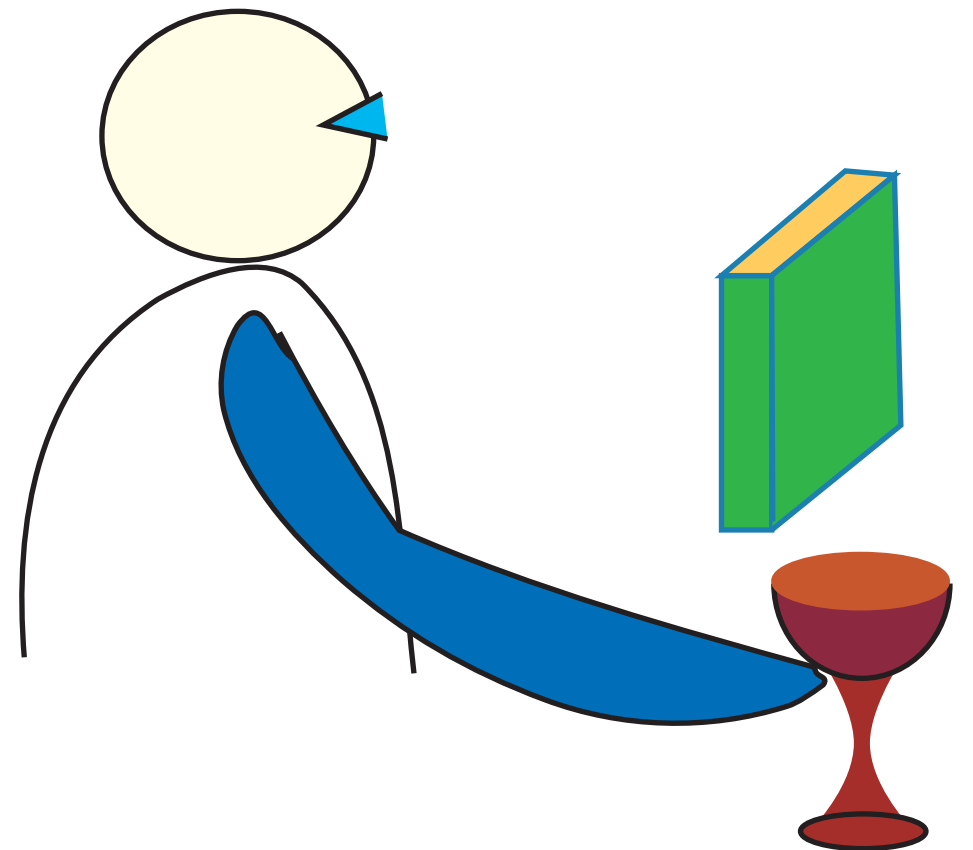
- Example: “in front of” can be in an ego-centric frame if the object has no special long axis and front end (e.g., “in front of the tree” meaning “between me and the tree”)

- but can be in an object centered frame if the object has a long axis and front end (e.g. “in front of the car” meaning “on the side of the car in the direction in which its front end points”)

- (and on this count different languages differ)

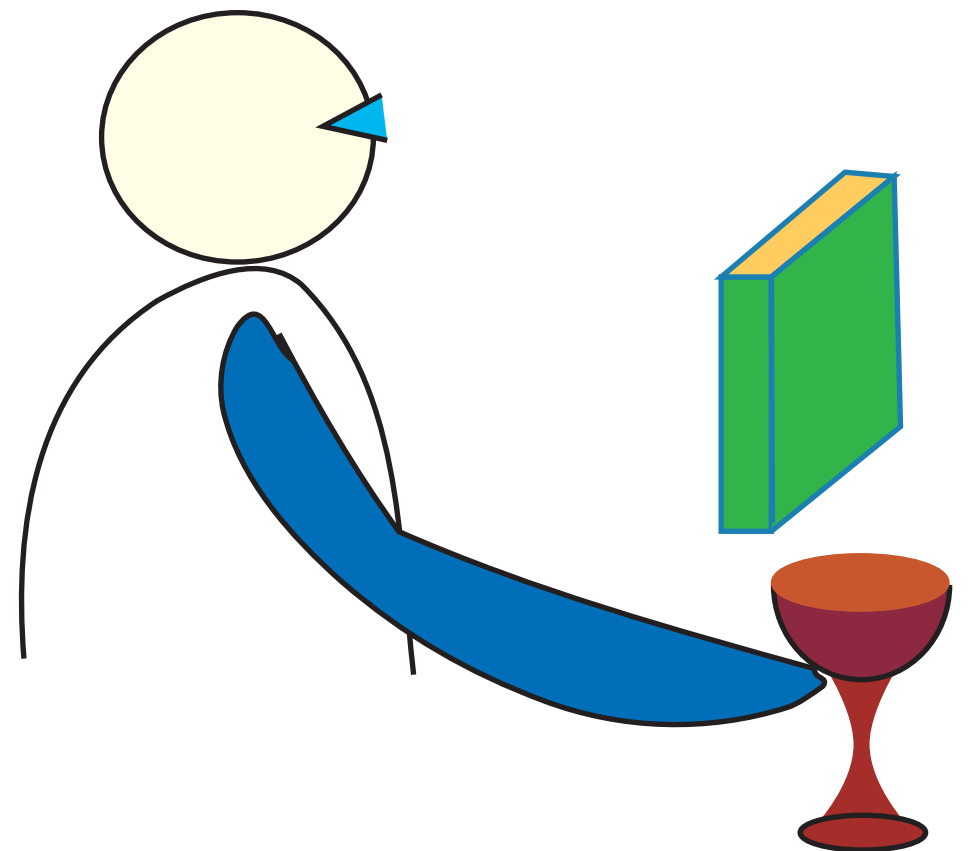
# Grounding spatial language

- spatial language often involves reference objects
- Example: “to the right of the green book”: this is a statement in an ego-centric reference frame for direction but that is spatially centered in an object



# Grounding spatial language

- spatial language often involves coordinate transforms
- e.g., “to the right of the green book”: coordinate transformation: from the speaker/observer centered reference frame into a frame centered in the reference object
- e.g., “to my right” requires the listener to transform the reference frame from his or her own view to the directional and positional frame of the speaker



# Operations involved in grounding spatial language

- bring objects (target and reference) into the perceptual foreground (visually find them)
- make coordinate transformation
- apply comparison operators

# DFT approach to bringing a perceptual object into the foreground

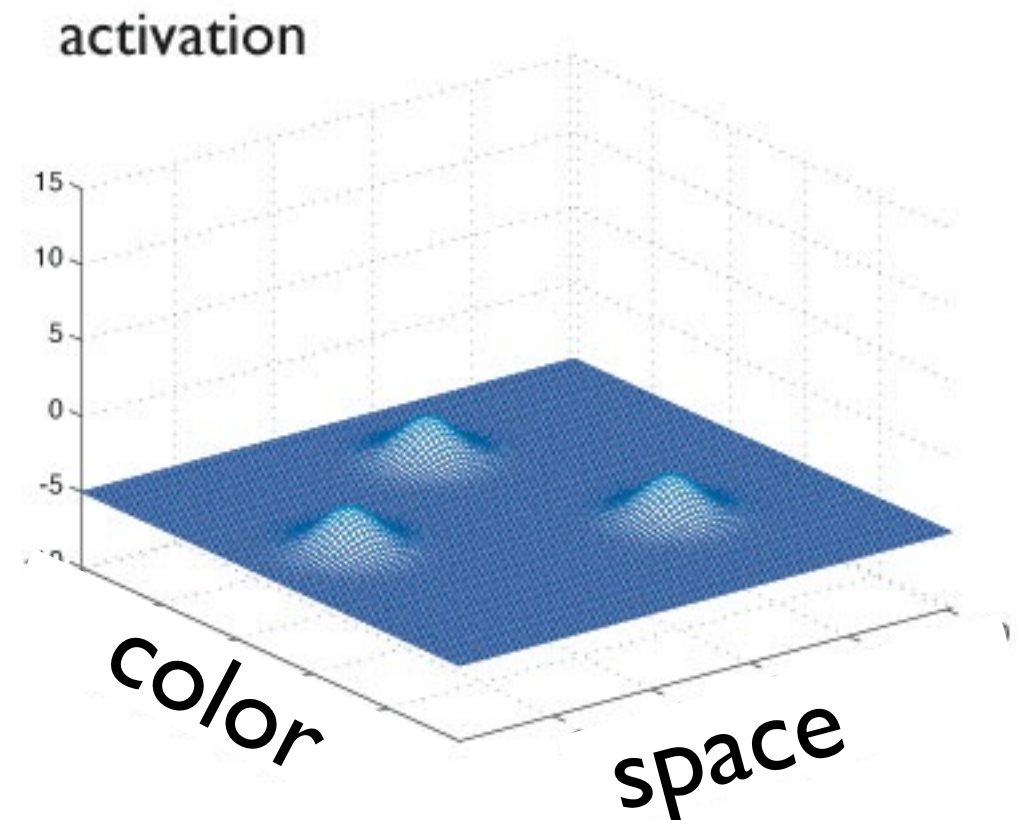
■ => lecture on higher-dimensional fields



# Bringing an object to the foreground



■ visual search:  
“where is the  
red object”?

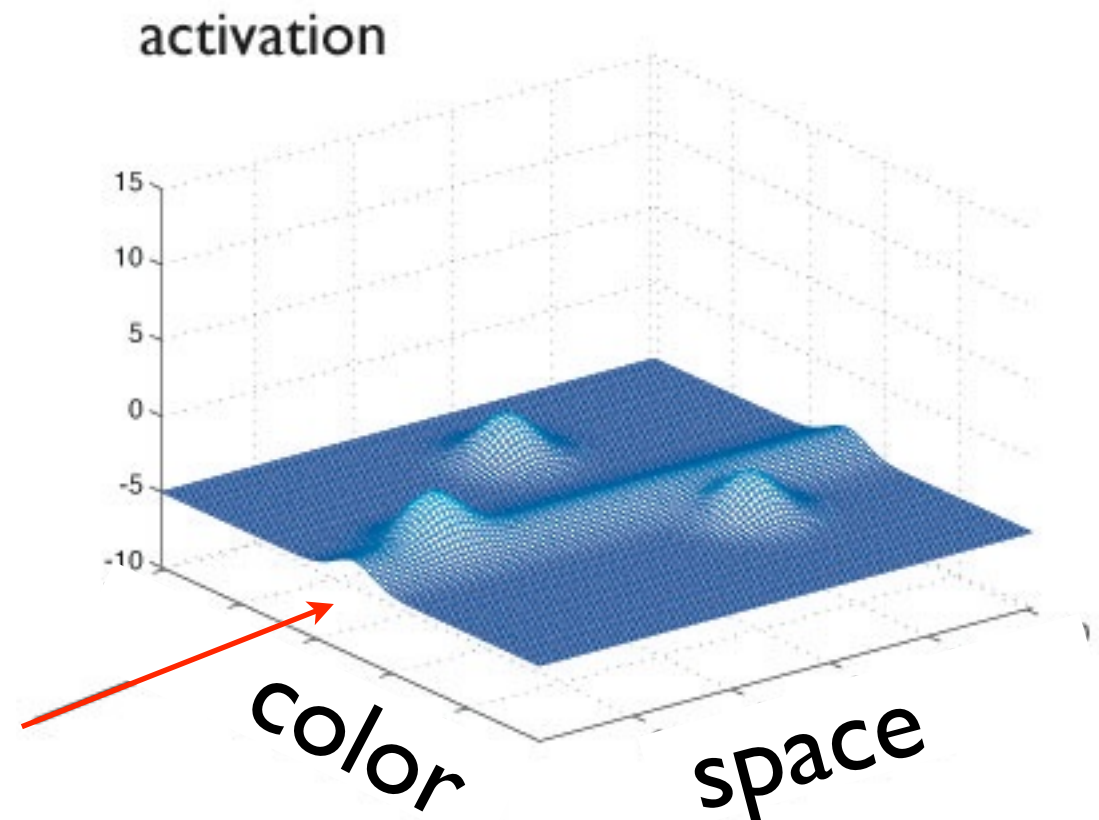


# Bringing an object to the foreground



- visual search:  
“where is the  
red object”?

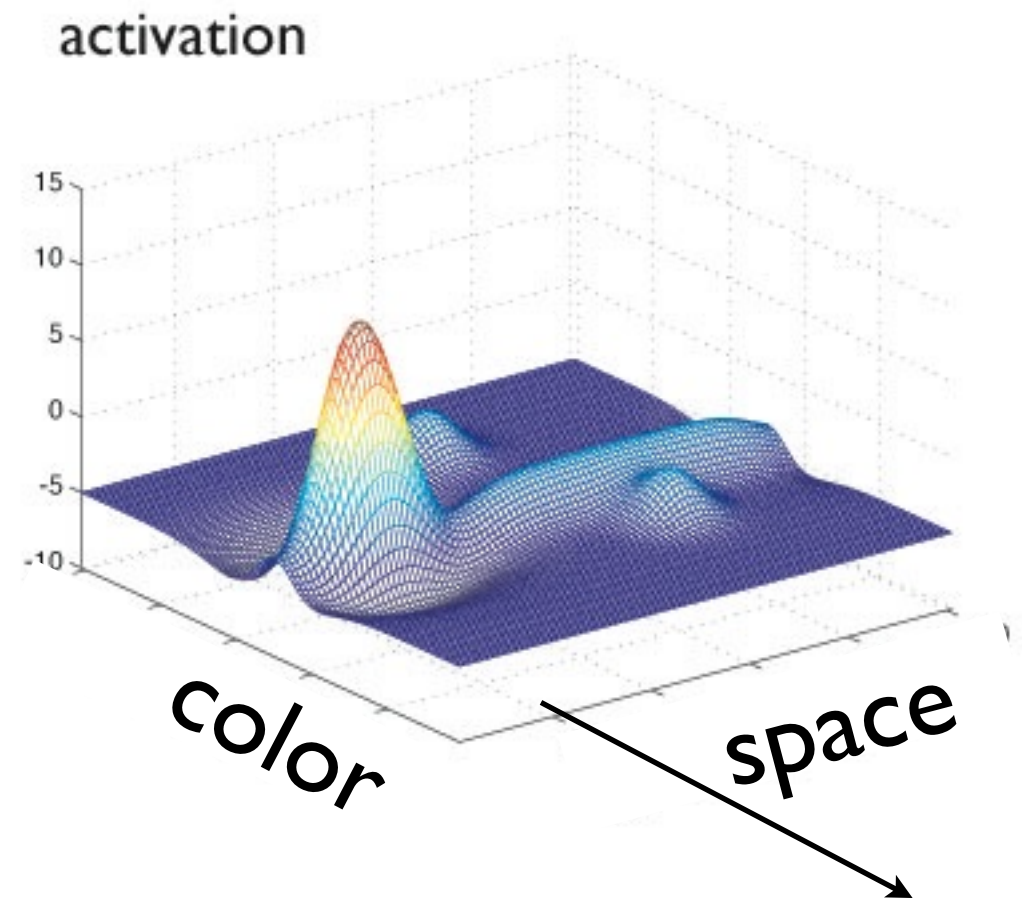
ridge  
specifying  
red



# Bringing an object to the foreground



■ visual search:  
“where is the  
red object”?

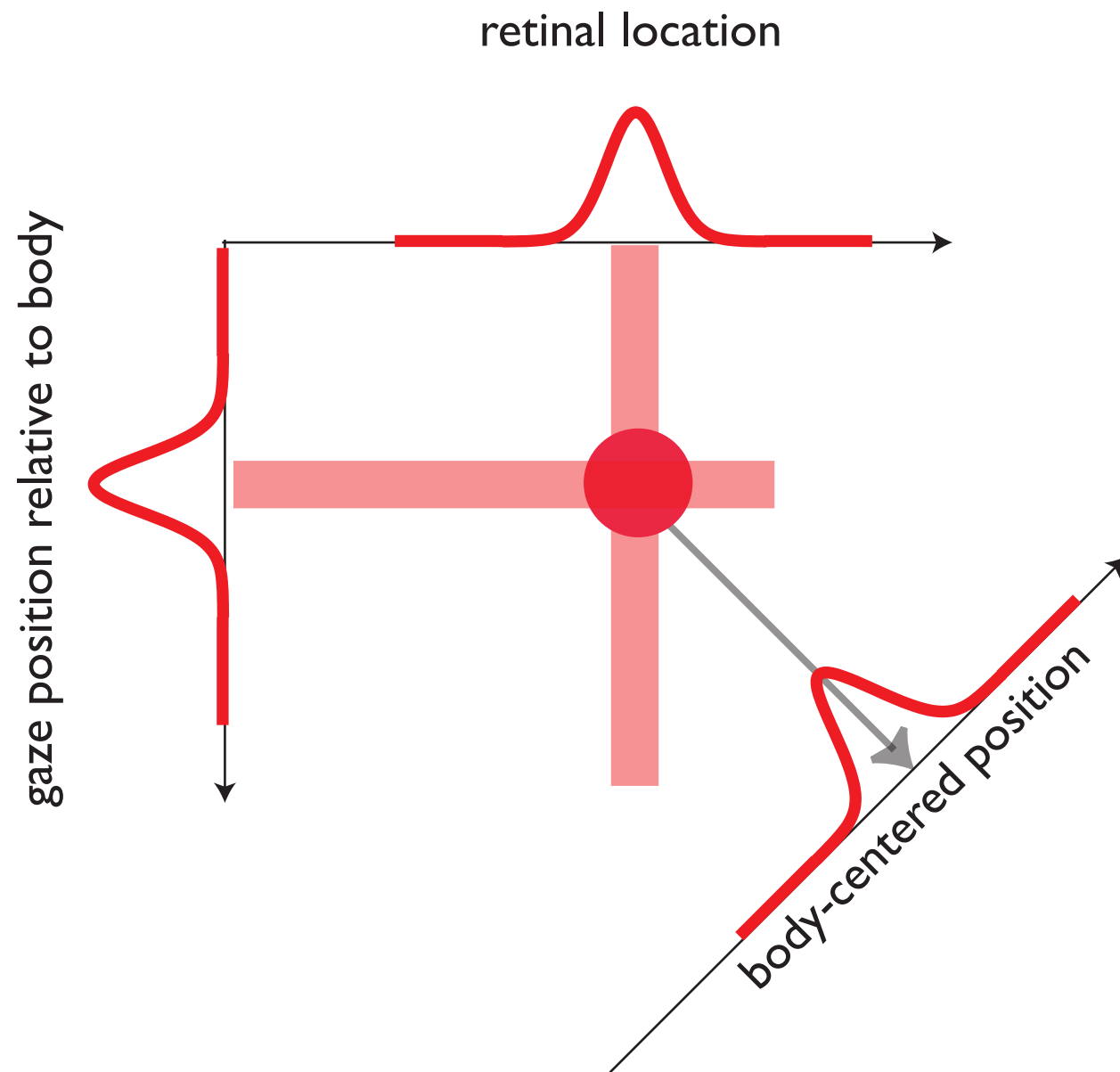


read out spatial  
location  
of red object

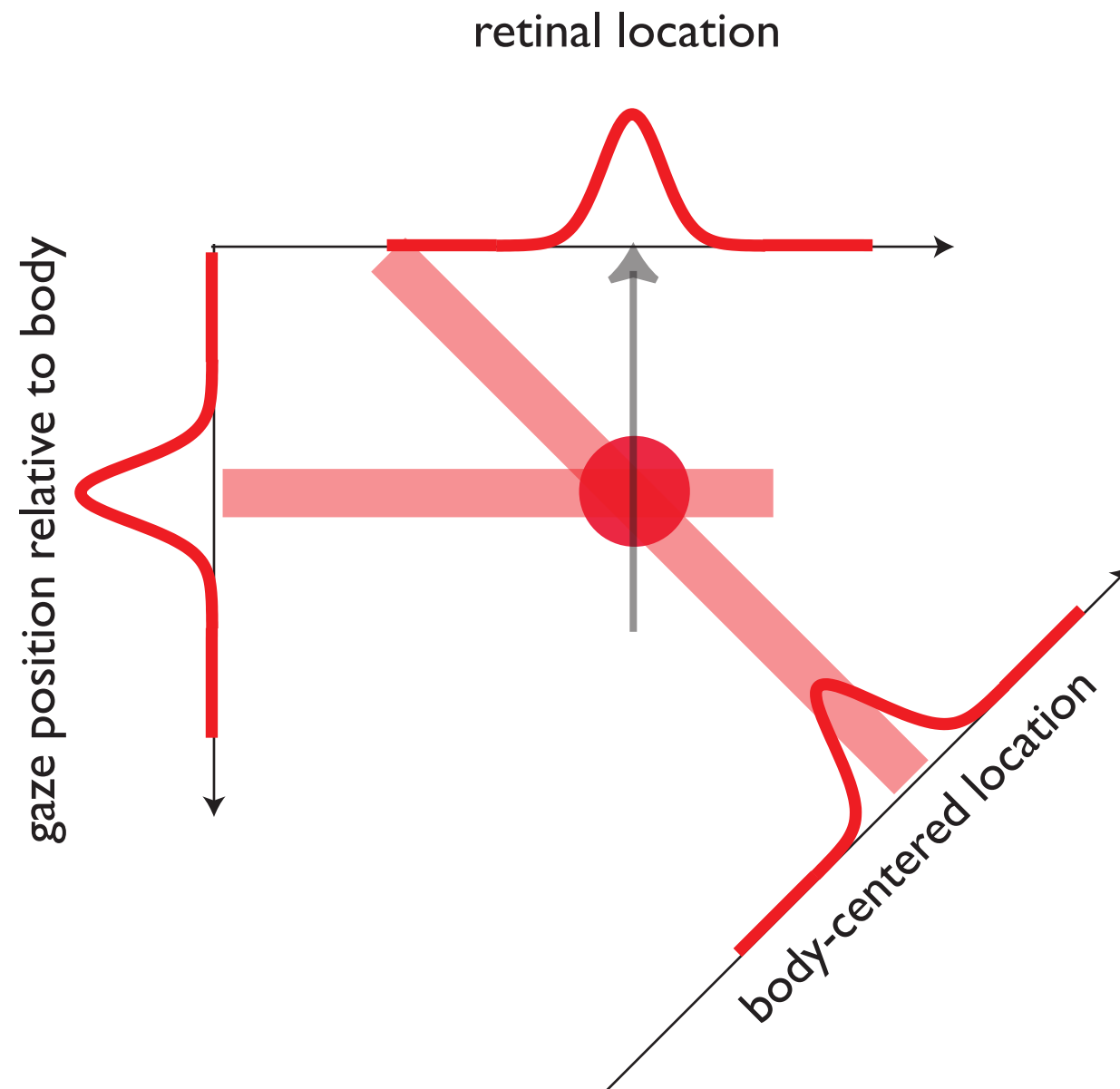
# DFT approach to coordinate transforms

■ => lecture on higher-dimensional fields

# Coordinate transformations

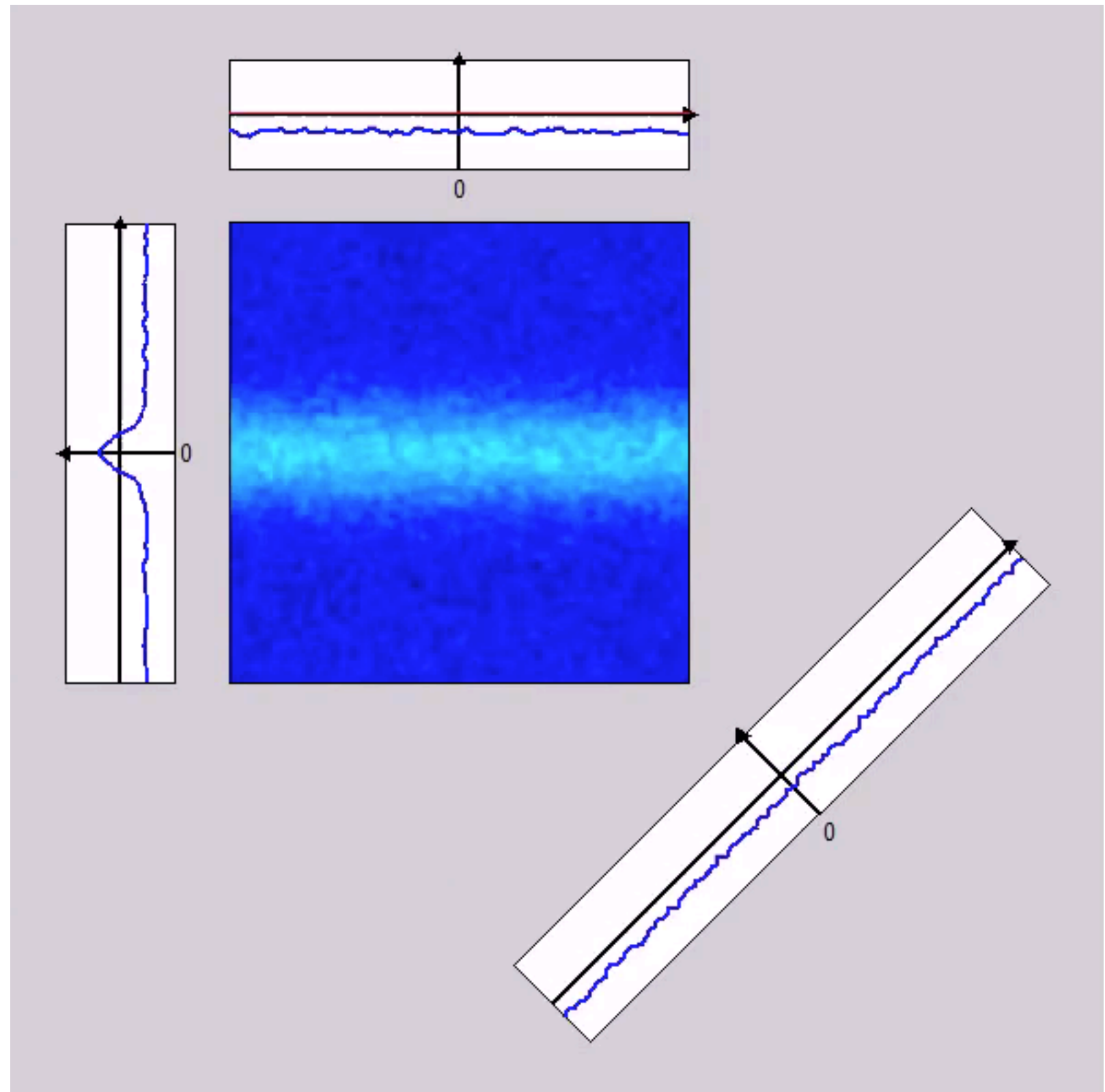


# Coordinate transformations



# Coordinate transformations

- predict retinal location following gaze shift

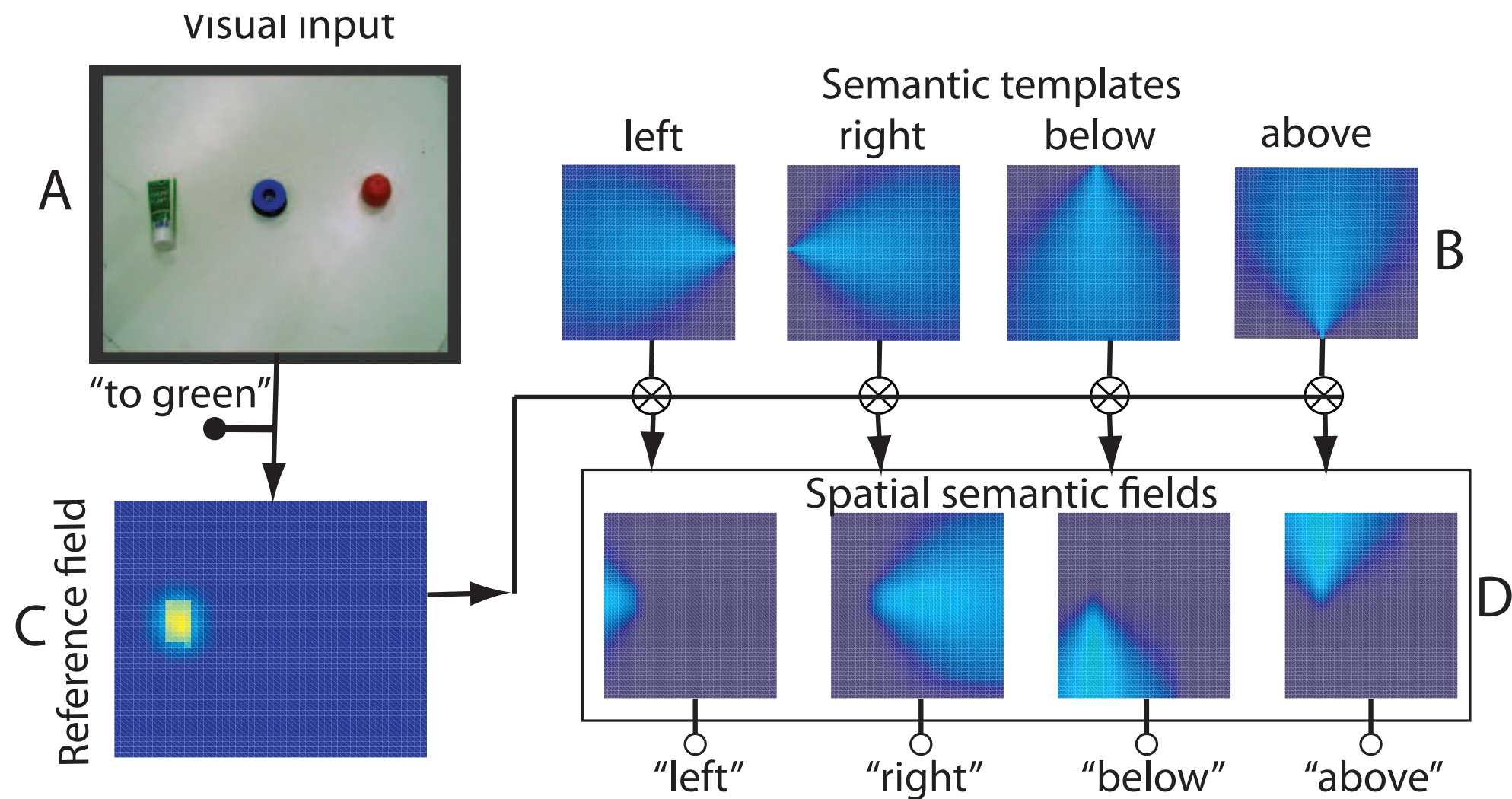


# DFT approach to applying operators



# DFT approach to applying operators

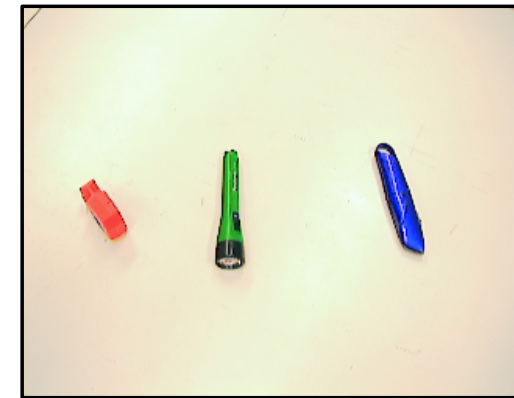
- based on convolution of fields with kernels



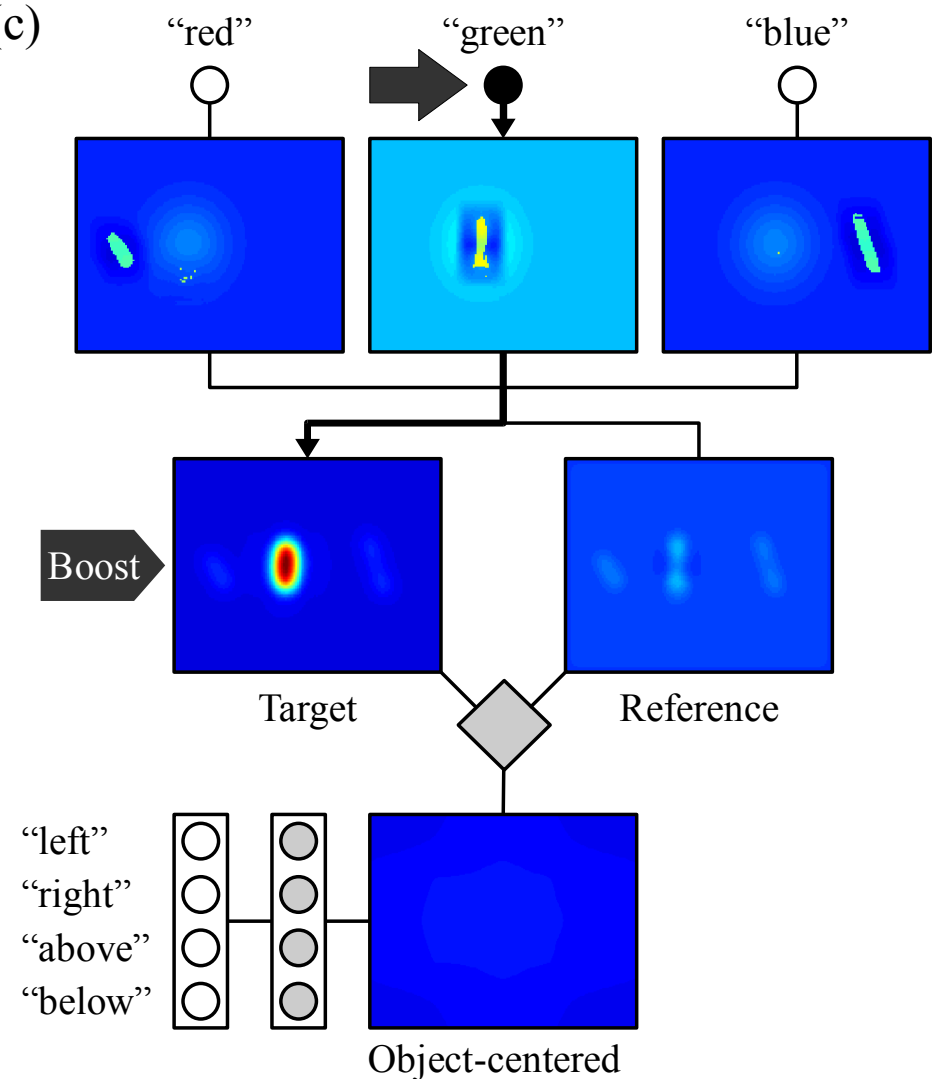
[from: Lipinski, Sandamirskaya, Schöner, 2009]

# A cognitive architecture for grounded spatial language in DFT

(a)

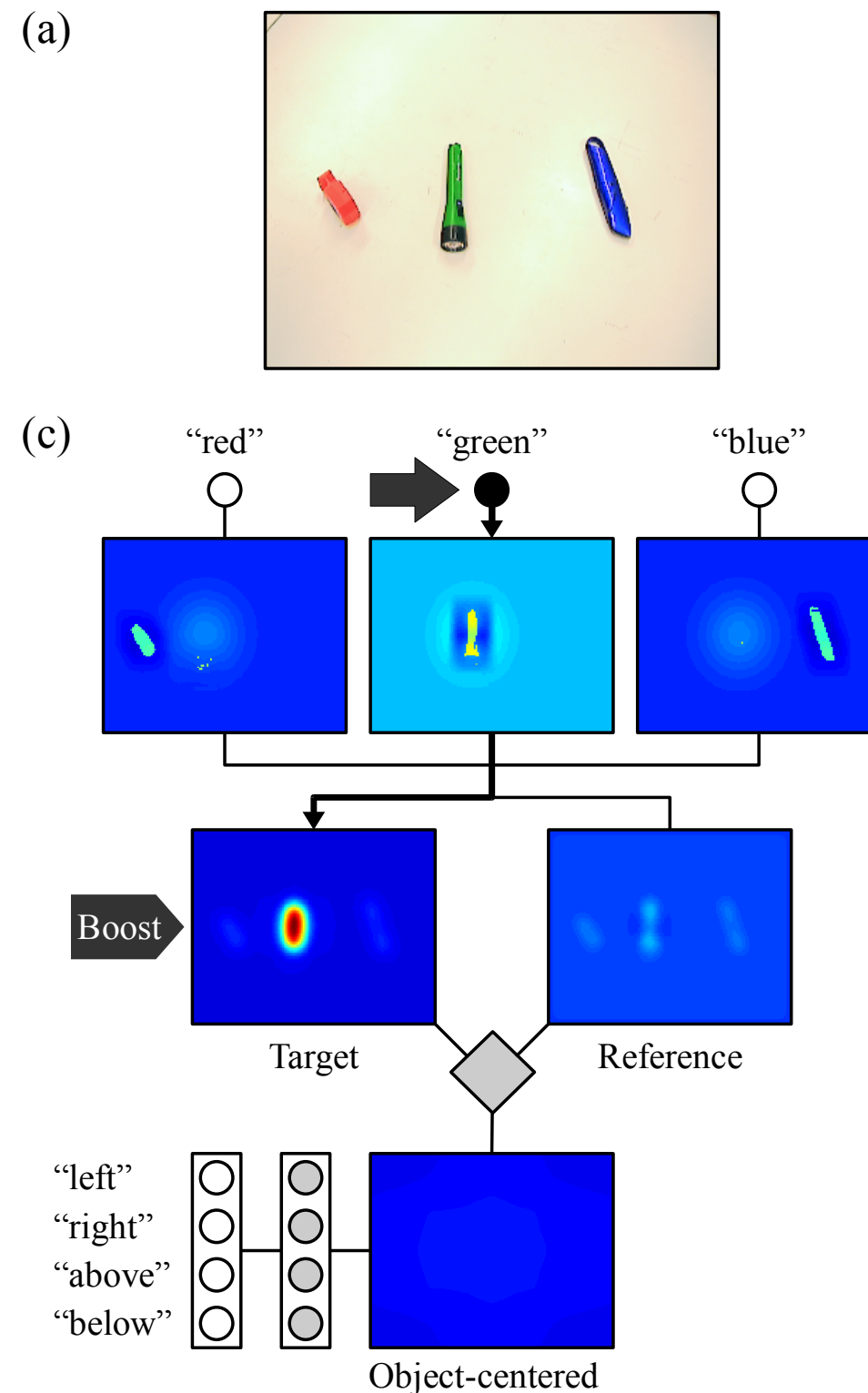


(c)



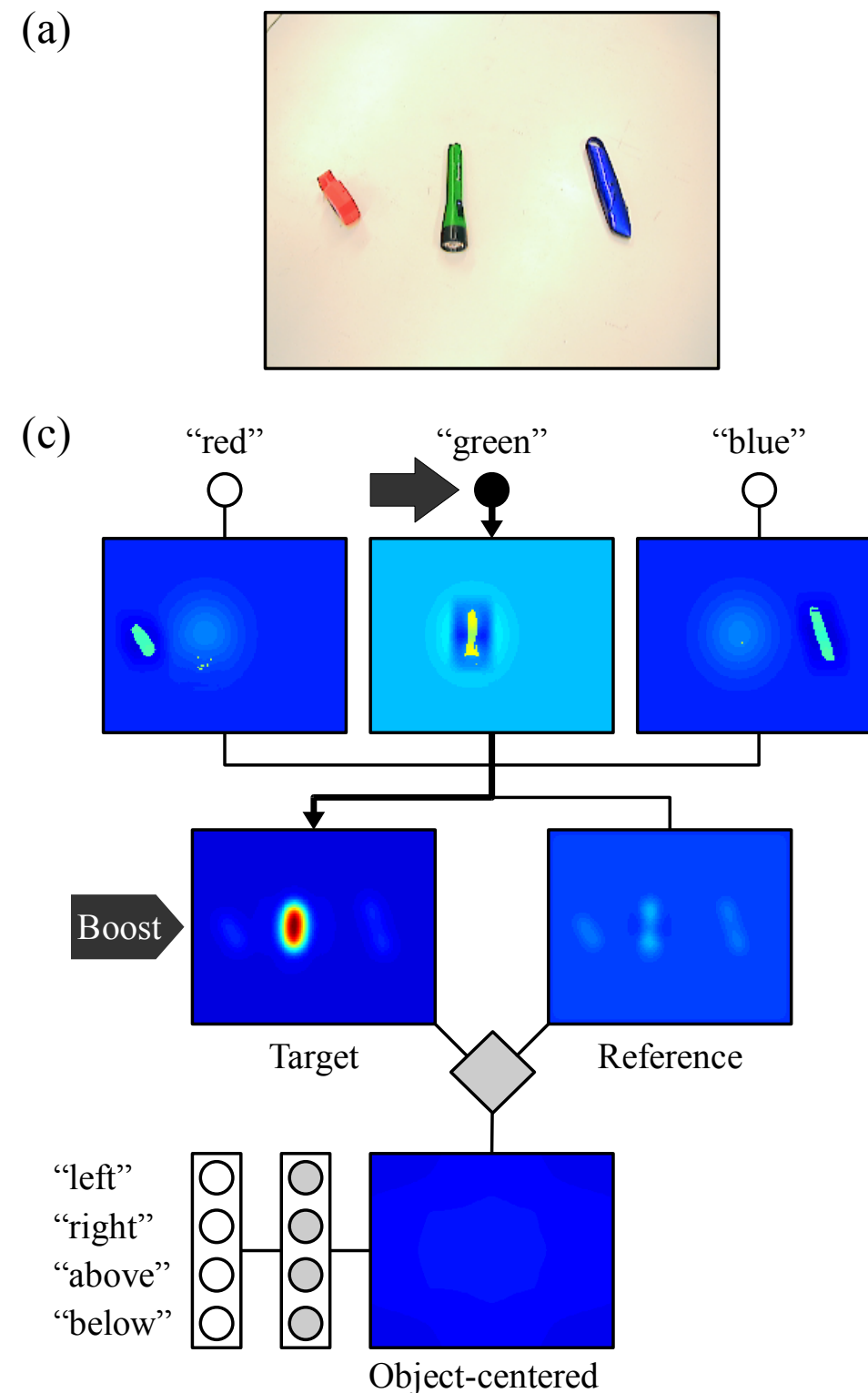
# Spatial comparison in DFT

- bring objects into foreground
- make coordinate transformation
- apply comparison operators



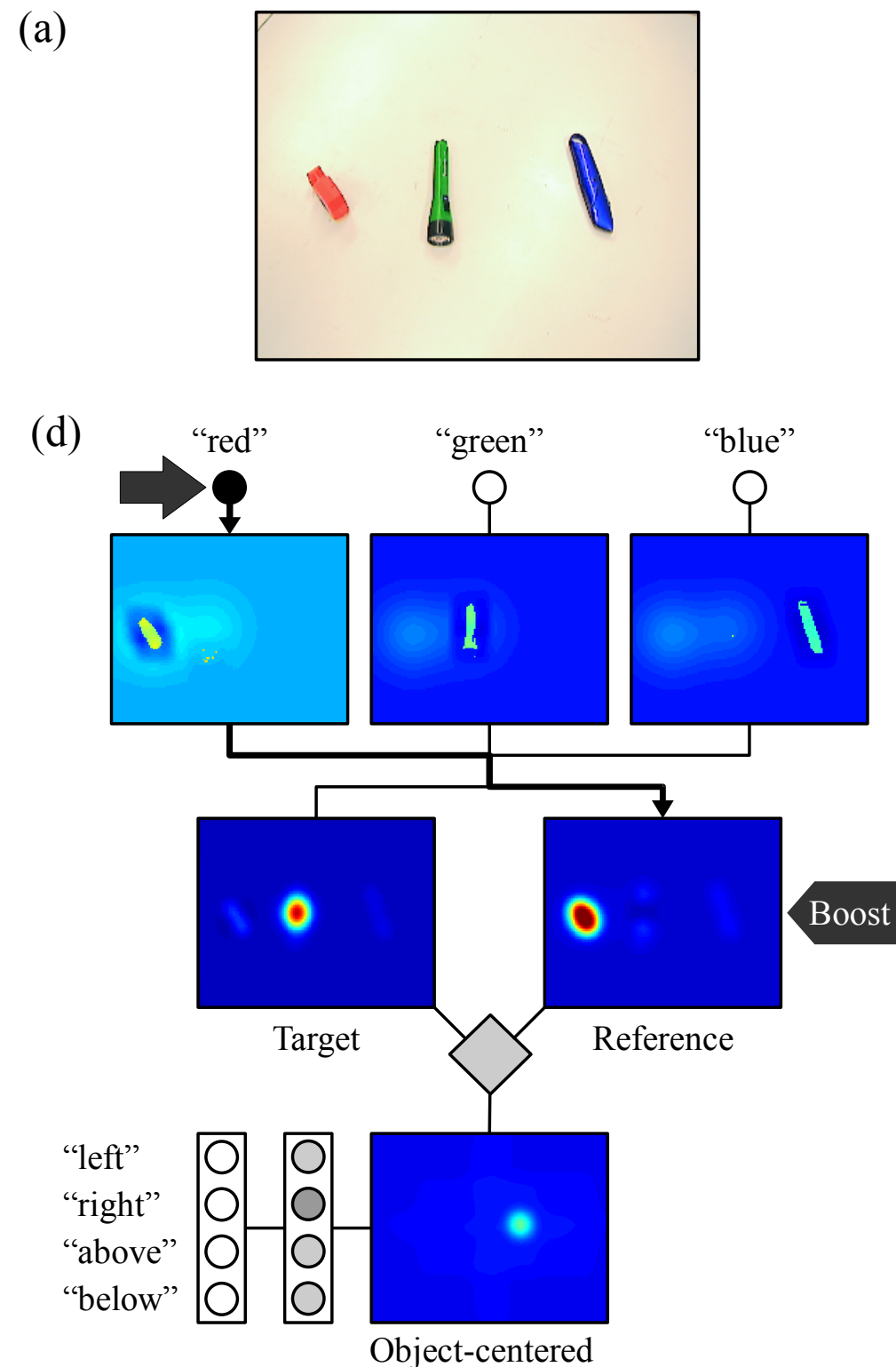
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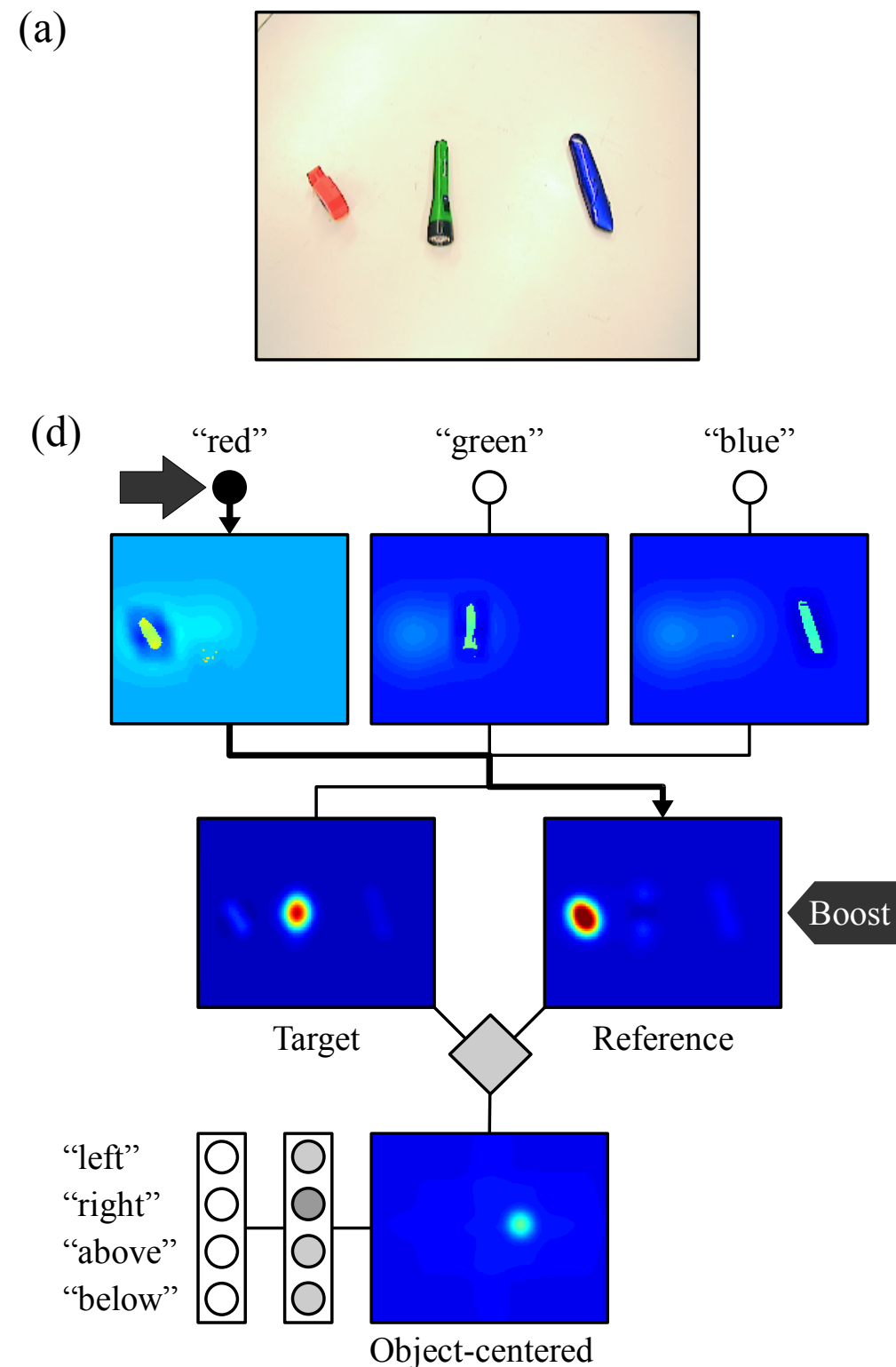
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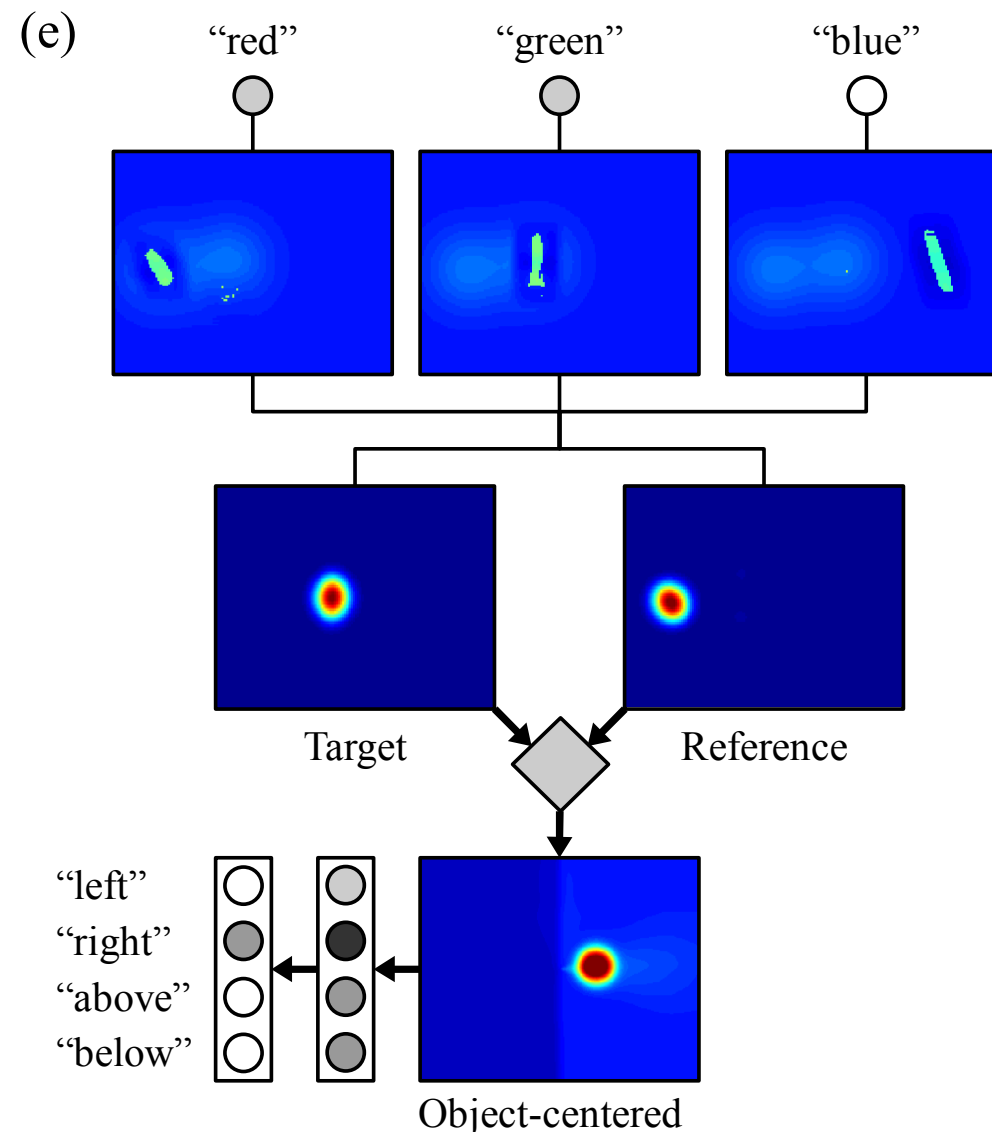
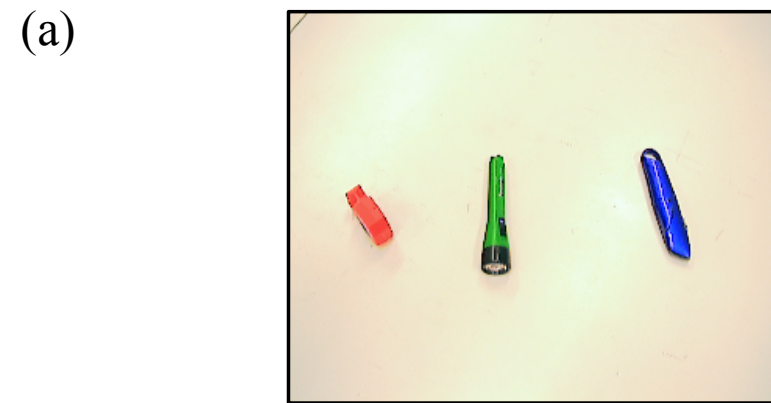
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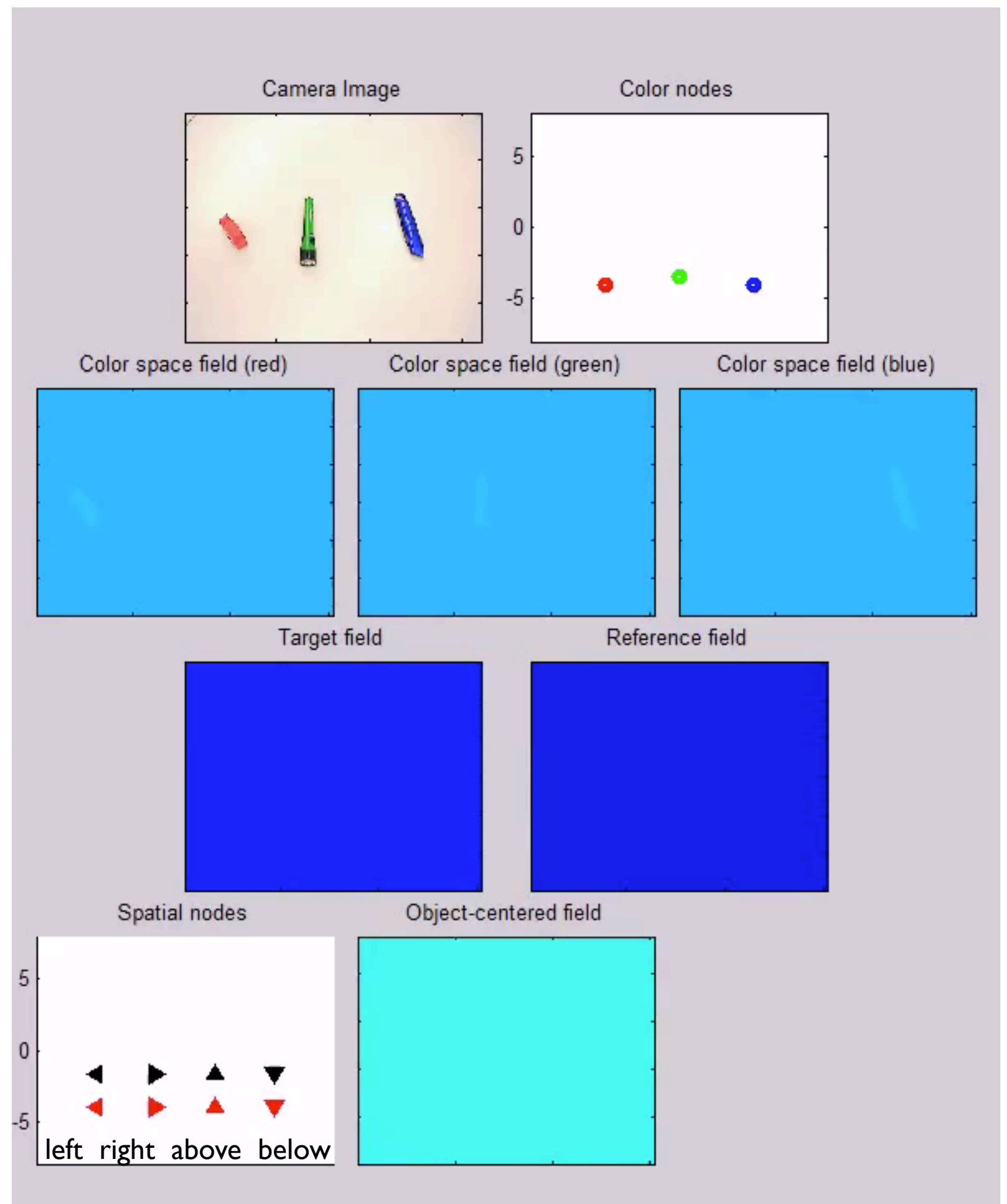


# Spatial comparison in DFT

- bring objects into foreground
- make coordinate transformation
- apply comparison operators

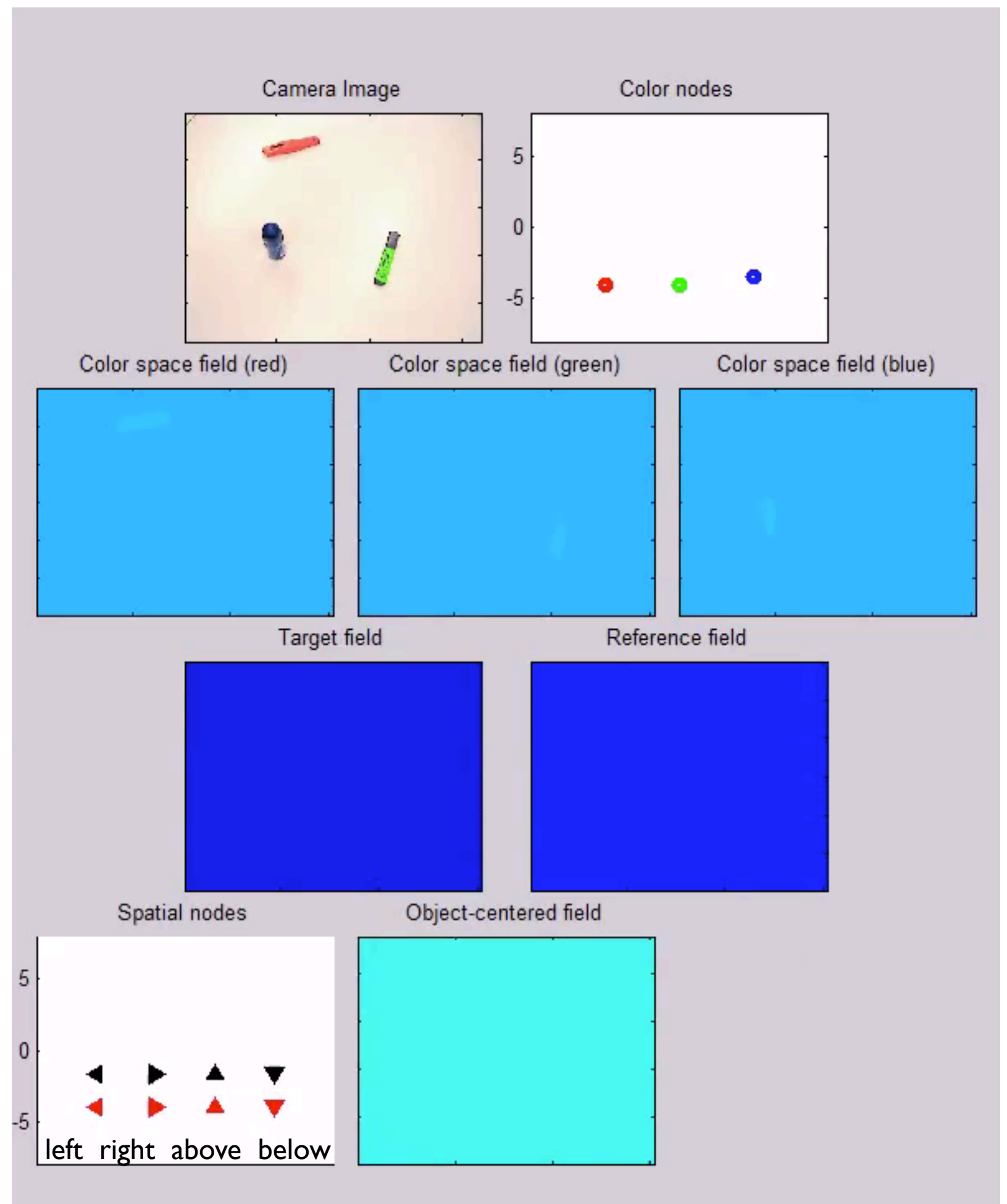


■ “where is the green object relative to the red object?”

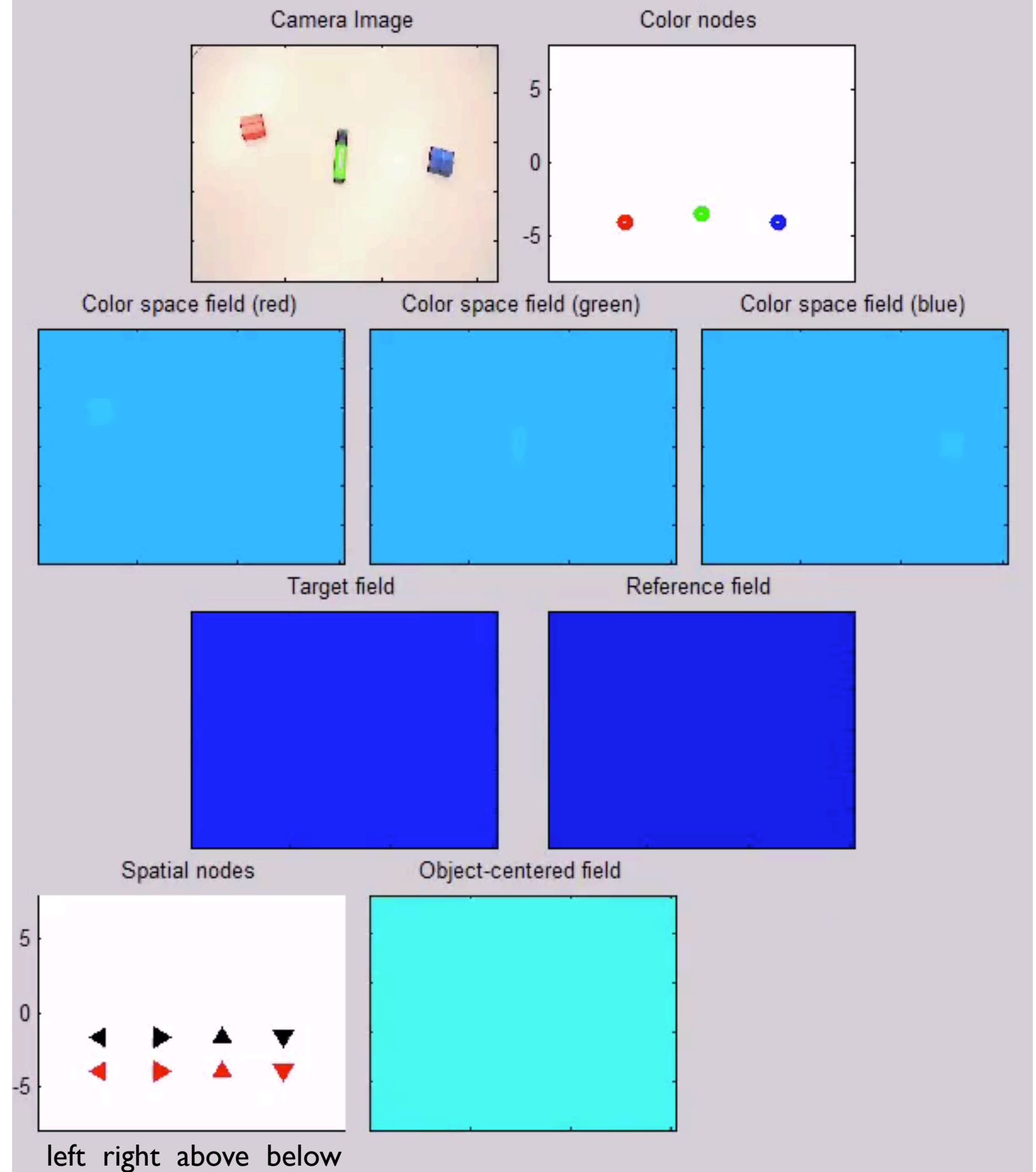




■ “which object is above the blue object?”

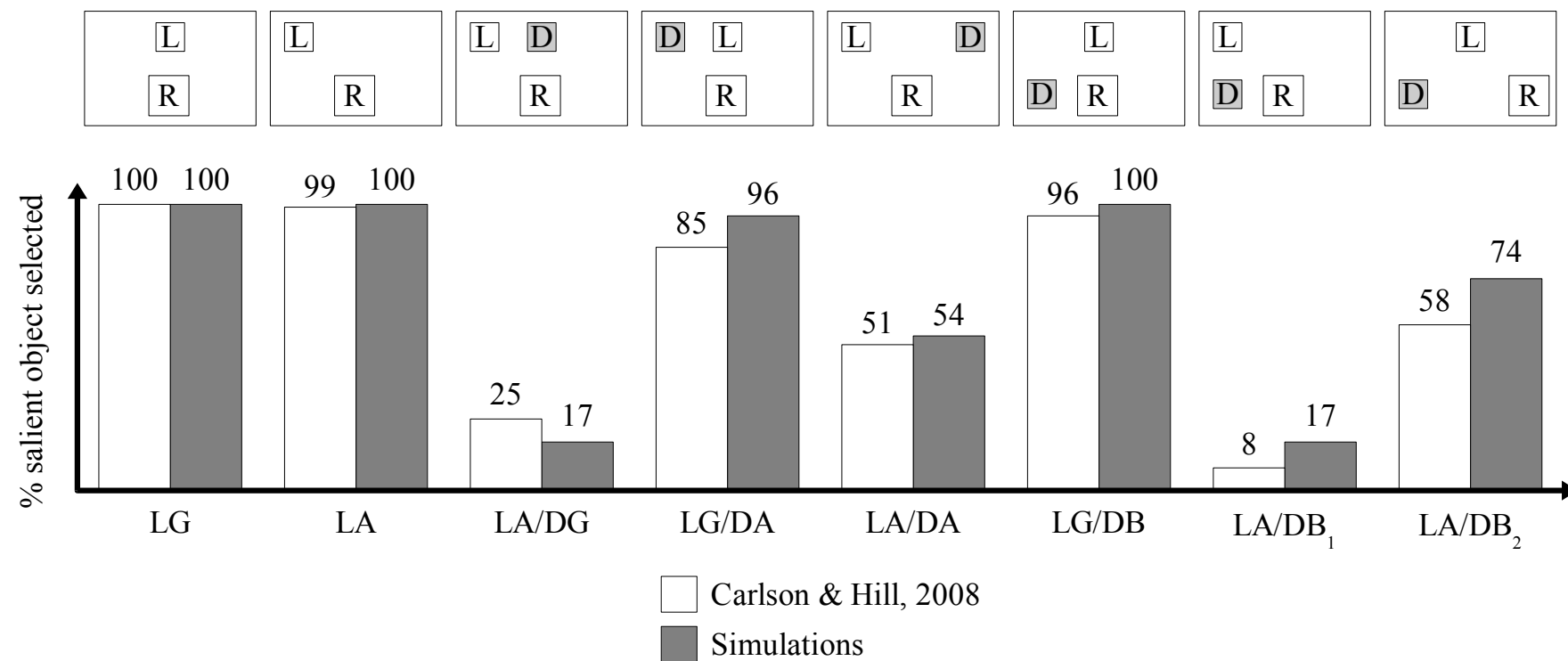


■ “where is the green object?”

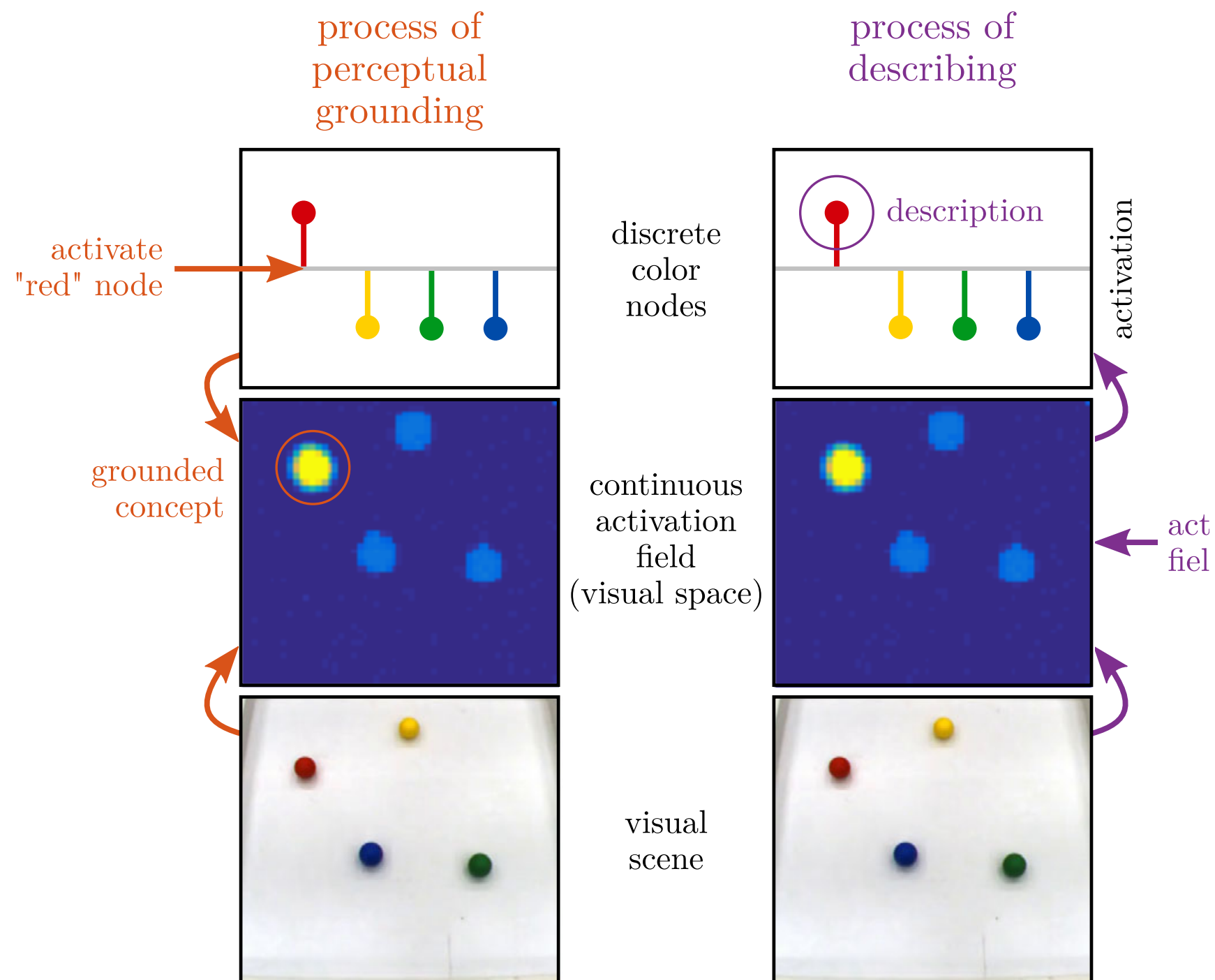


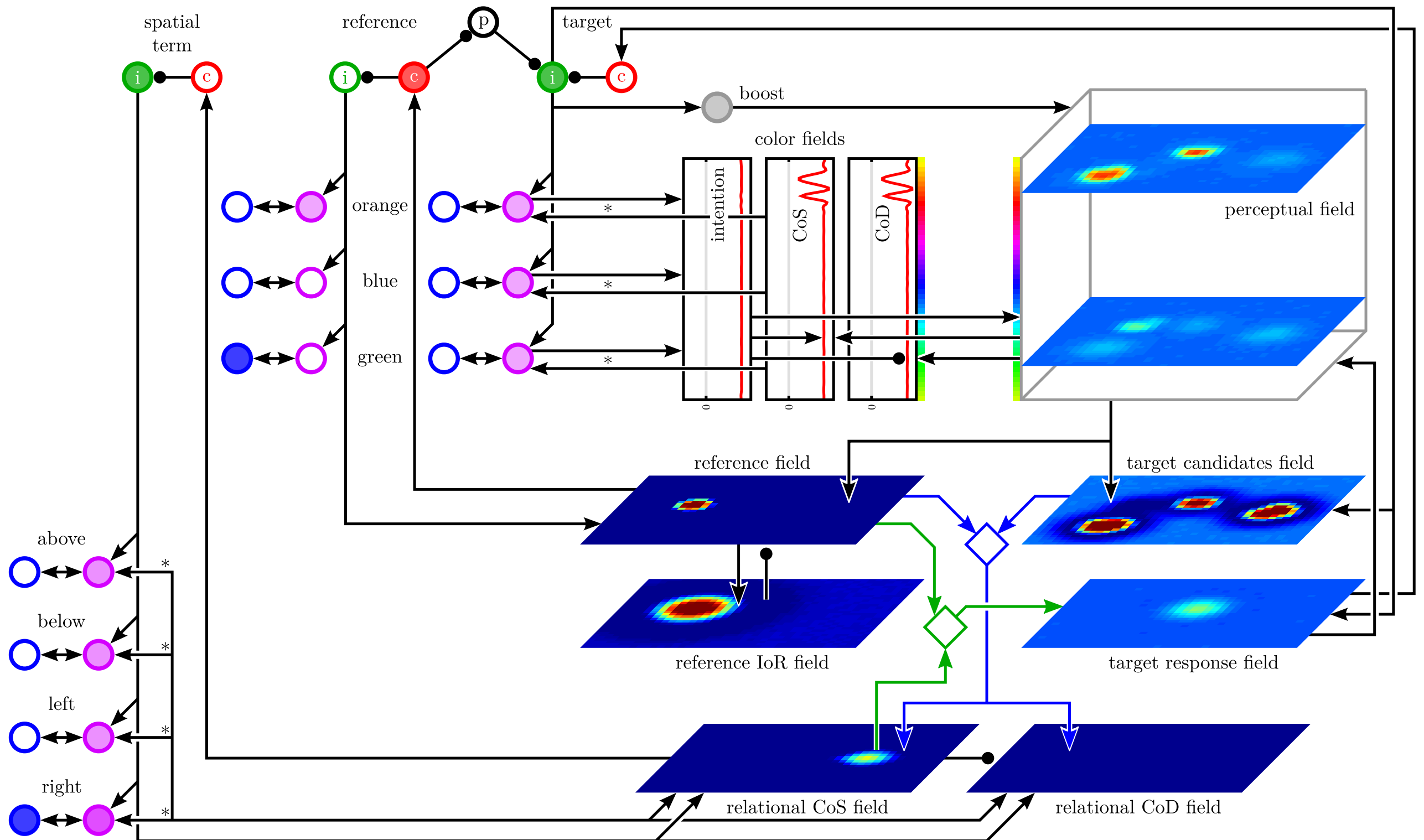
# Spatial comparison in DFT

■ accounts for human data



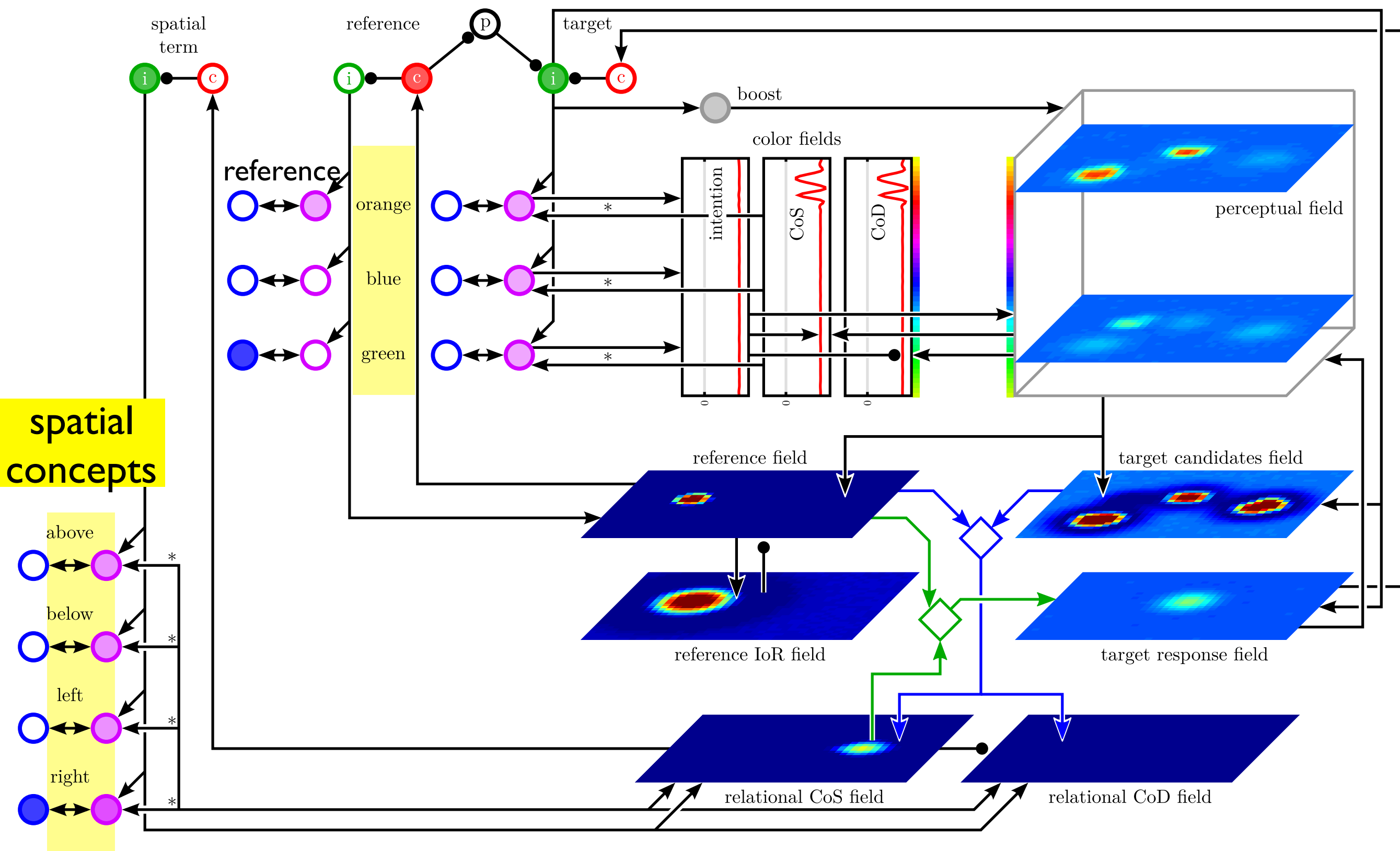
# A DFT architecture that does both grounding and describing

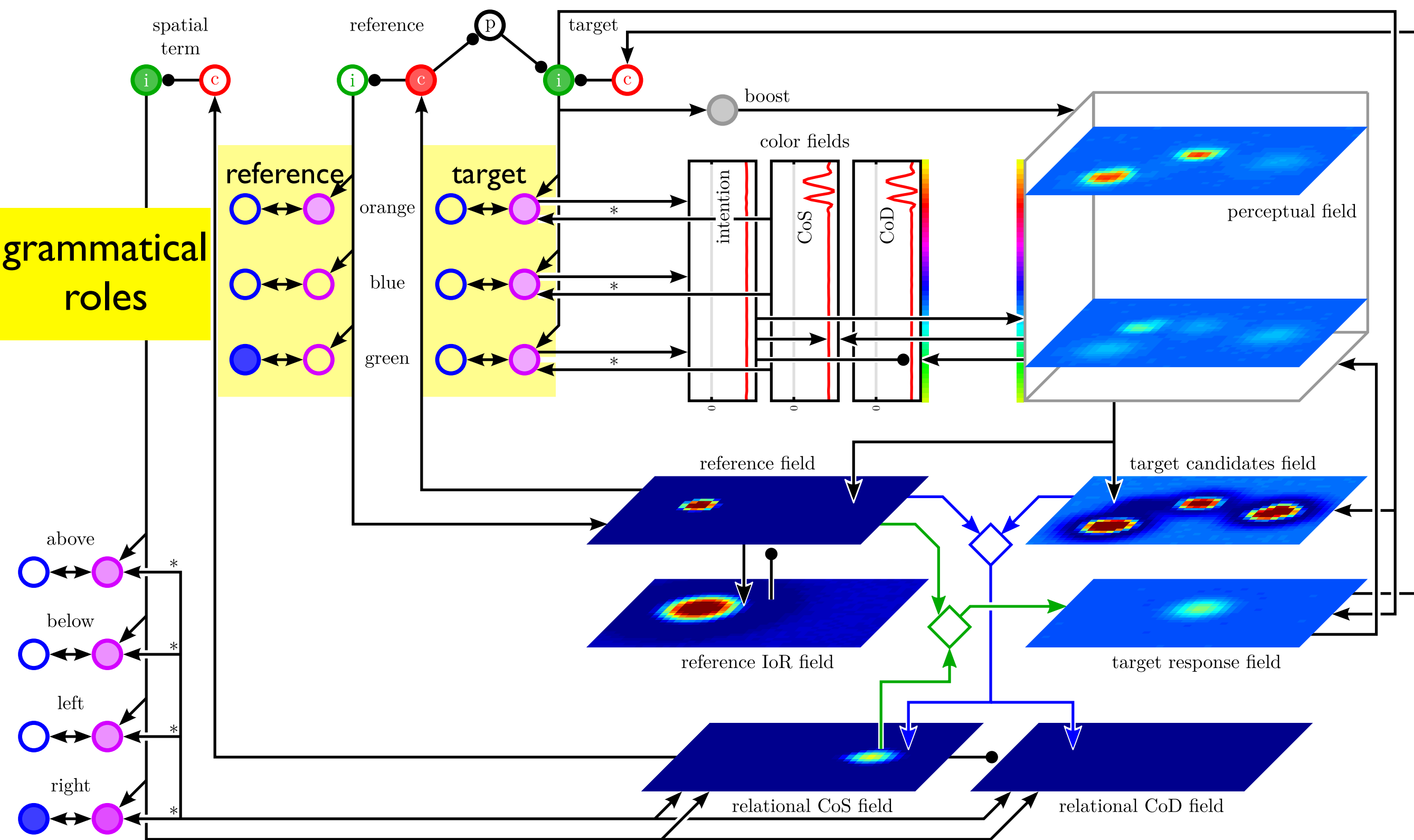


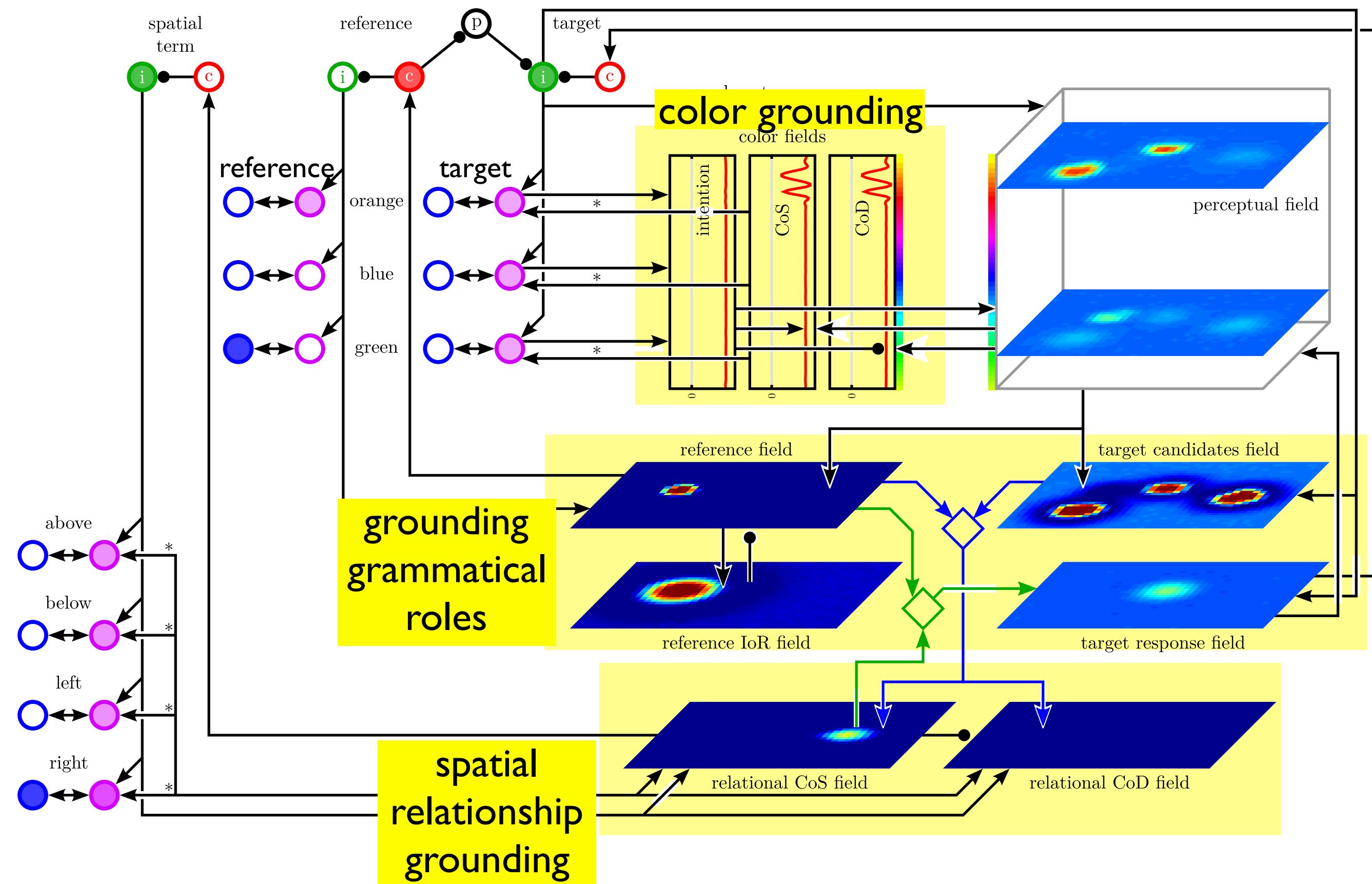


# color concepts

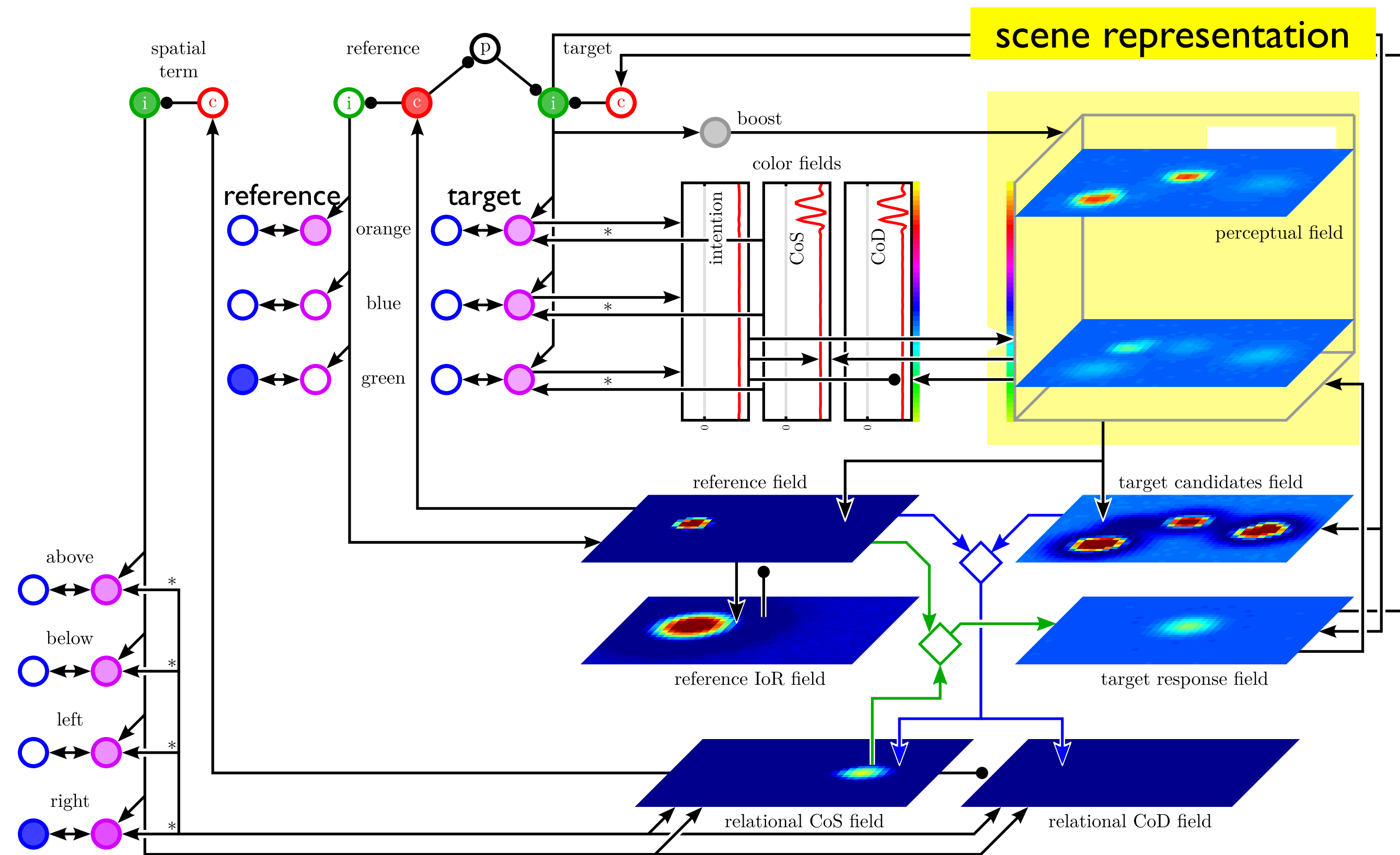
# spatial concepts







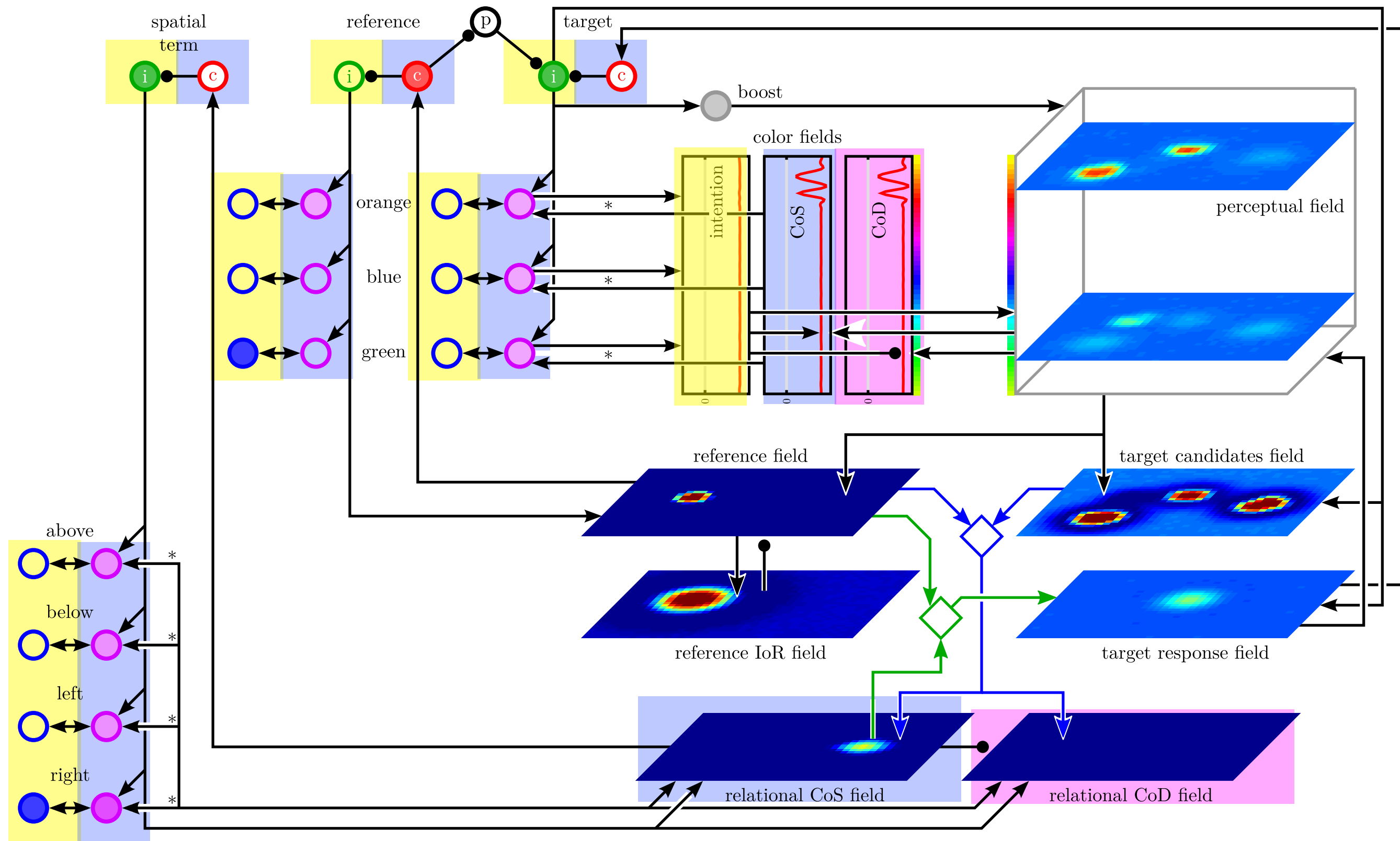




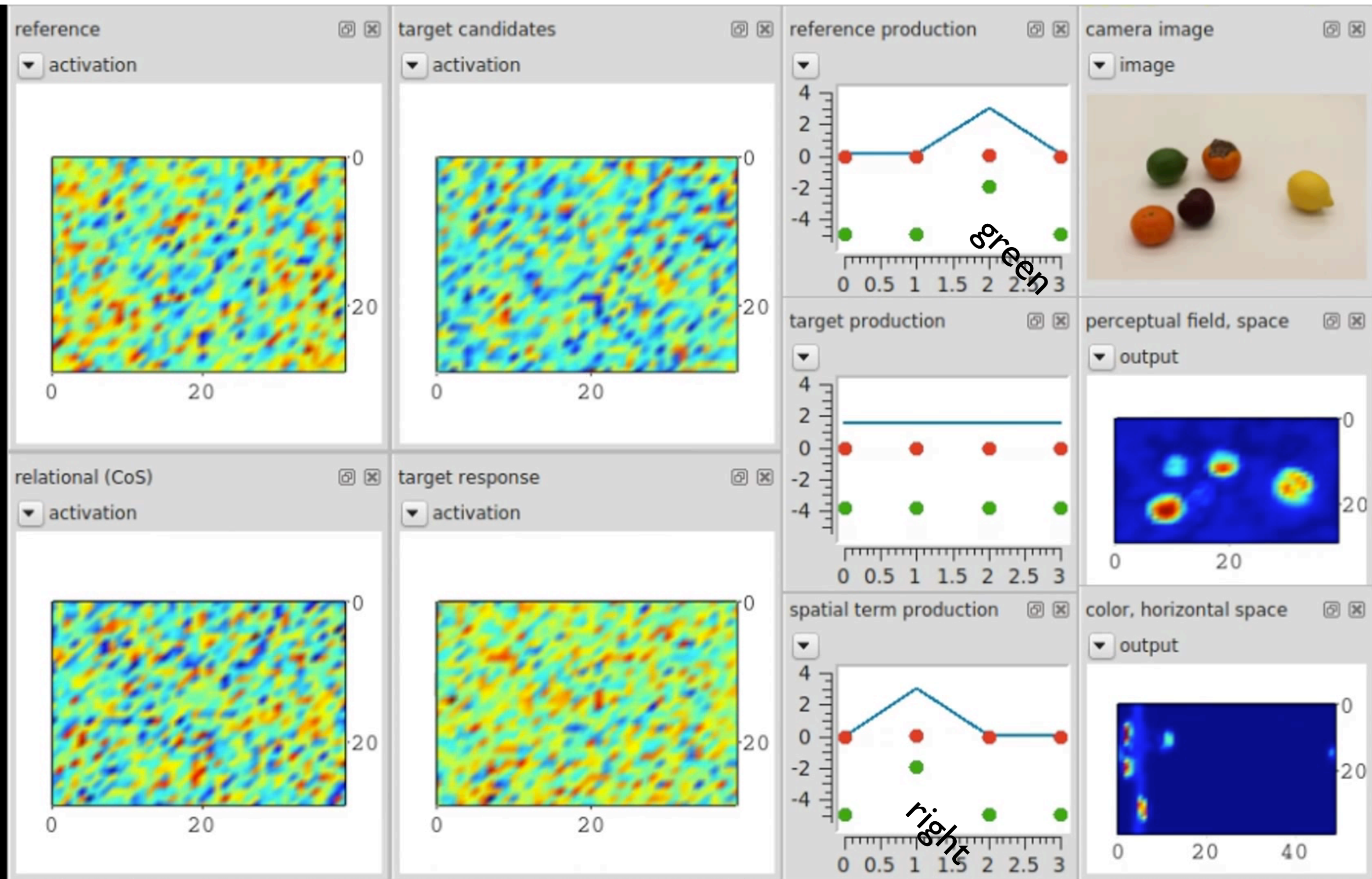
Intention

Condition of Satisfaction

Condition of Dissatisfaction

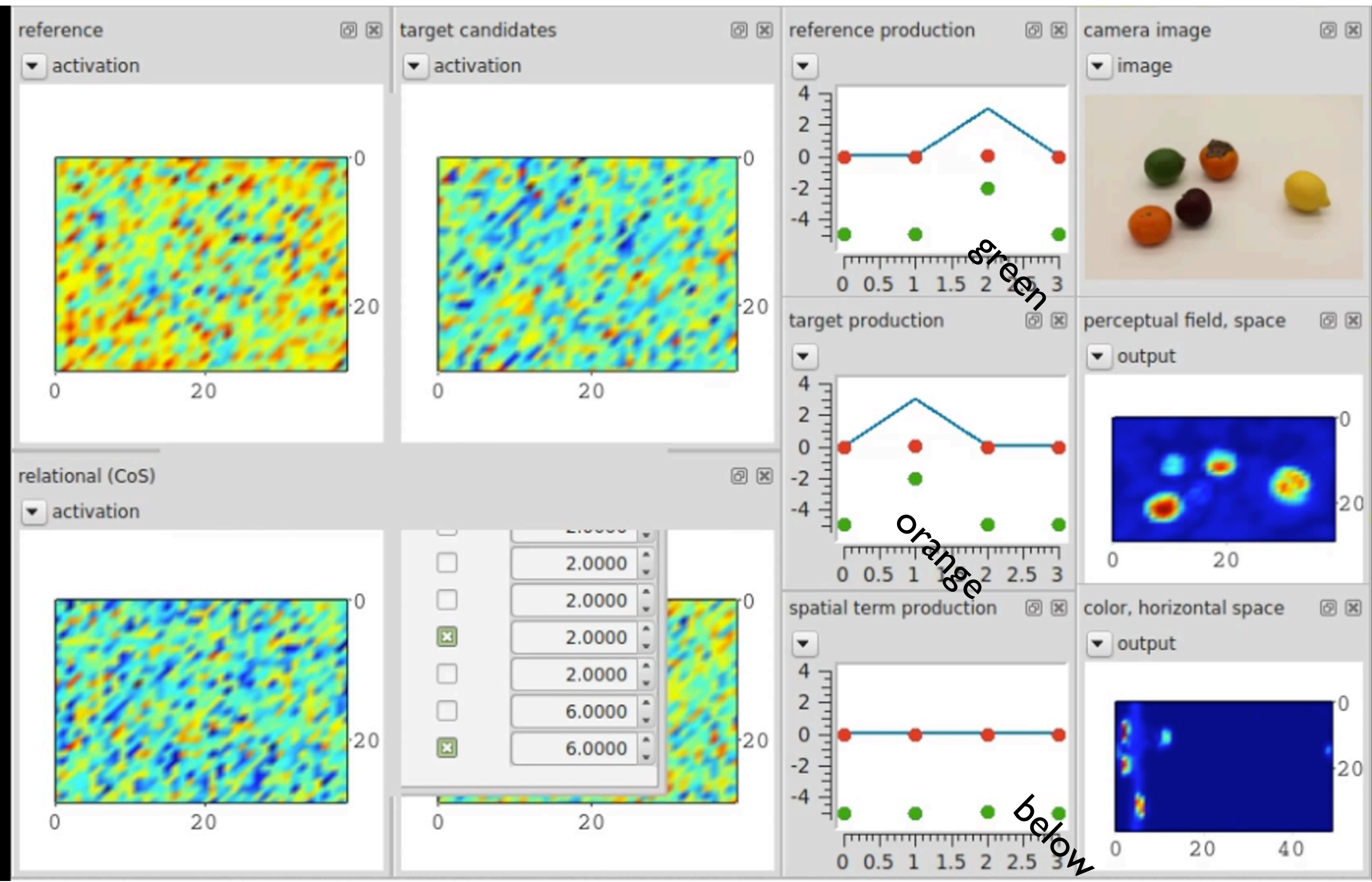


■ what is to the right of the green object?





■ where is the orange relative to the green object

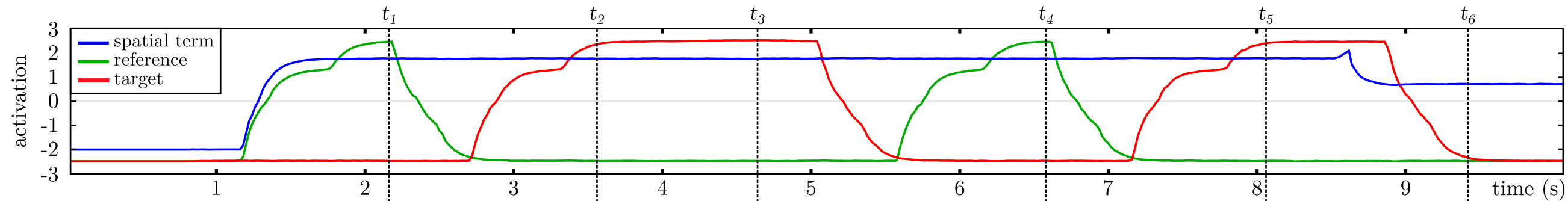


# Autonomous hypothesis testing

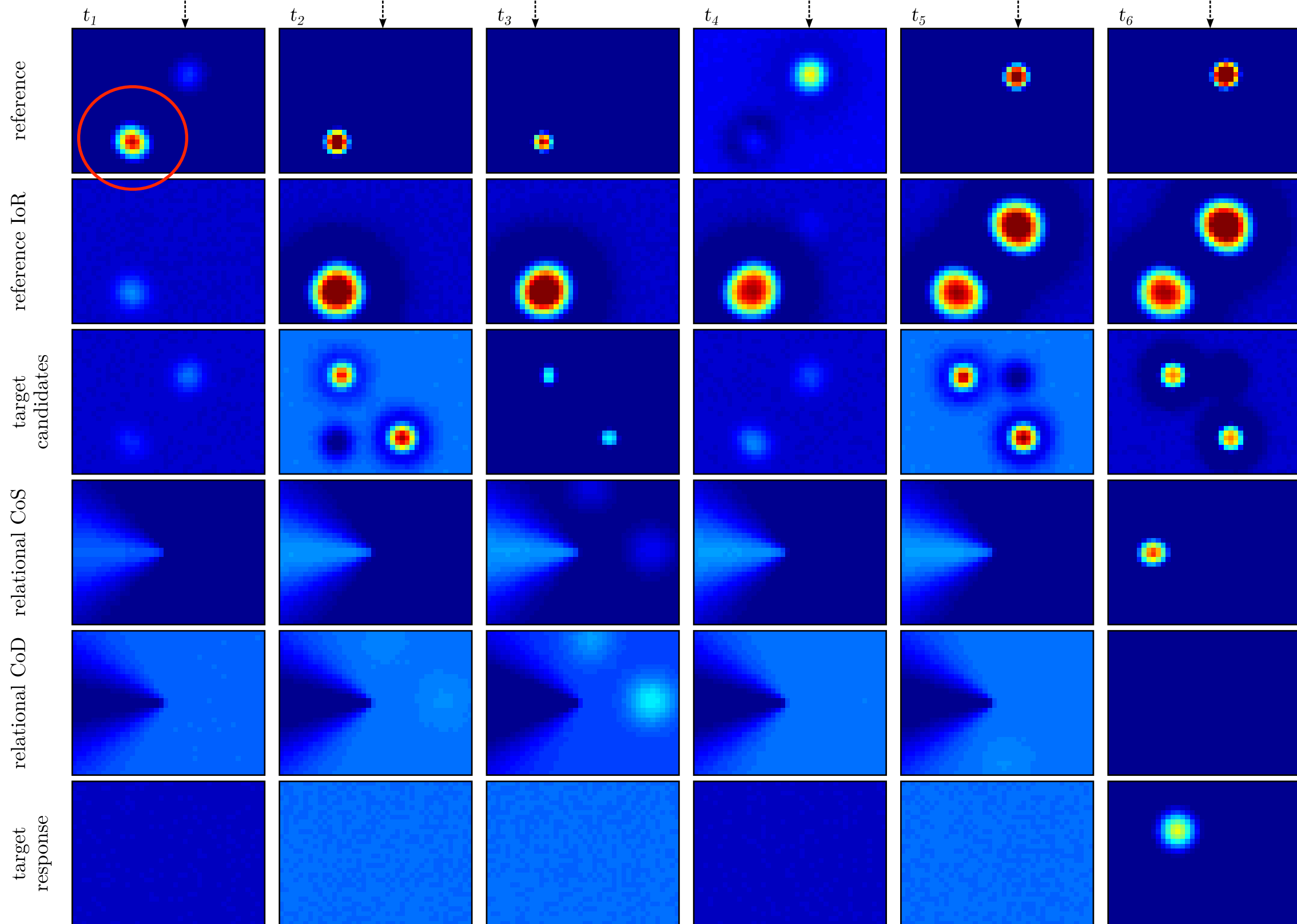
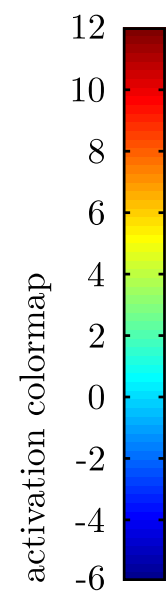


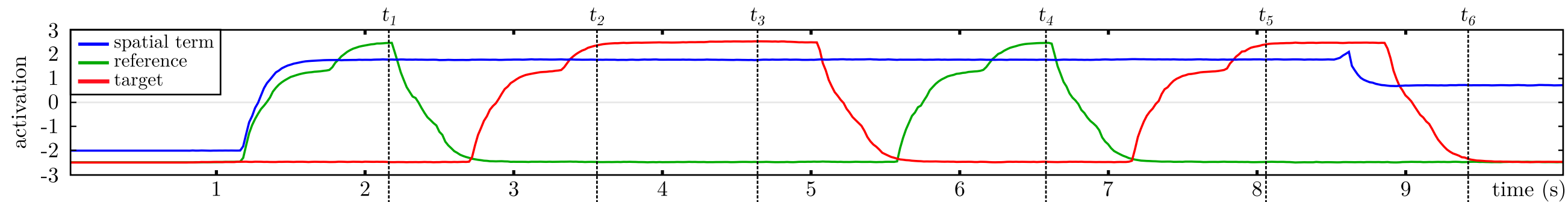
“the red cup that is to the left of the green cup”

[Richter, Lins et al, CogSci 2014]

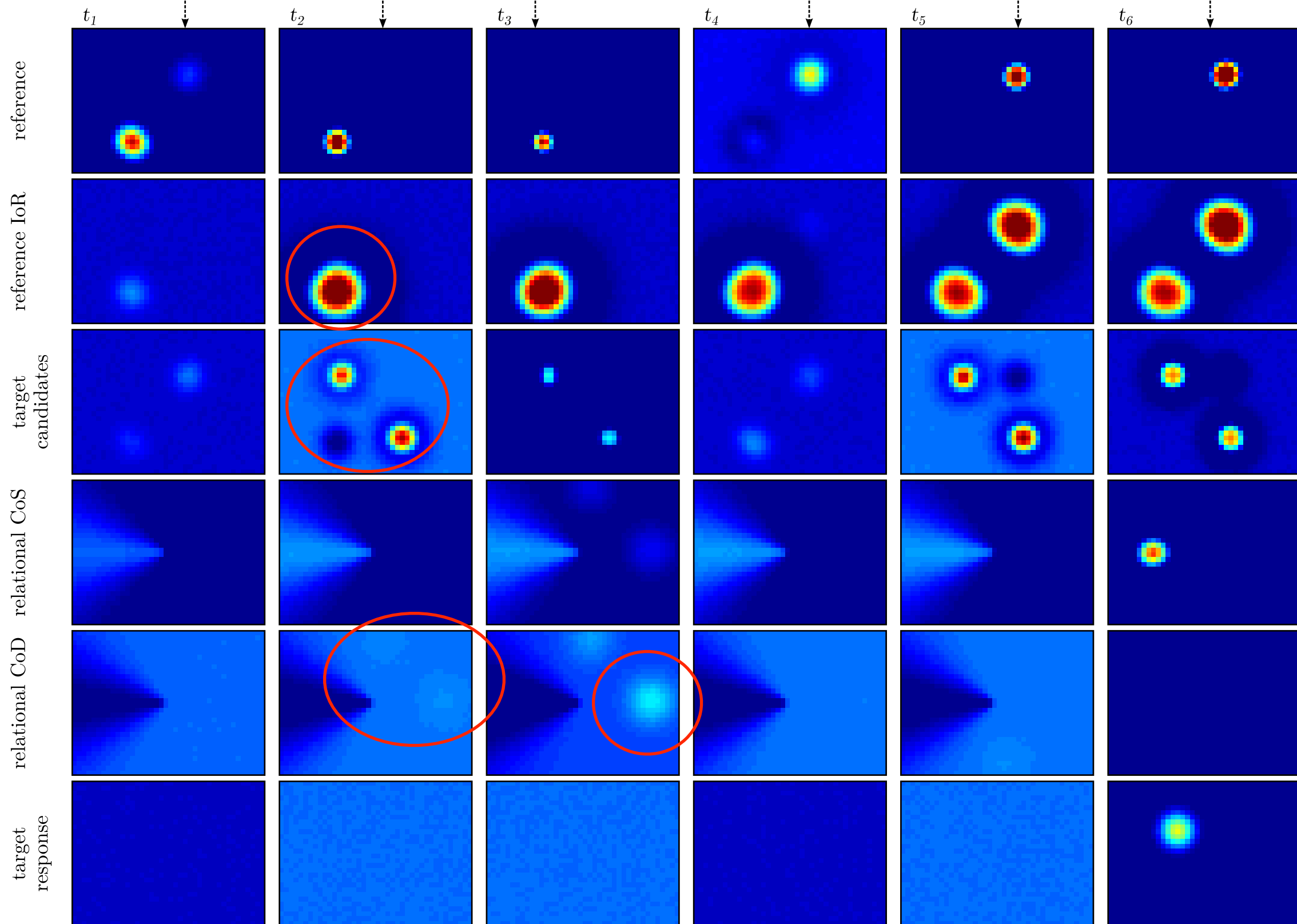
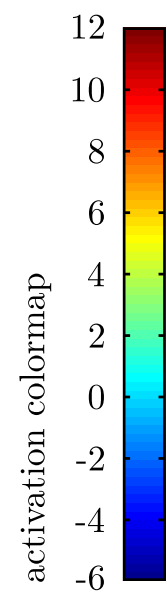


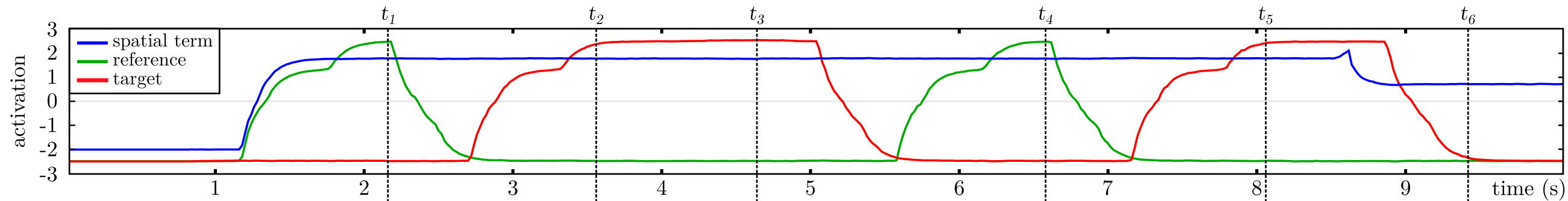
“the red cup  
that is to the  
left of the  
green cup”



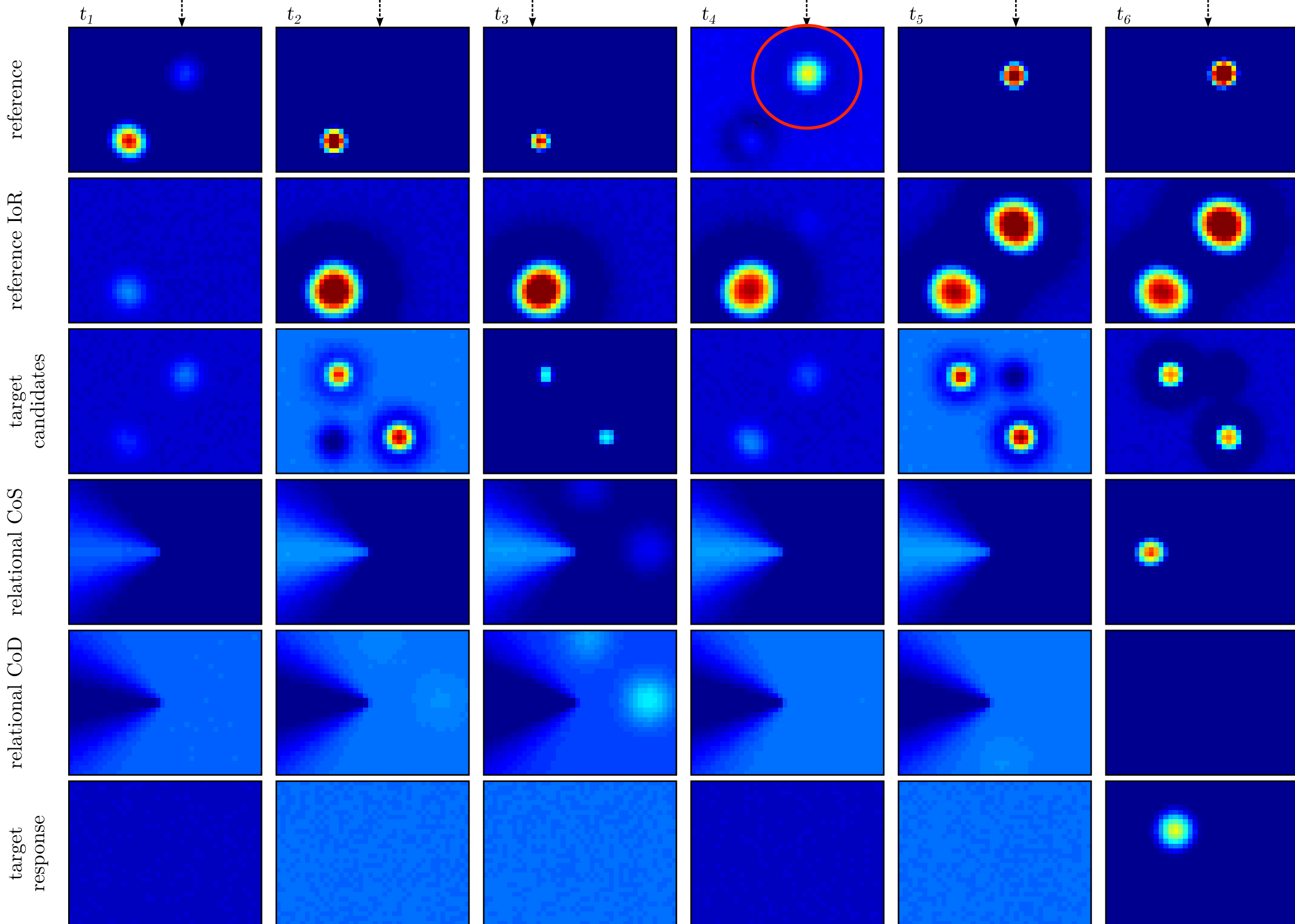
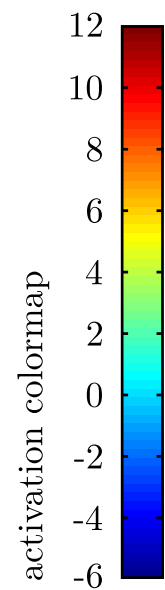


“the red cup  
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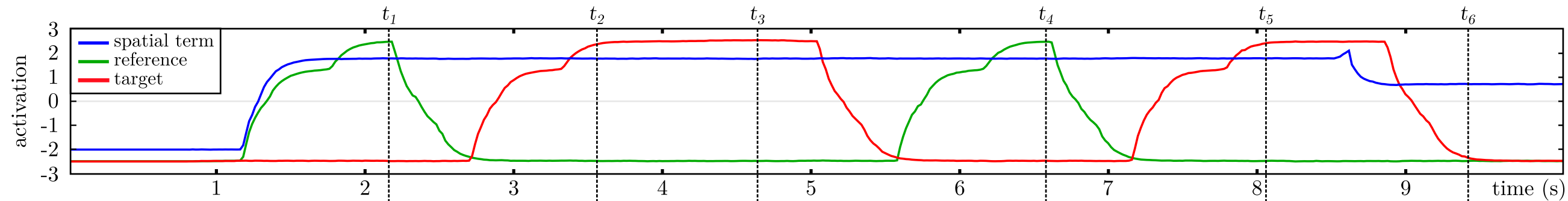




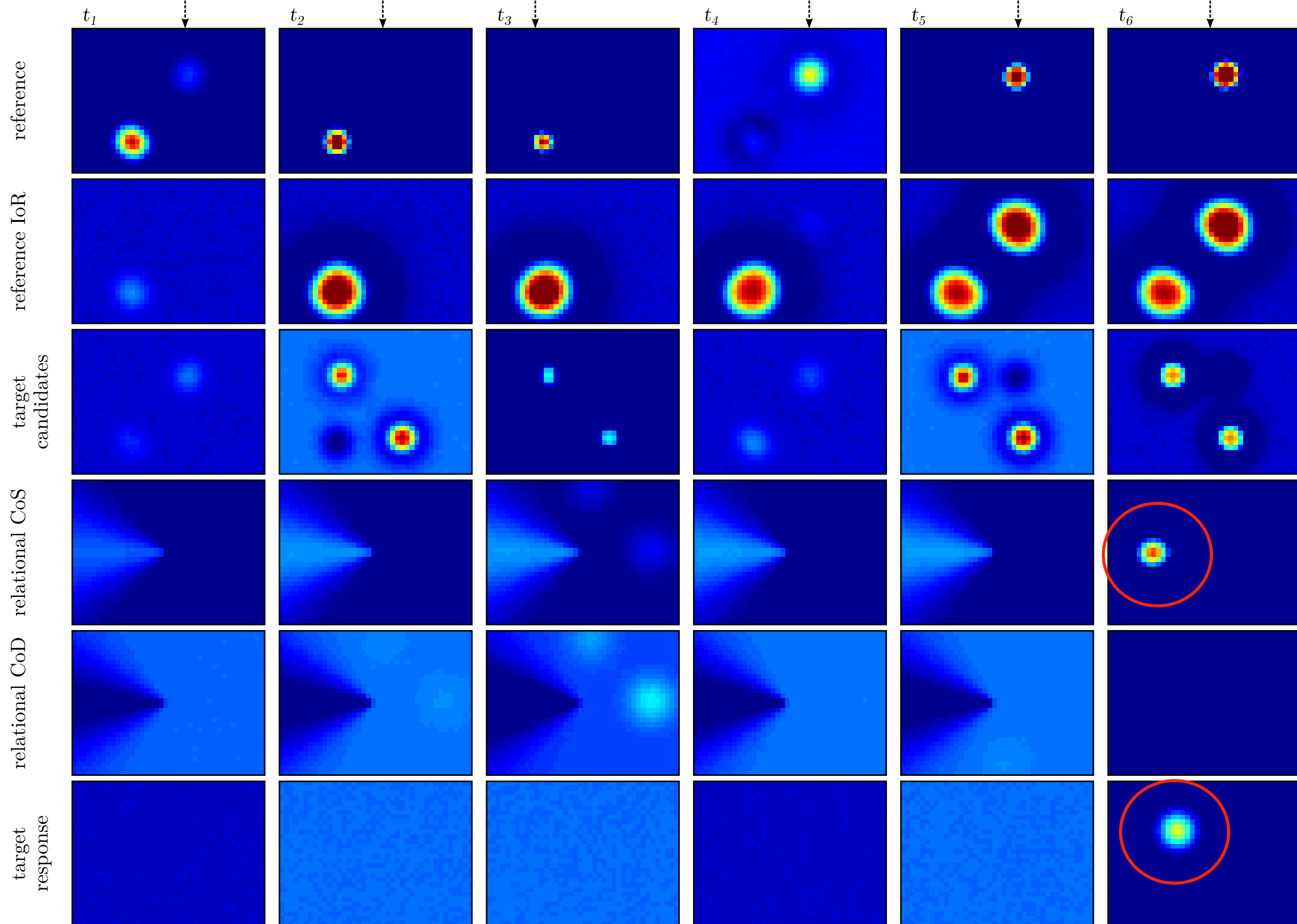
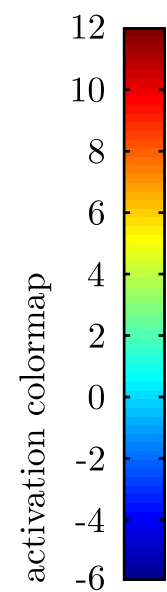
“the red cup  
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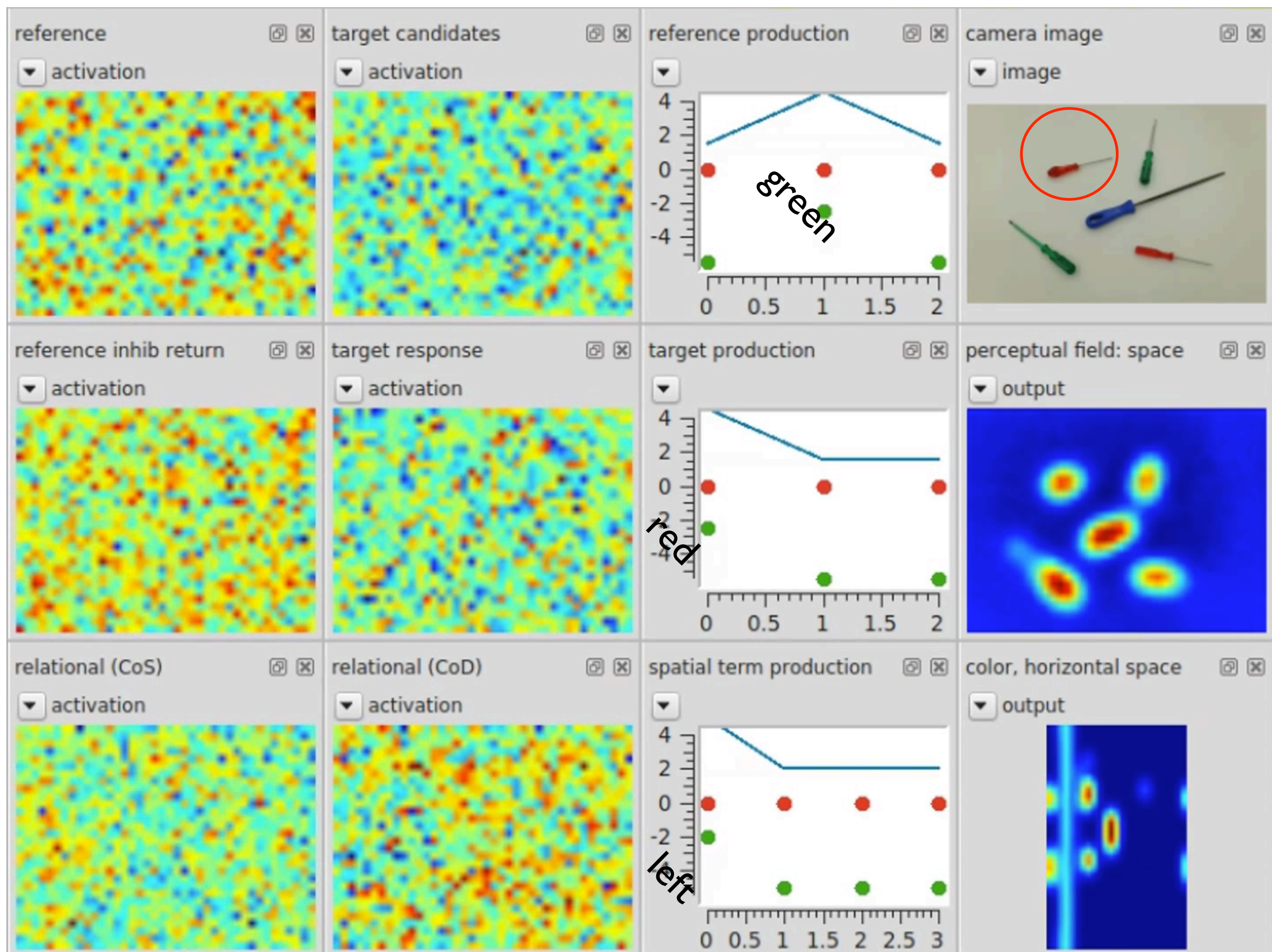




“the red cup  
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left of the  
green cup”

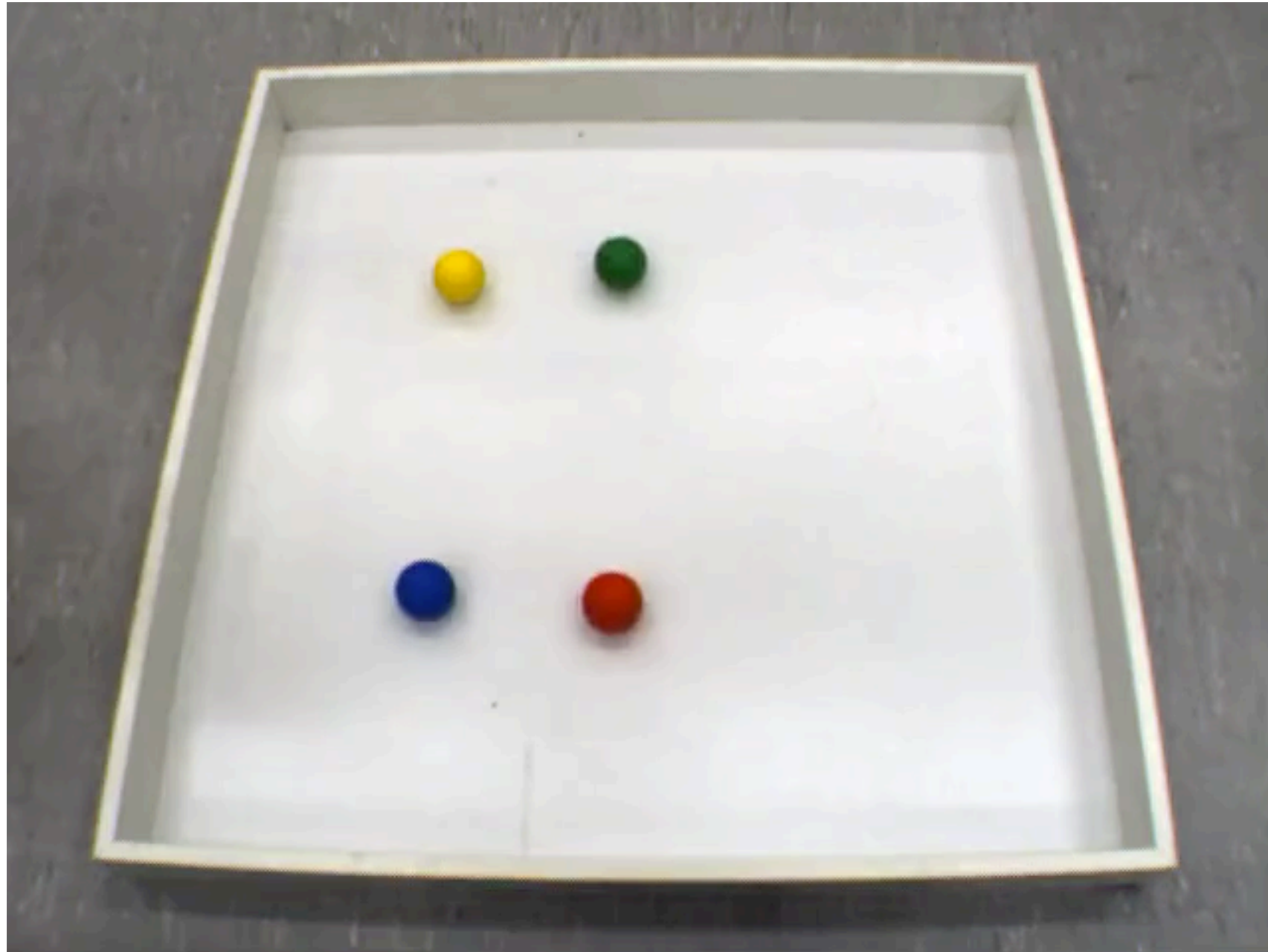


“the red to the left of the green”

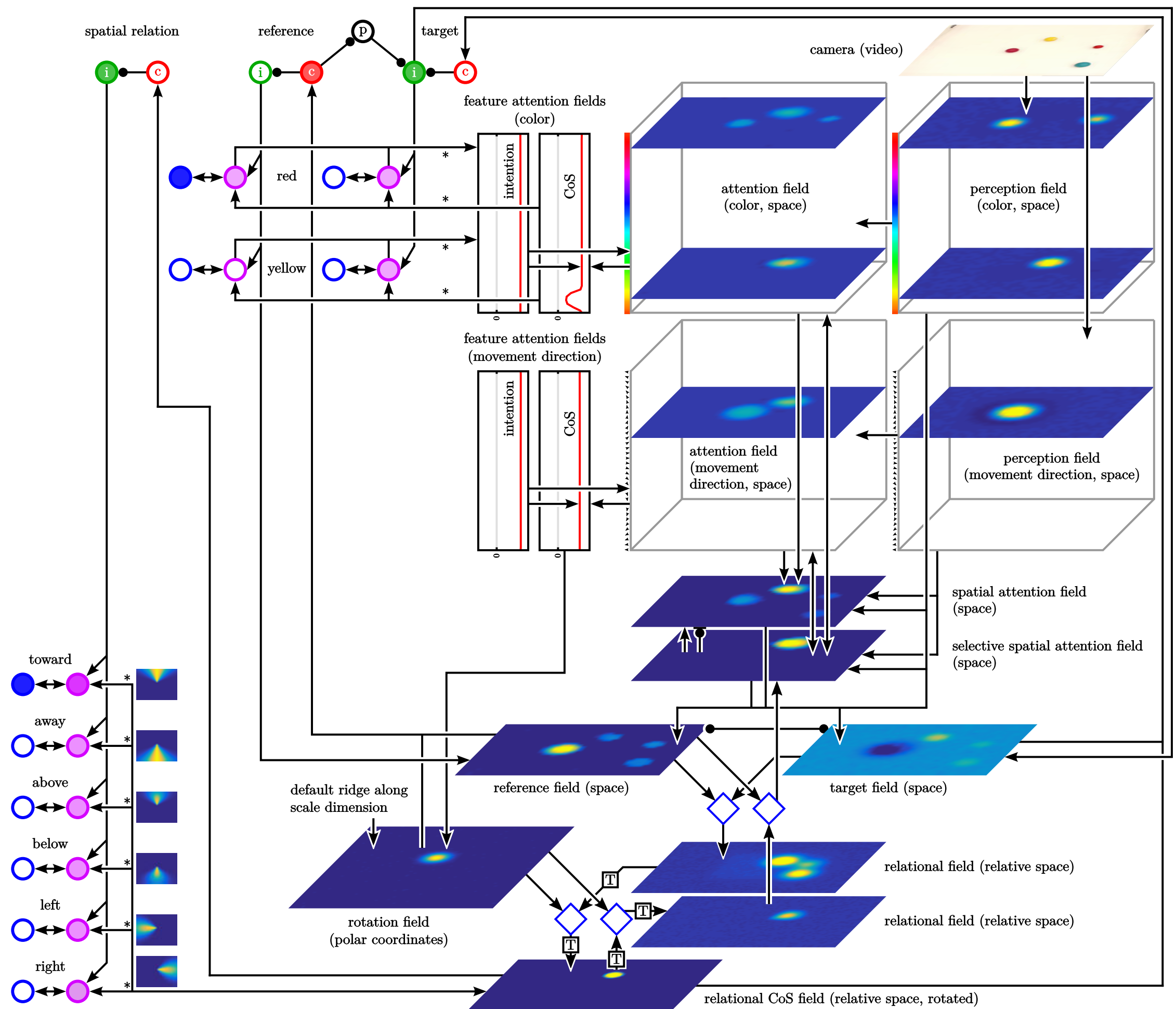


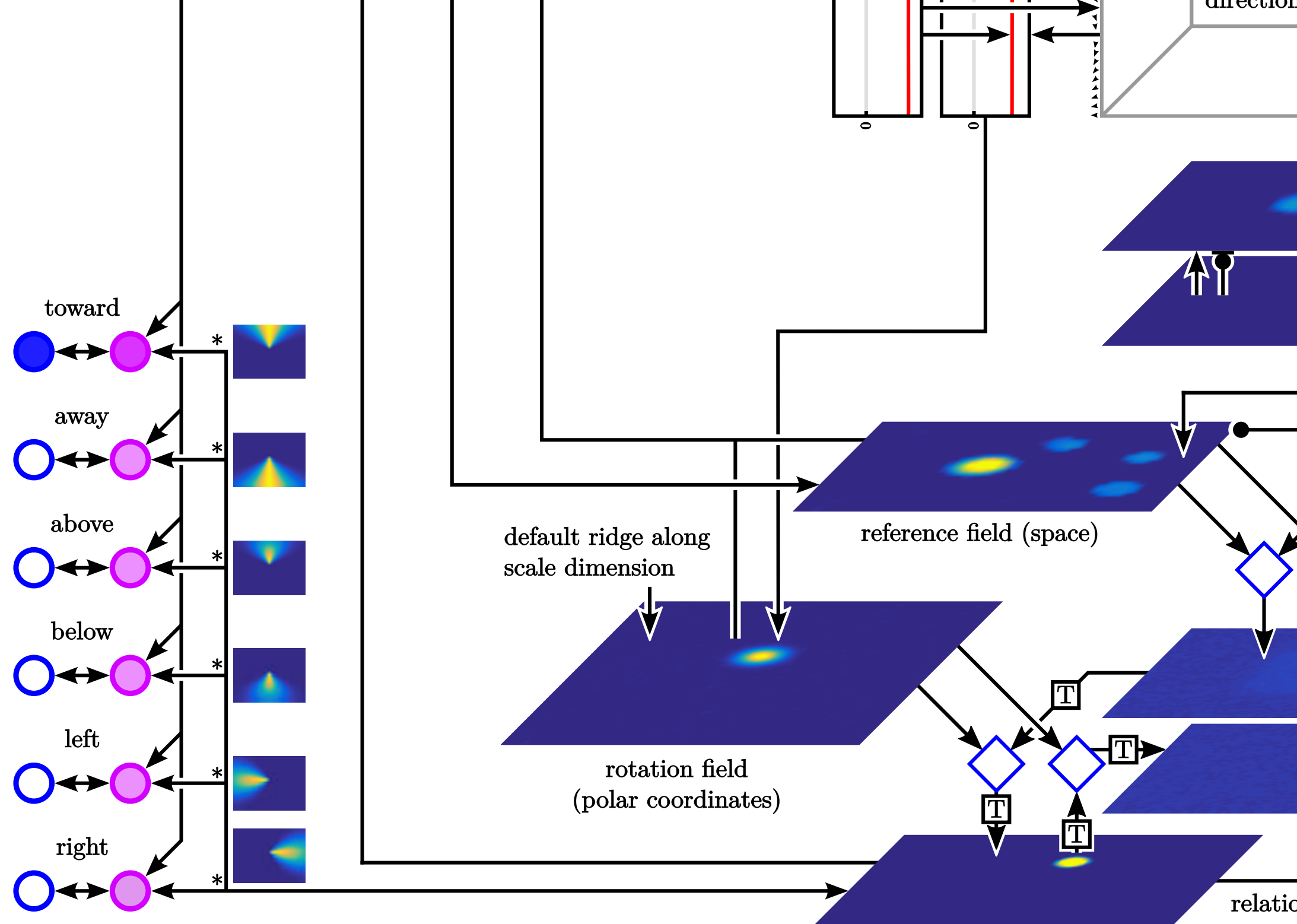


# Grounding movement relations



[Richter,  
Lins,  
Schöner,  
ToPiC  
(2017)]

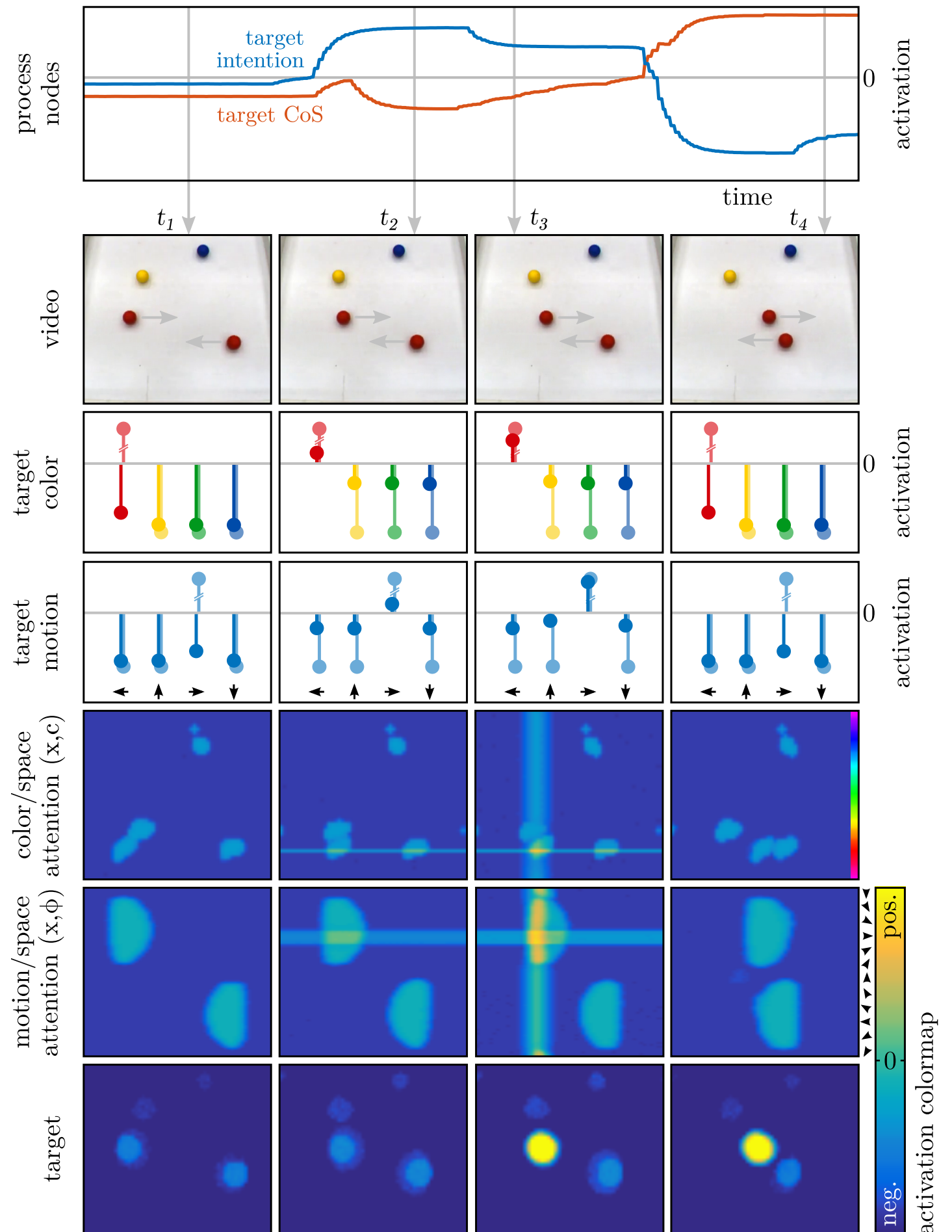




“the red  
moving to the  
right”

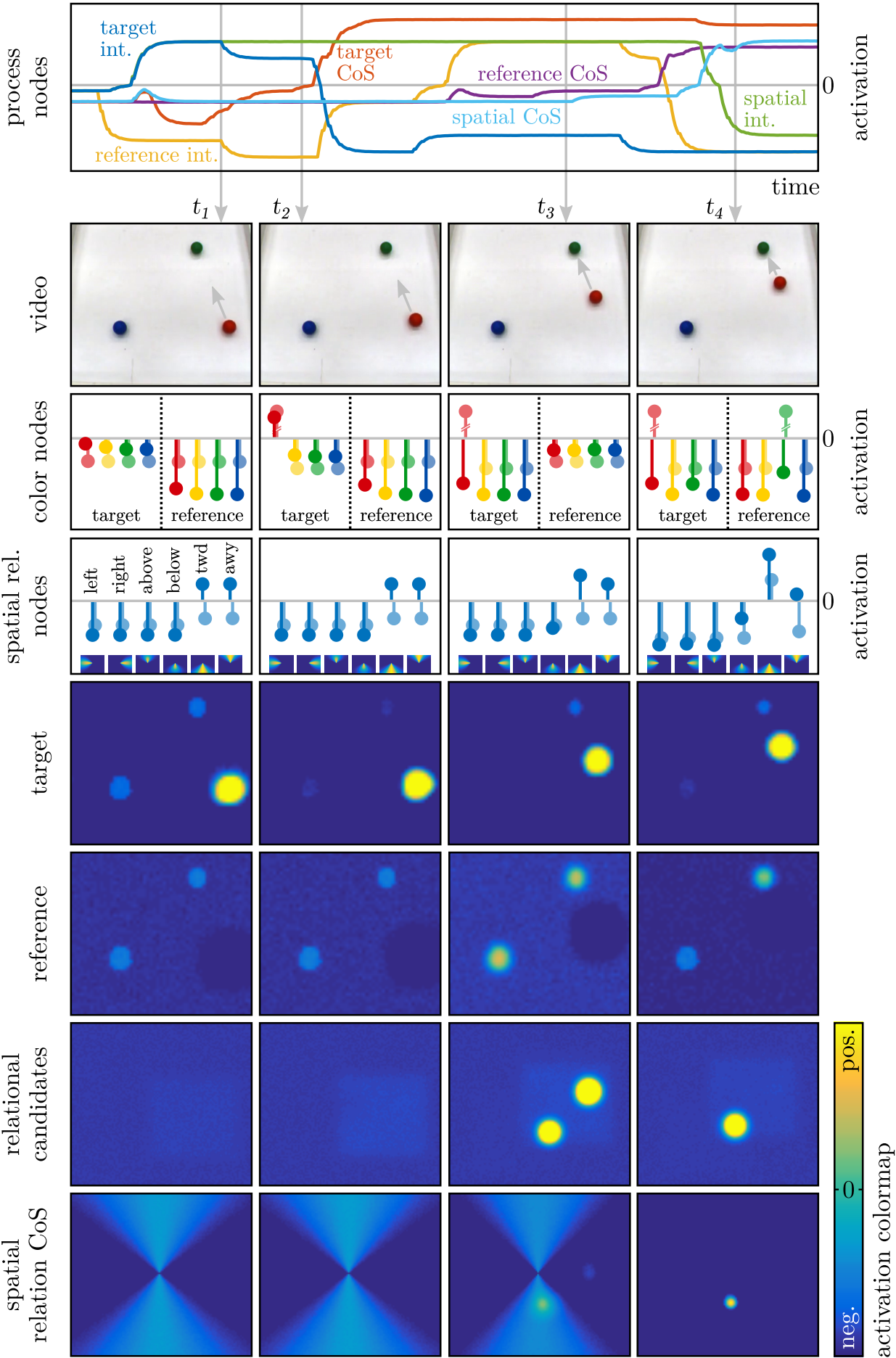
perceptual  
grounding

[Richter et al]



[Richter et al]

description



# Mental mapping and inference

- making sense of propositions (about spatial relations) purely mentally, without any perception to ground in
- and operating on such “sense” by drawing inferences...



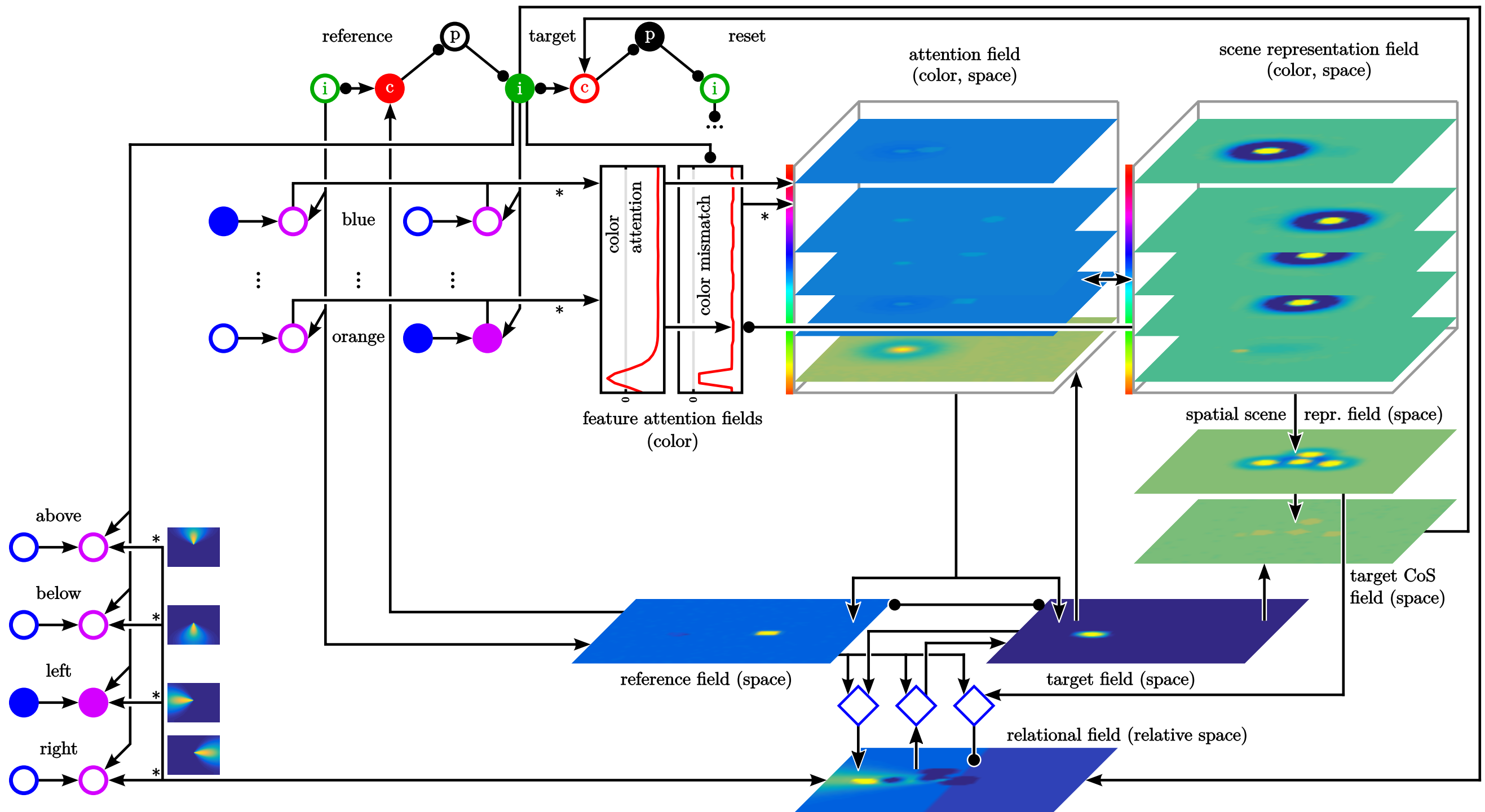
# Mental mapping and inference

## ■ mental map formation from propositions

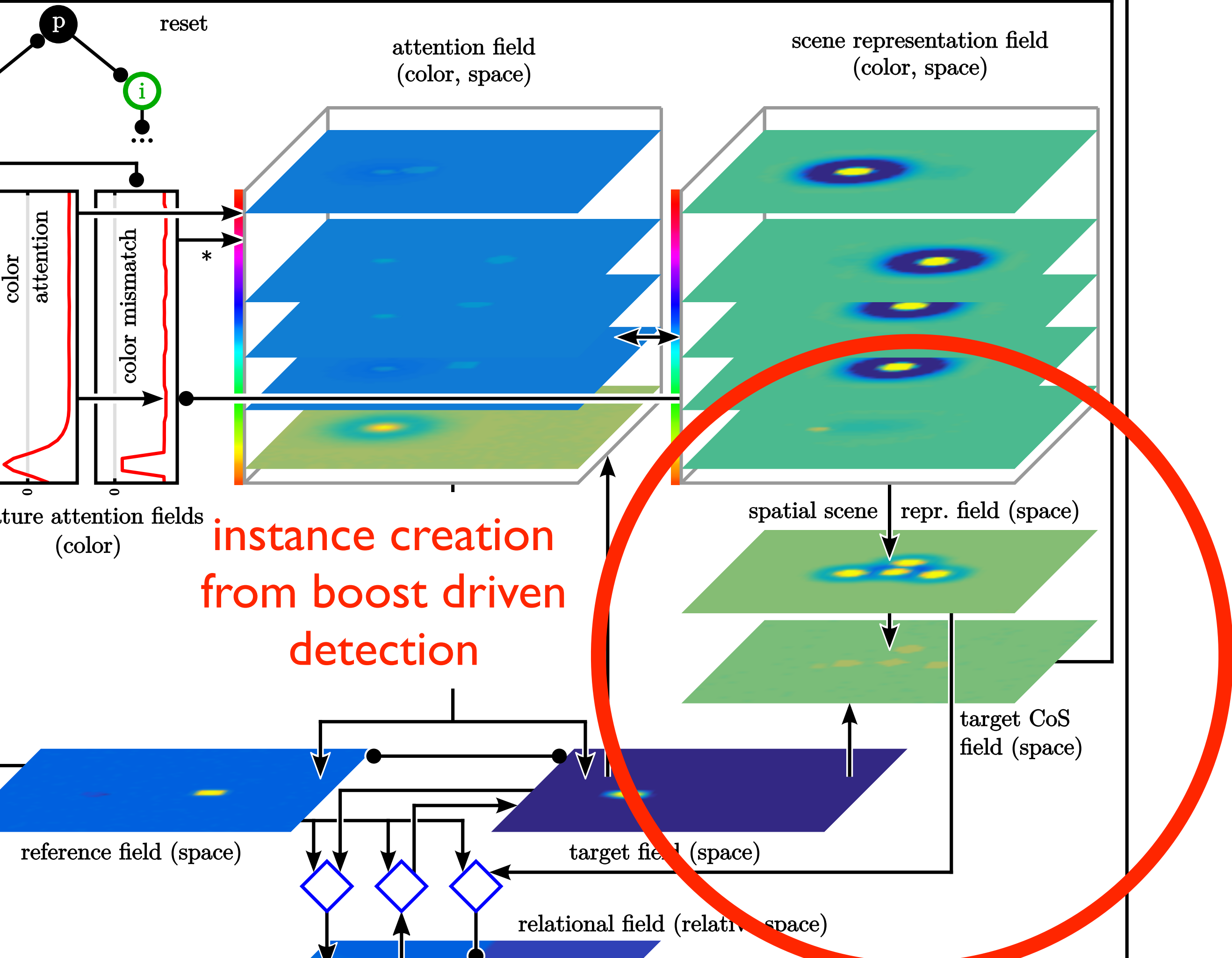
- “There is a cyan object above a green object.”
- “There is a red object to the left of the green object.”
- “There is a blue object to the right of the red object.”
- “There is an orange object to the left of the blue object.”

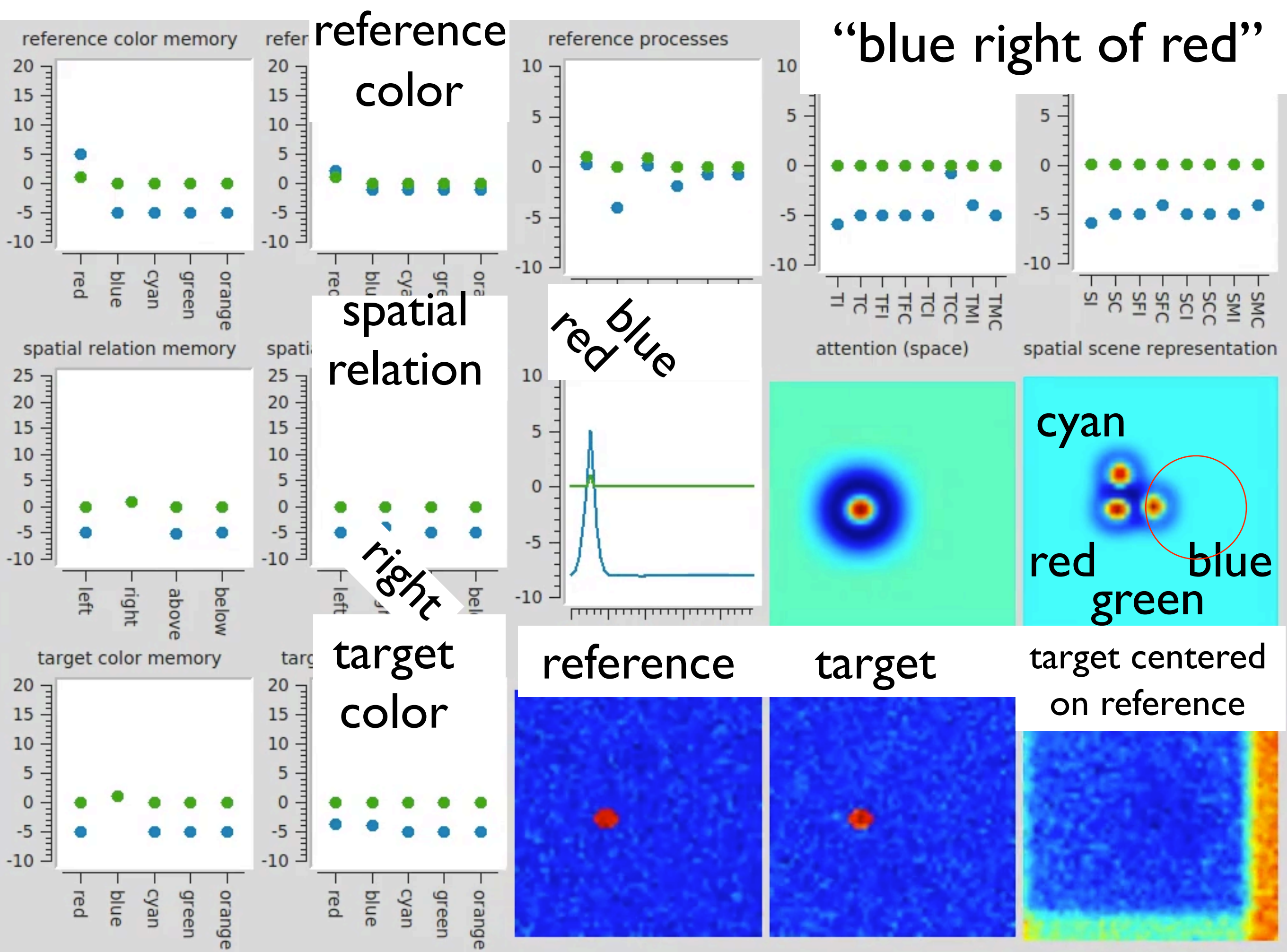
## ■ inference

- “Where is the blue object relative to the red object?”



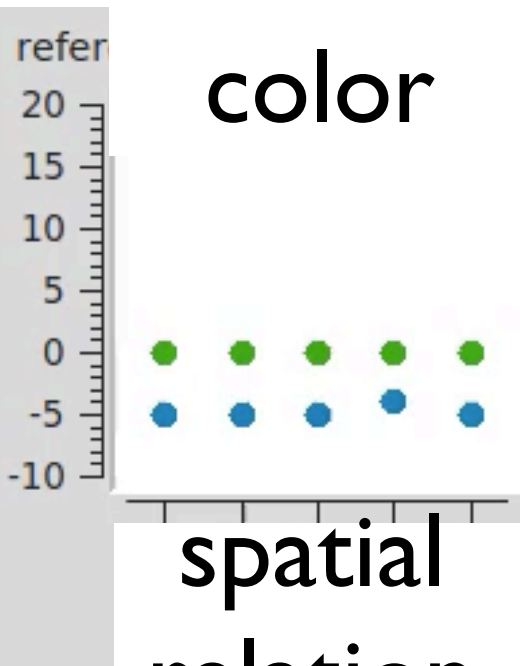
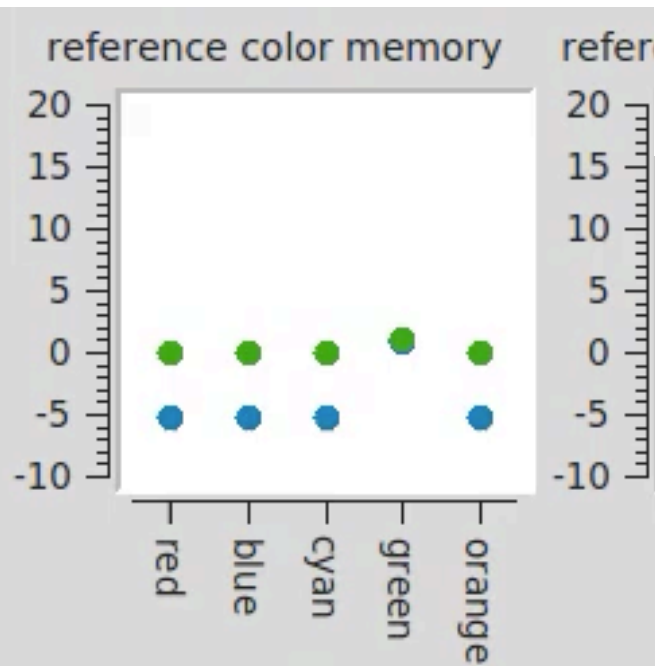
[Kounatidou, Richter, Schöner, CogSci 2018]



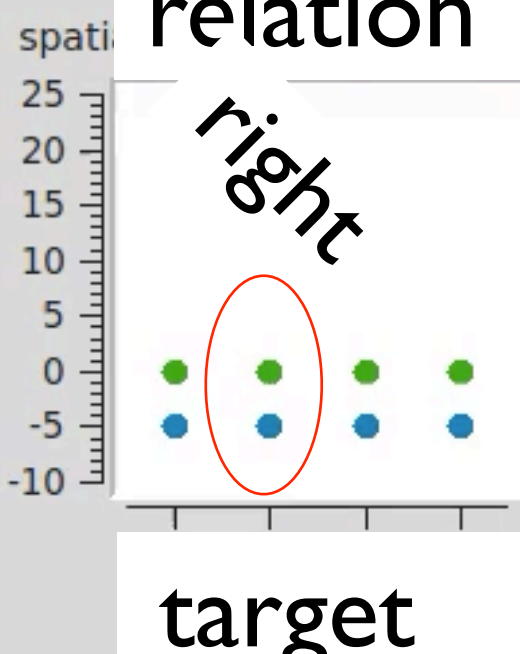
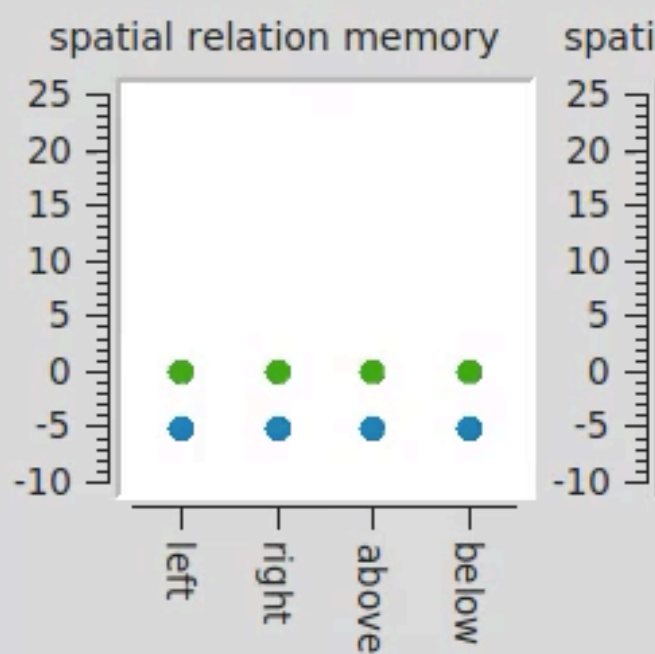




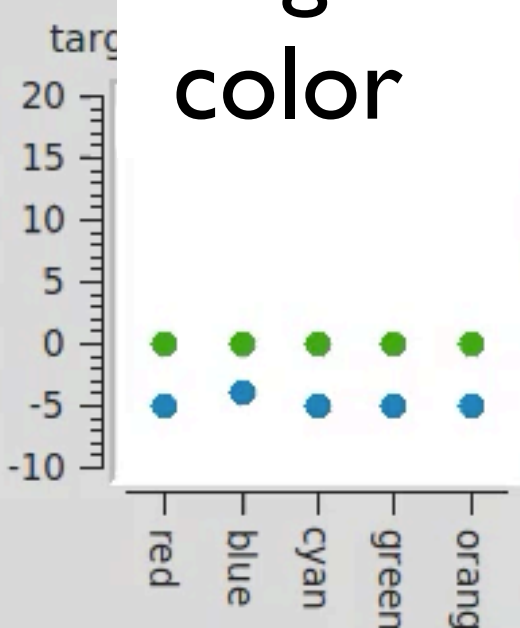
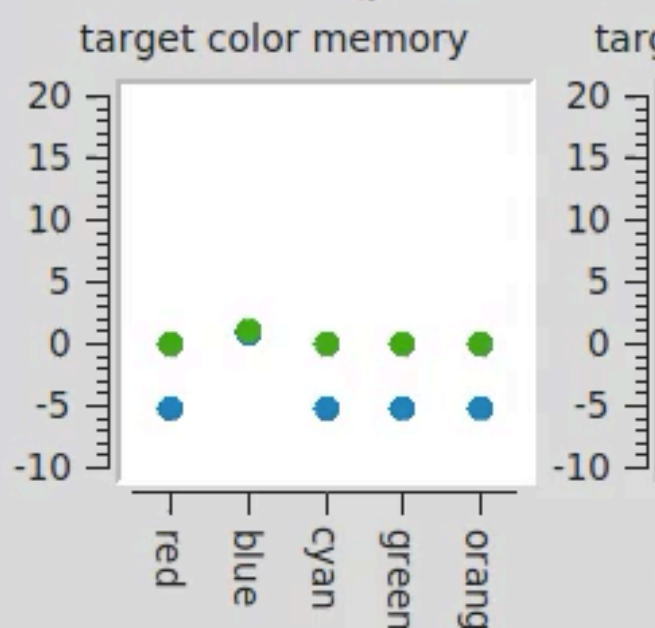
reference  
color



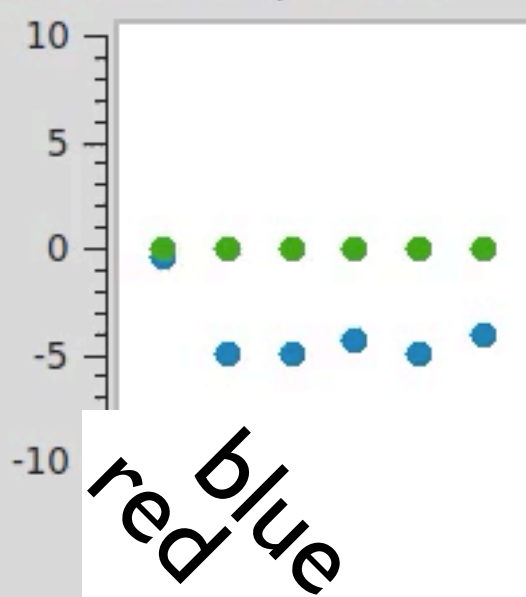
spatial  
relation



target  
color

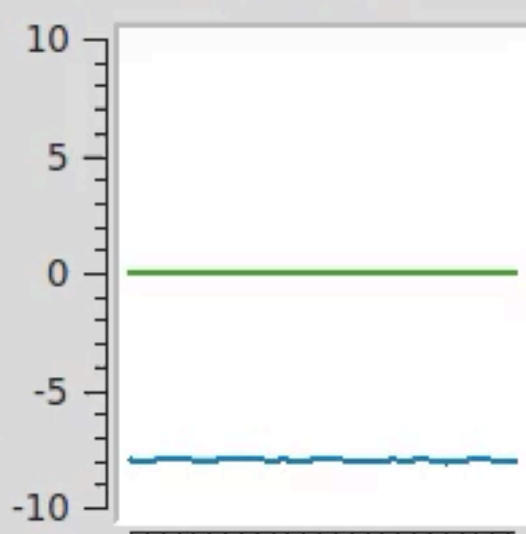


reference processes

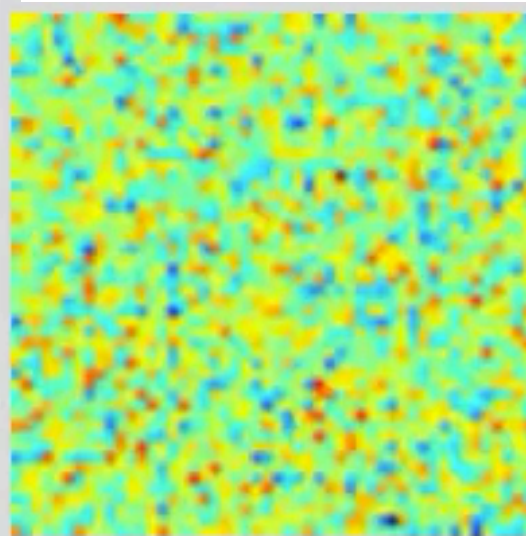


red blue

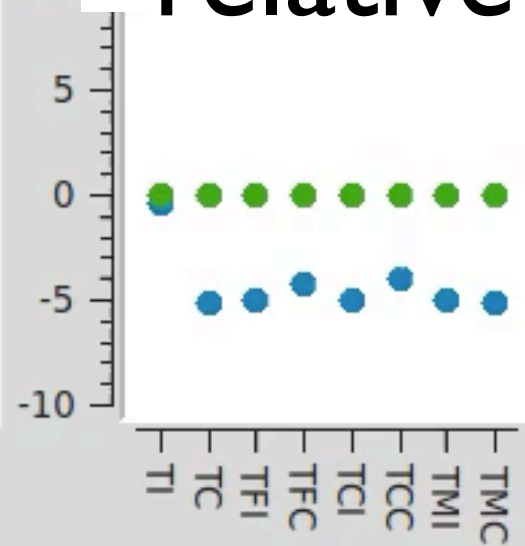
color attention



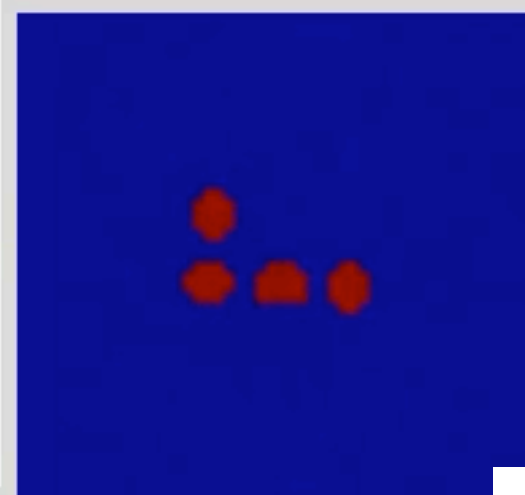
reference



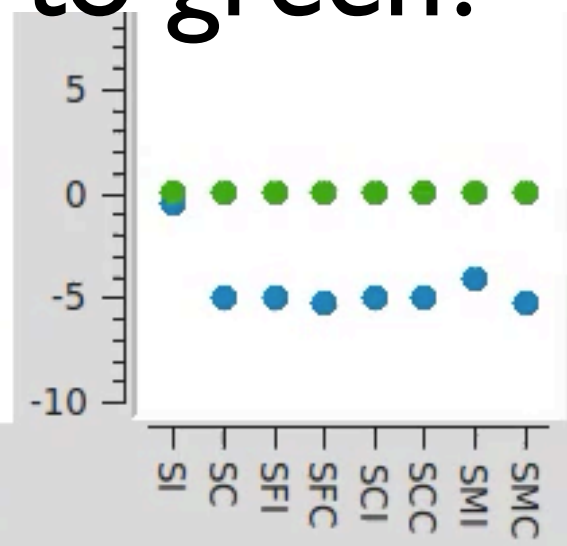
“where is blue  
relative to green?”



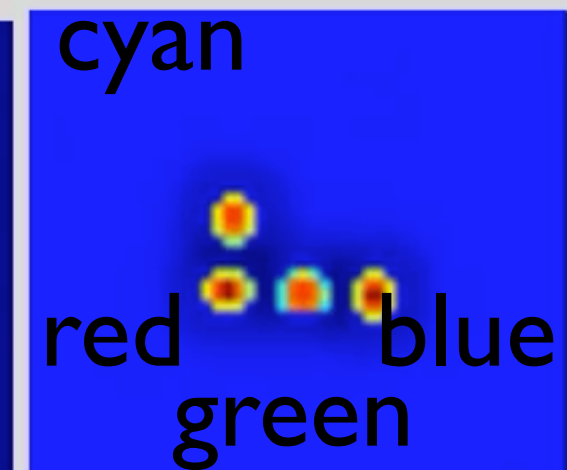
attention (space)



target



spatial scene representation



target centered  
on reference

# Conclusion

- ... higher dimensional fields
- arranged in architectures...
- deliver higher cognitive functions
- such as perceptual grounding, describing scenes, mental imaging, and inference