Grounding Spatial Language:

A case study in Dynamic Field Theory as a framework for neurally grounded architectures for higher cognition

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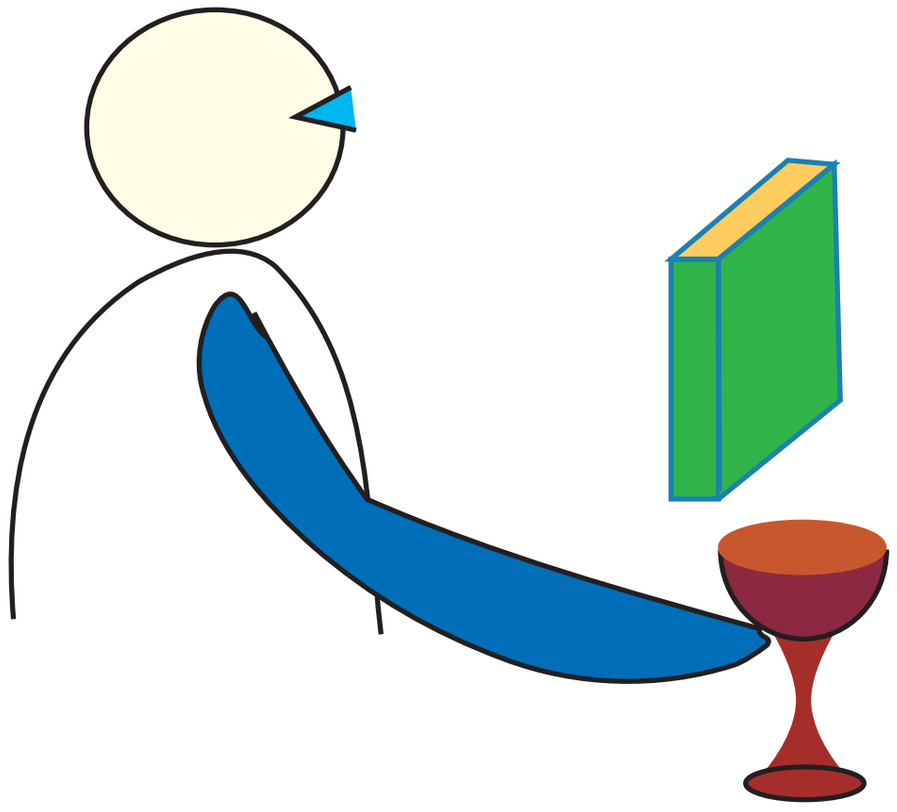
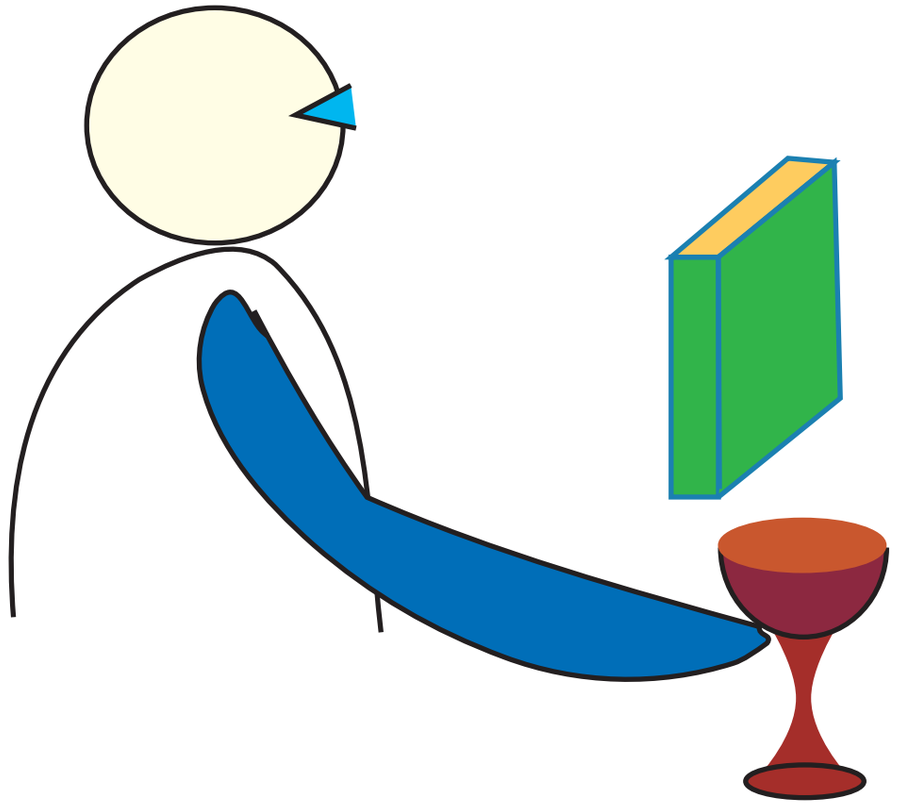
Perceptually grounding language

- human communication in its simplest form is about things that are our there in our environment, perceivable, reachable by action
- e.g., this cup is brown



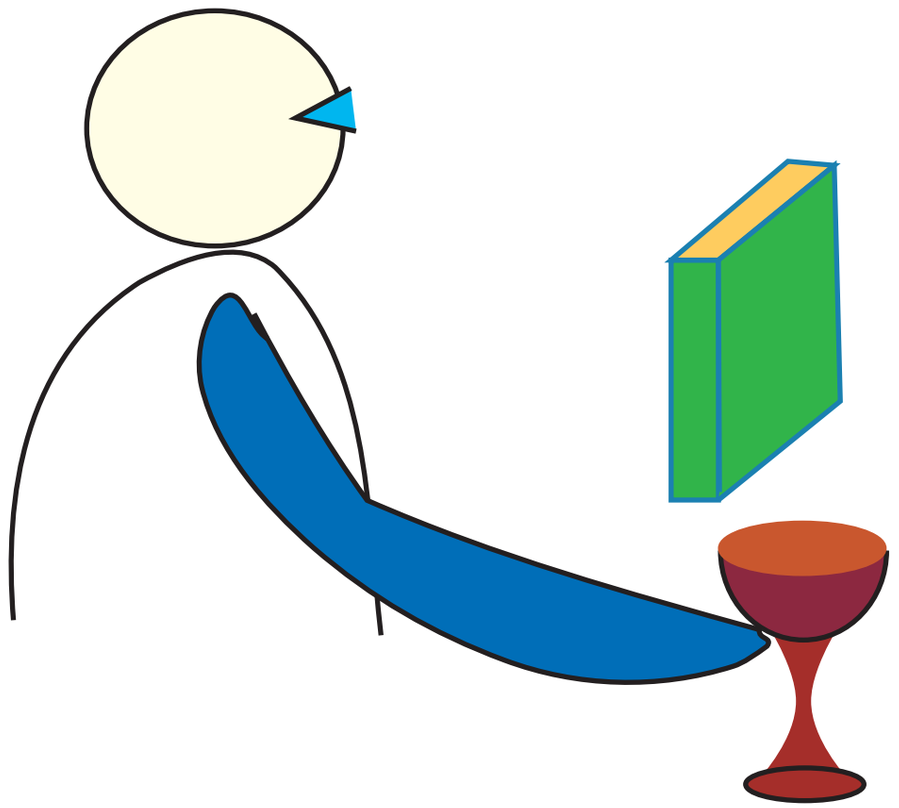
Perceptually grounding language

- this could be based by both the speaker and the listener looking at the scene and grounding the word “cup” by bringing an object of that category into the foreground



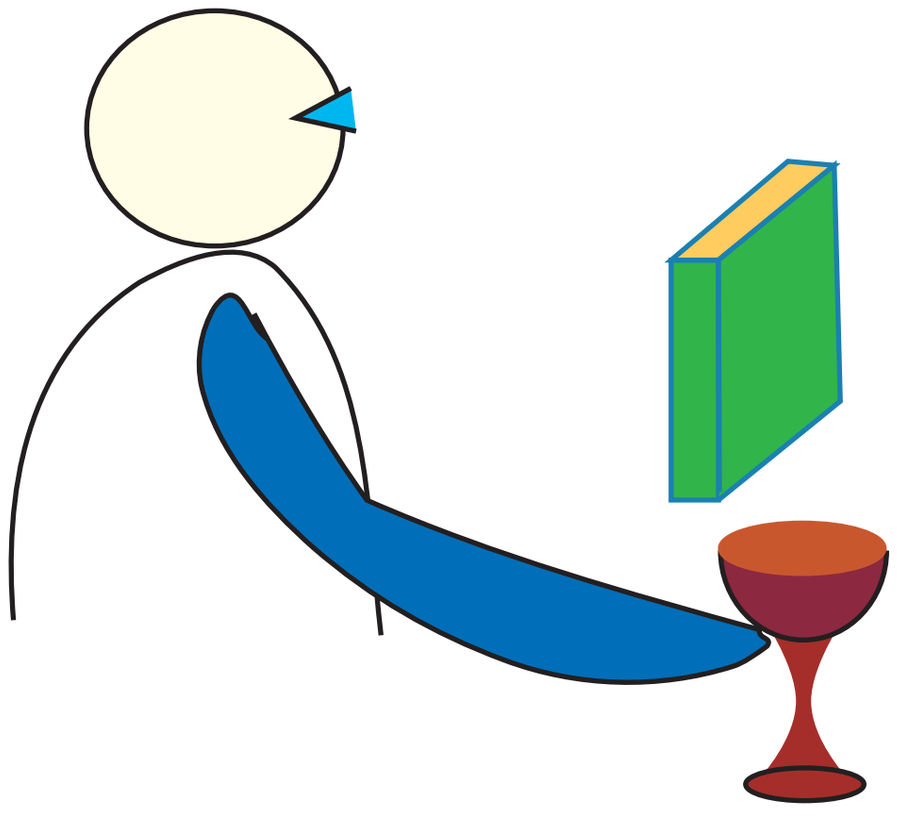
Perceptually grounding language

- that process could be mediated by other forms of communication, e.g., pointing (deictic code)



Perceptually grounding language

- that process could also be mediated by spatial language, e.g., "the cup to the right of the green book is brown" (spatial language)
- (which presupposes that the reference object "green book" is grounded for speaker and observer)



Perceptually grounding language vs. describing

- Perceptual grounding: understanding phrases by finding in the visual array the objects to which the phrase refers
- Describing: producing phrases that describe an observed scene or event

"what is to the right of the green object"

Spatial language

- such utterances as “to the left of”, “on top of”, “in”, “in front of”, “toward the south”, “in front of” etc.
- a part of language that deep: evolves slowly in languages, with profound differences between languages and cultures, that is particularly challenging for “grounding”

Spatial language

- Examples:
  - some cultures use absolute directions "north", "south" etc. even on a local scale (e.g, "the car north of the house" rather than "the car in front of the house").
  - others have special spatial language referring to geographical landmarks (e.g., islanders who have a word for "toward the beach" vs. "away from the beach, toward the inland")
  - "in front of" is used differently even in different indo-european languages

Grounding spatial language

- involves necessarily reference frames… there are 4 basic and commonly used reference frames

Grounding spatial language

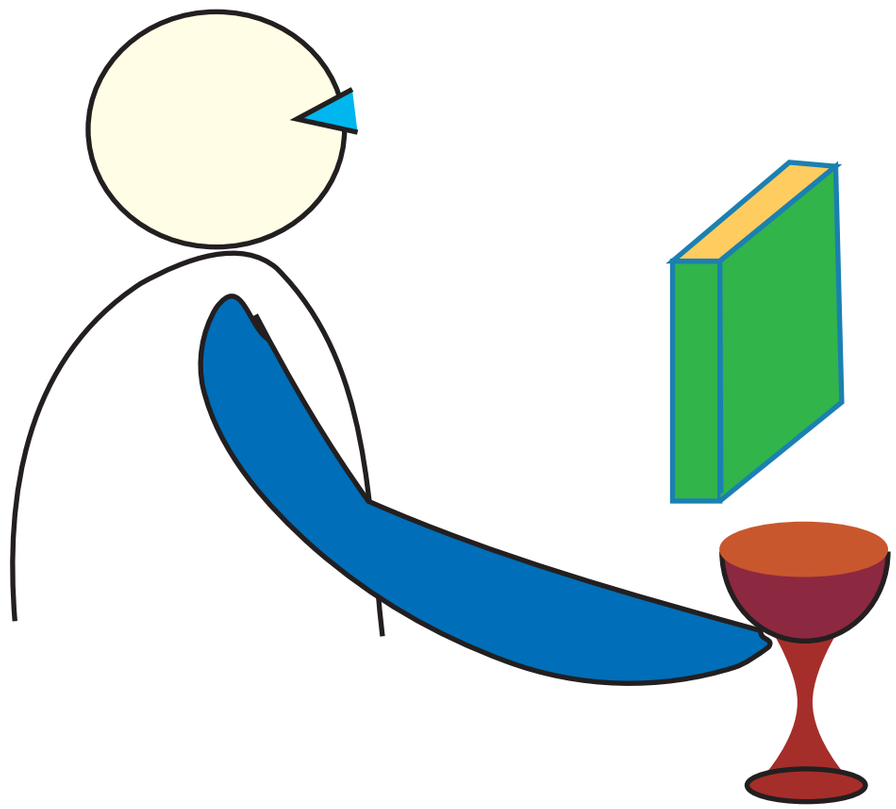
- orientation relative to speaker, position centered in speaker
  - “on my left”
- orientation relative to world/object, position centered in speaker:
  - “north”, “south...” or “leeward”, “windward” ...
- orientation relative to speaker, position centered in object
  - “the cup to the right of the bottle”
- orientation relative to object, position centered in object
  - “leave the train on the right hand side”

Grounding spatial language

- reference frames are subtle
  - Example: “in front of” can be in an ego-centric frame if the object has no special long axis and front end (e.g., “in front of the tree” meaning “between me and the tree”)
  - but can be in an object centered frame if the object has a long axis and front end (e.g. “in front of the car” meaning “on the side of the car in the direction in which its front end points”)
    - (and on this count different languages differ)

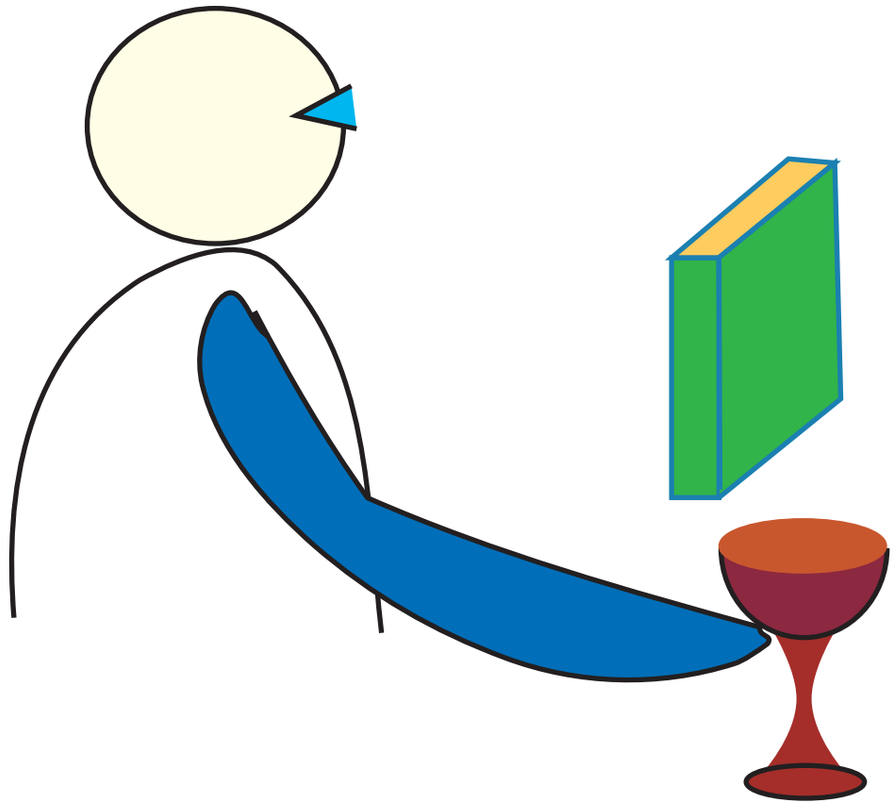
Grounding spatial language

- spatial language often involves reference objects
  - Example: “to the right of the green book”: this is a statement in an ego-centric reference frame for direction but that is spatially centered in an object



Grounding spatial language

- spatial language often involves coordinate transforms
  - e.g., "to the right of the green book": coordinate transformation: from the speaker/observer centered reference frame into a frame centered in the reference object
  - e.g., "to my right" requires the listener to transform the reference frame from his or her own view to the directional and positional frame of the speaker



Operations involved in grounding spatial language

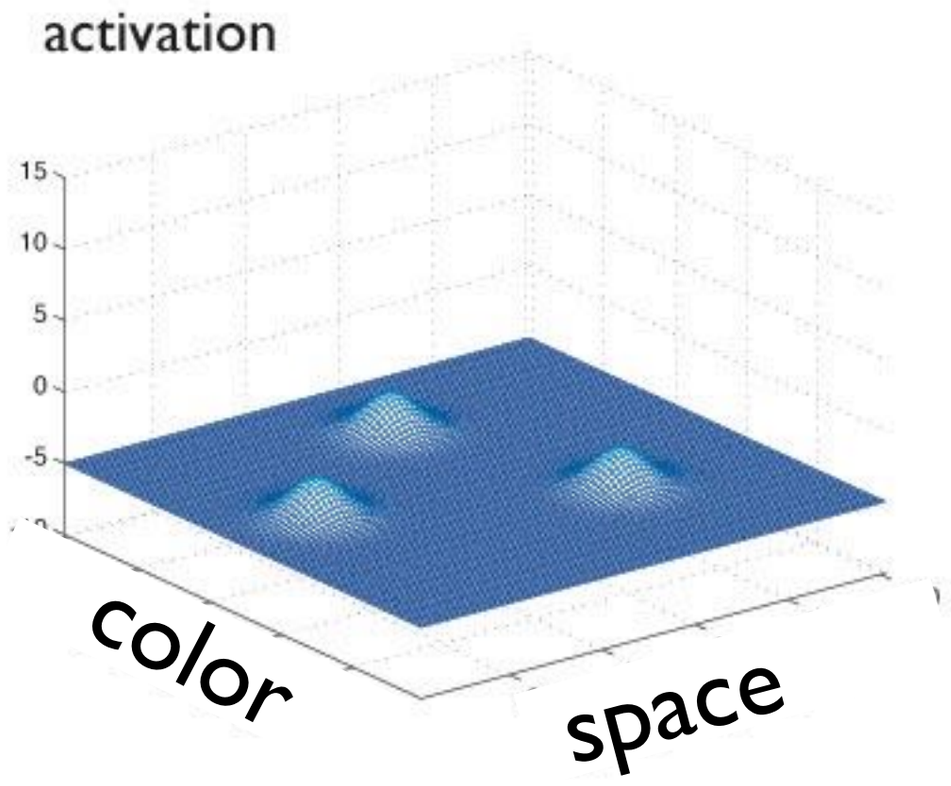
- bring objects (target and reference) into the perceptual foreground (visually find them)
- make coordinate transformation
- apply comparison operators

DFT approach to bringing a perceptual object into the foreground

- => lecture on higher-dimensional fields

Bringing an object to the foreground

- visual search: “where is the red object”?



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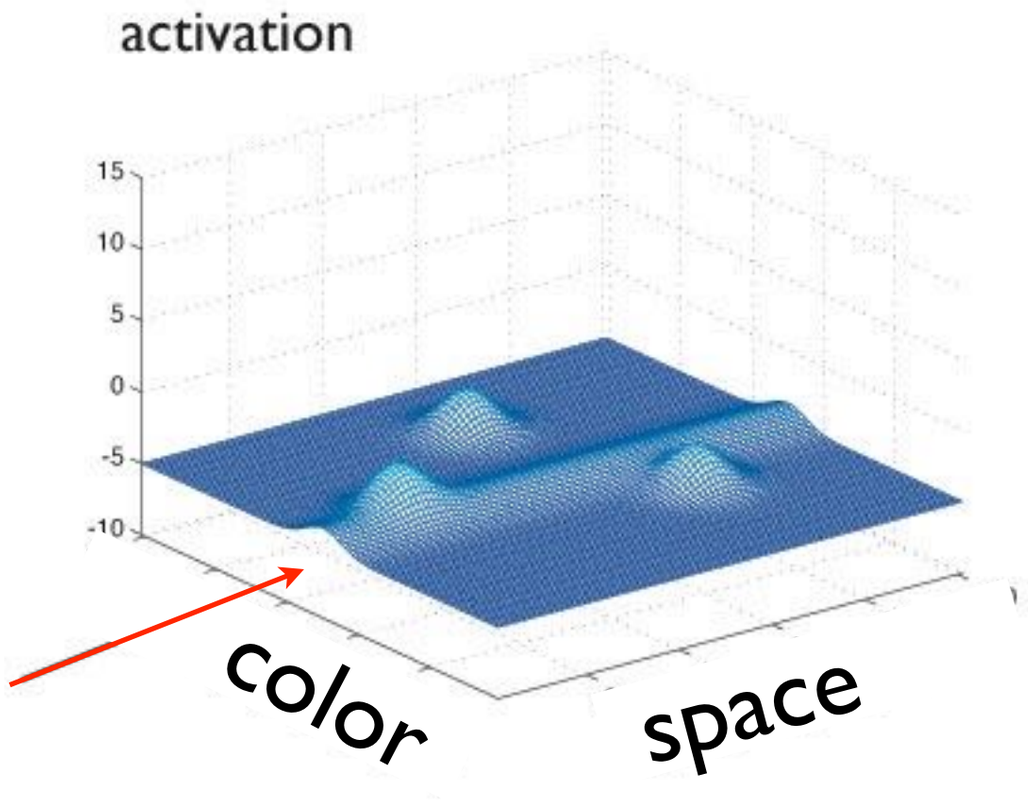

ridge specifying red

Bringing an object to the foreground

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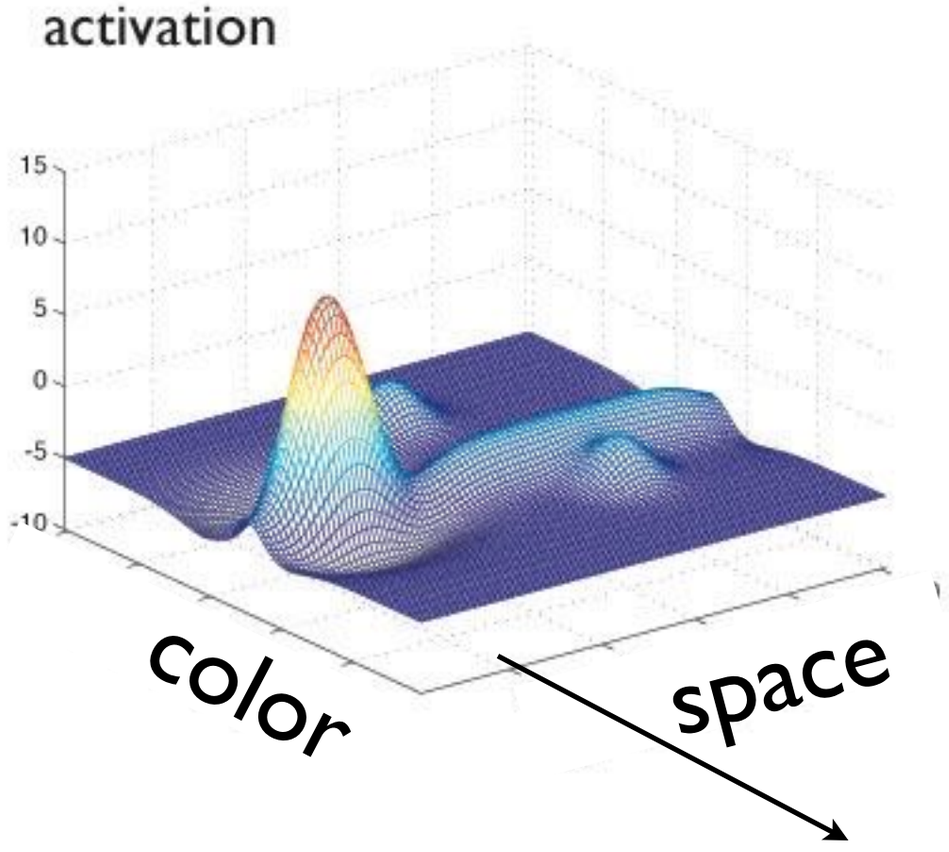
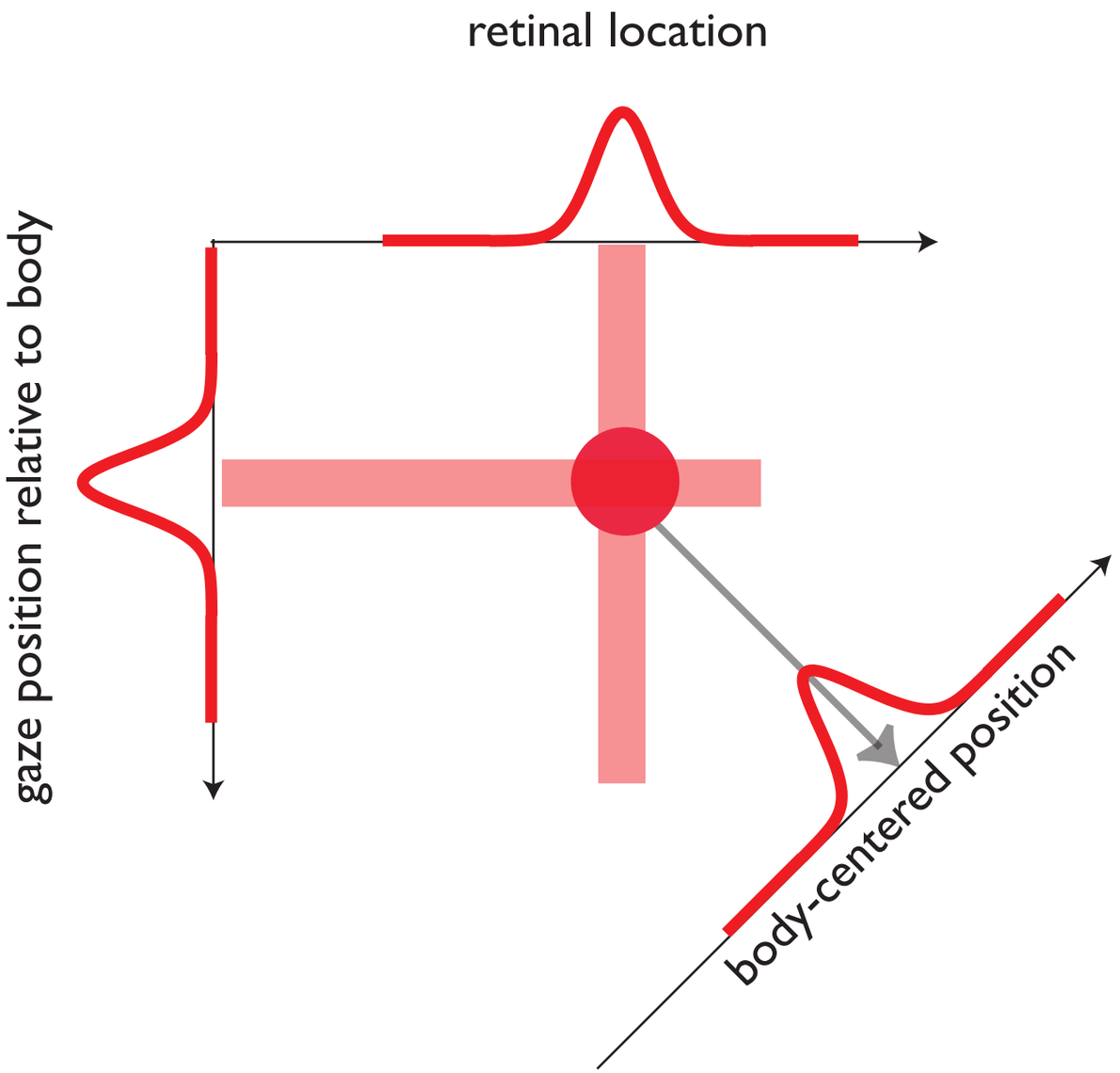


read out spatial location of red object

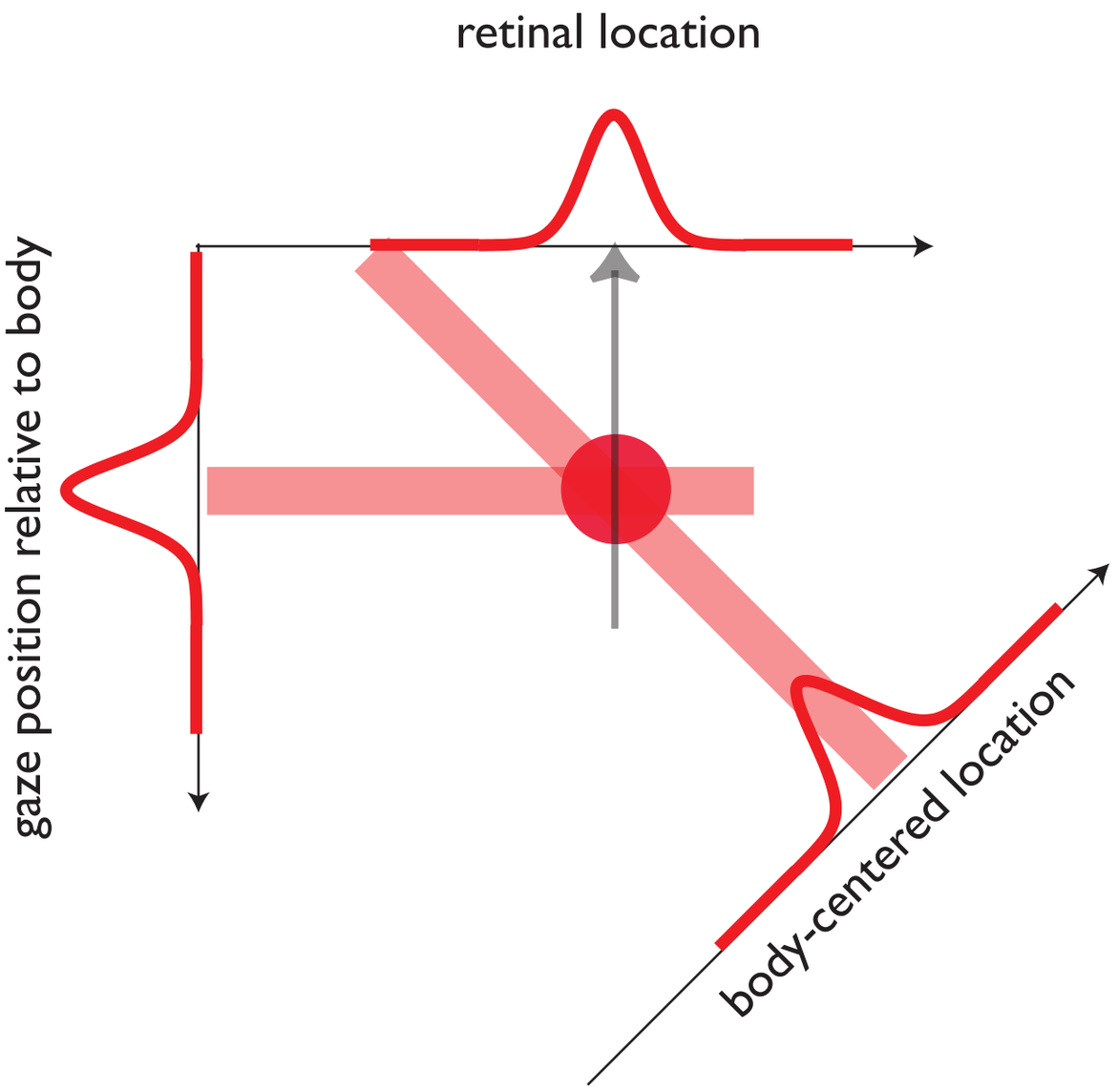
DFT approach to coordinate transforms

- => lecture on higher-dimensional fields

Coordinate transformations

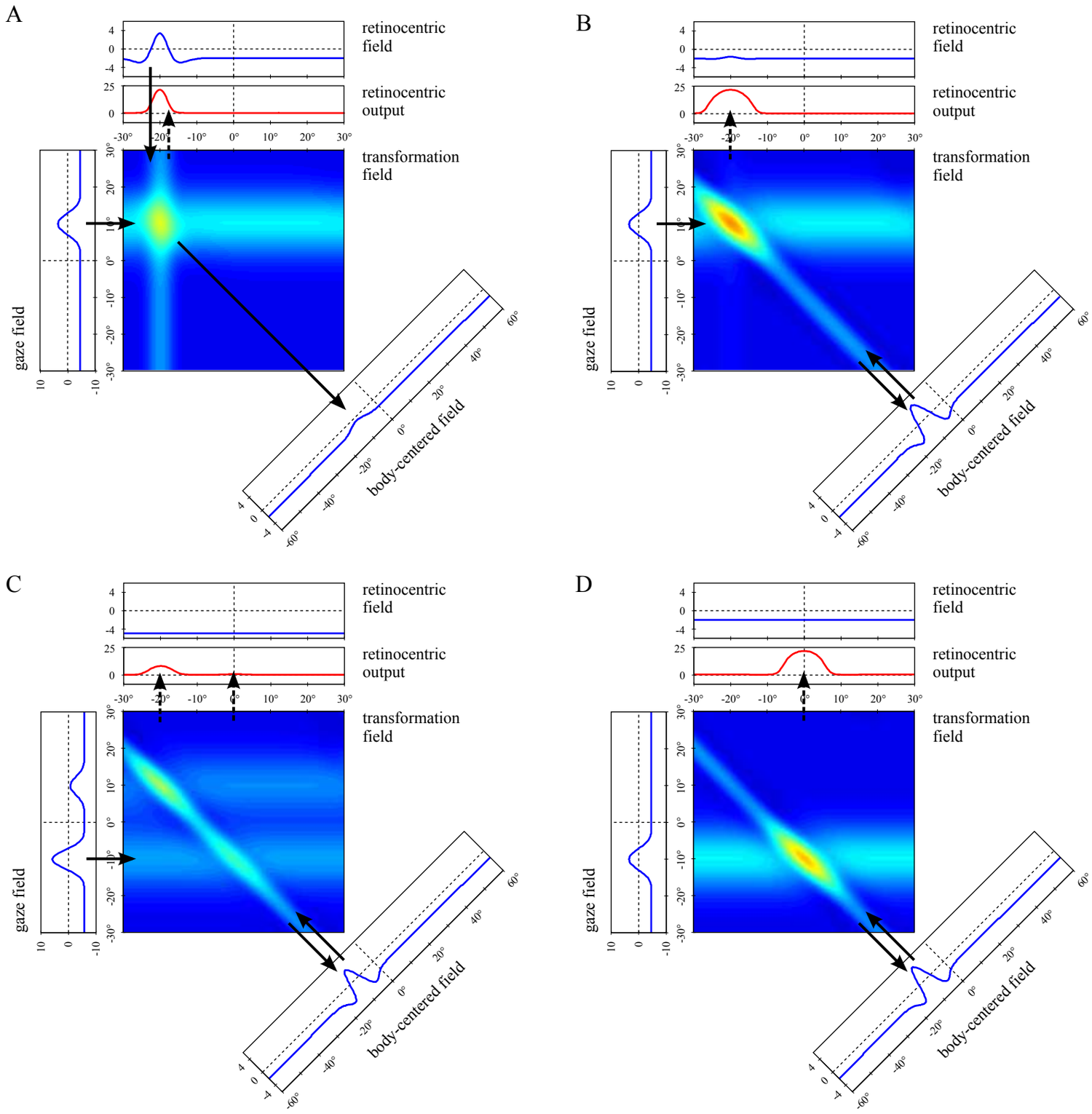


Coordinate transformations



Coordinate transformations

- predict retinal location following gaze shift



[Schneegans, Schöner, 2012]

Coordinate transformations

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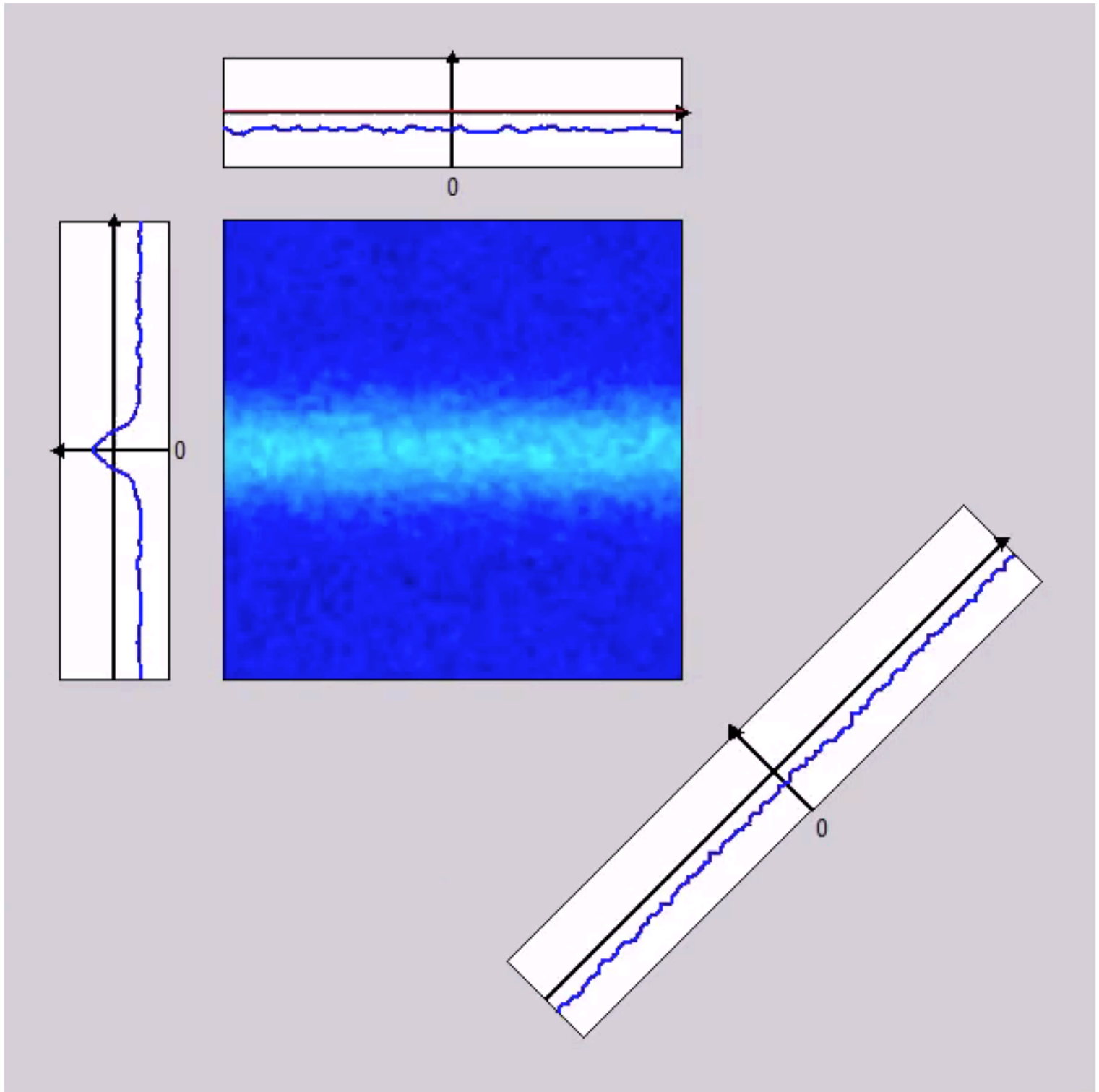
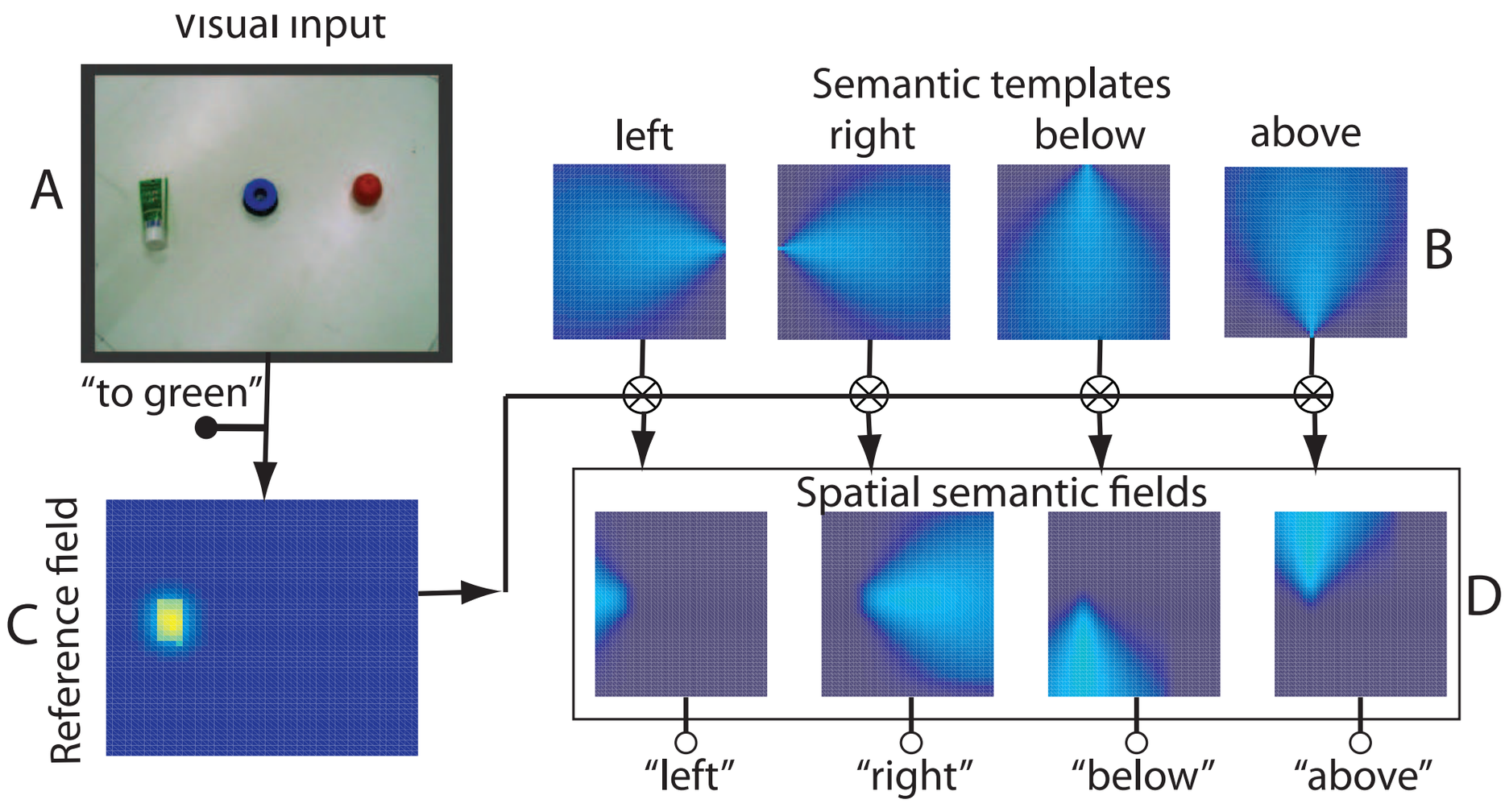


[Schneegans, Schöner, 2012]

DFT approach to applying operators

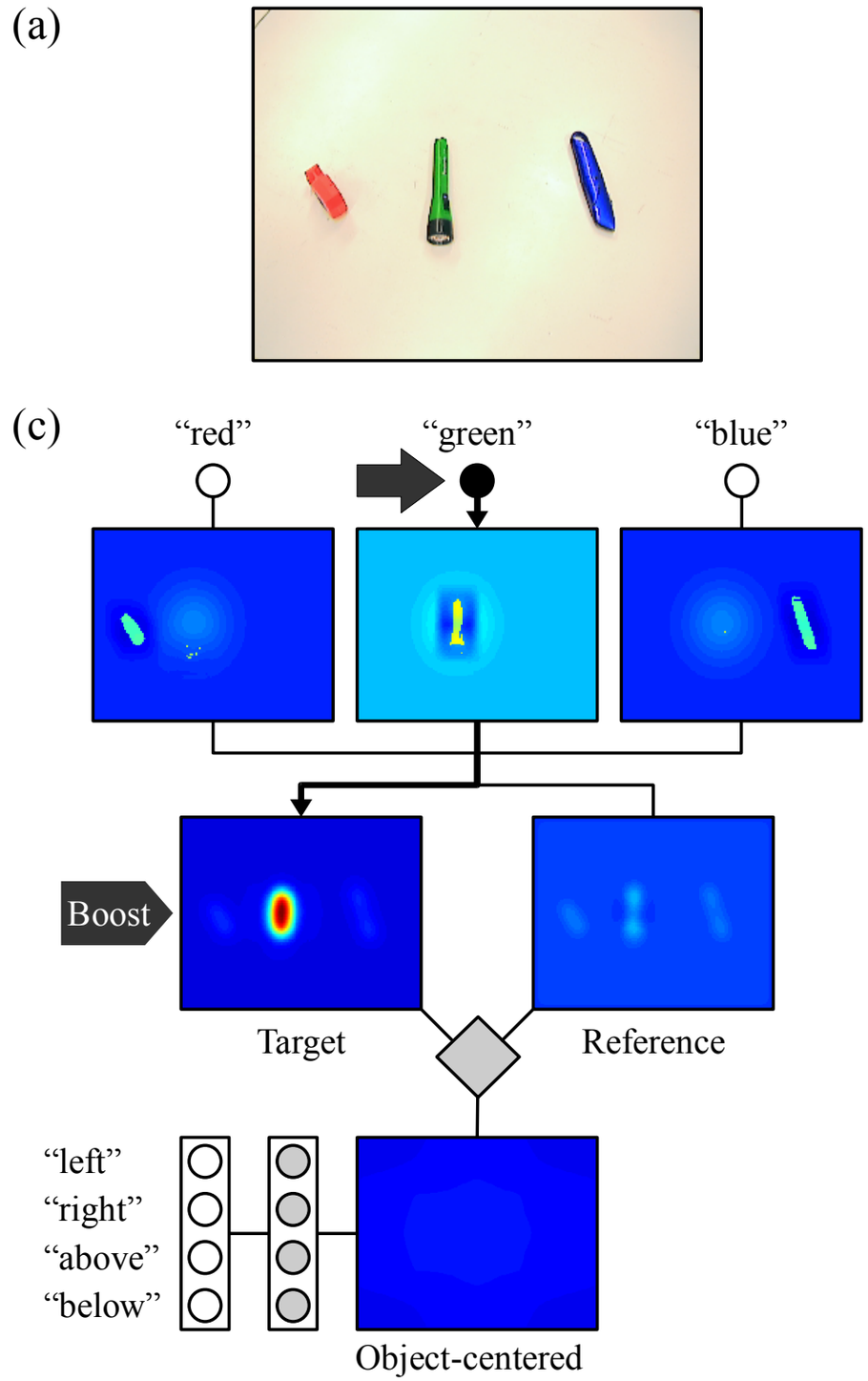
DFT approach to applying operators

- based on convolution of fields with kernels



[from: Lipinski, Sandamirskaya, Schöner, 2009]

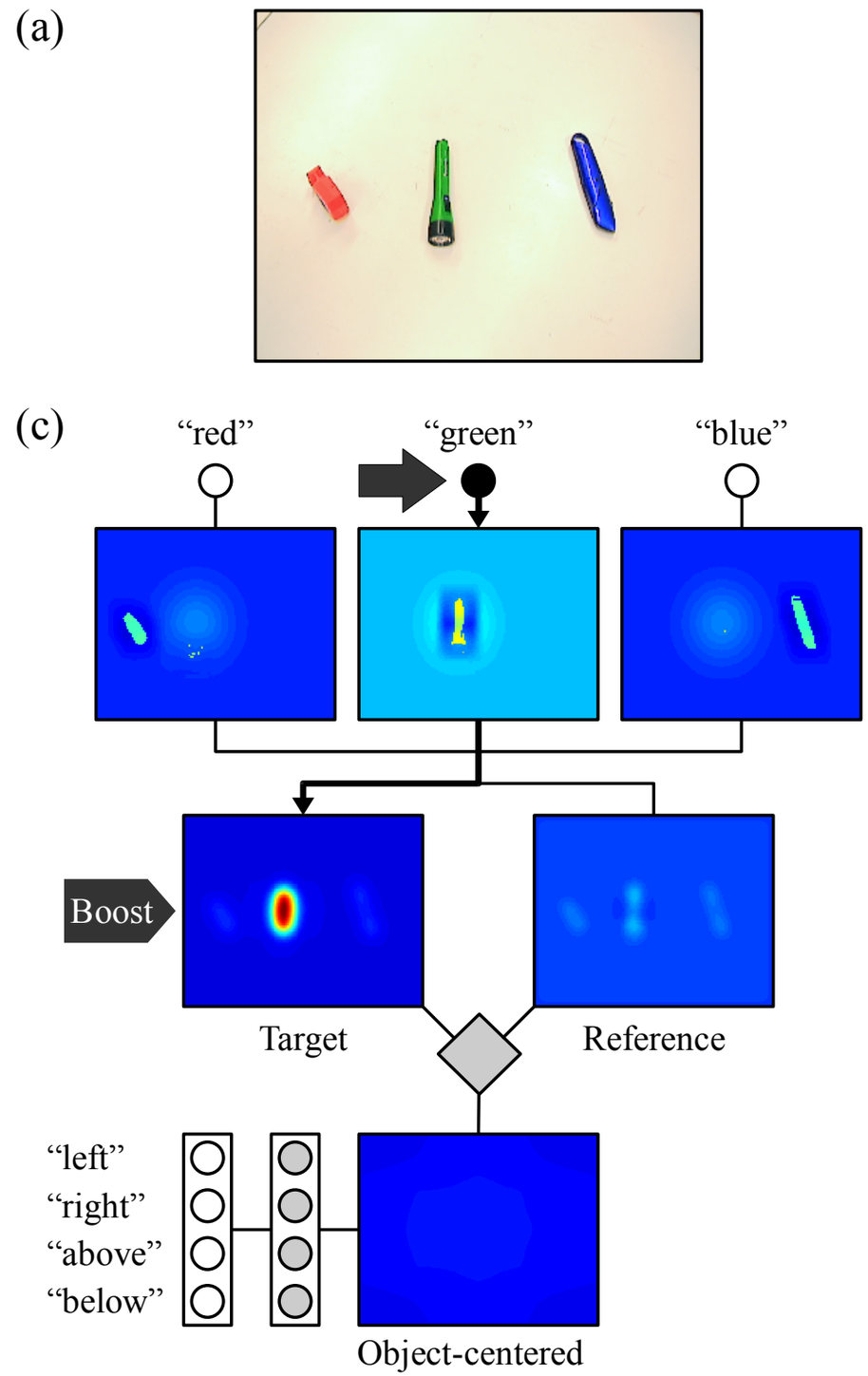
A cognitive architecture for grounded spatial language in DFT



[Lipinski et al: JEP:LMC (2011)]

Spatial comparison in DFT

- bring objects into foreground
- make coordinate transformation
- apply comparison operators



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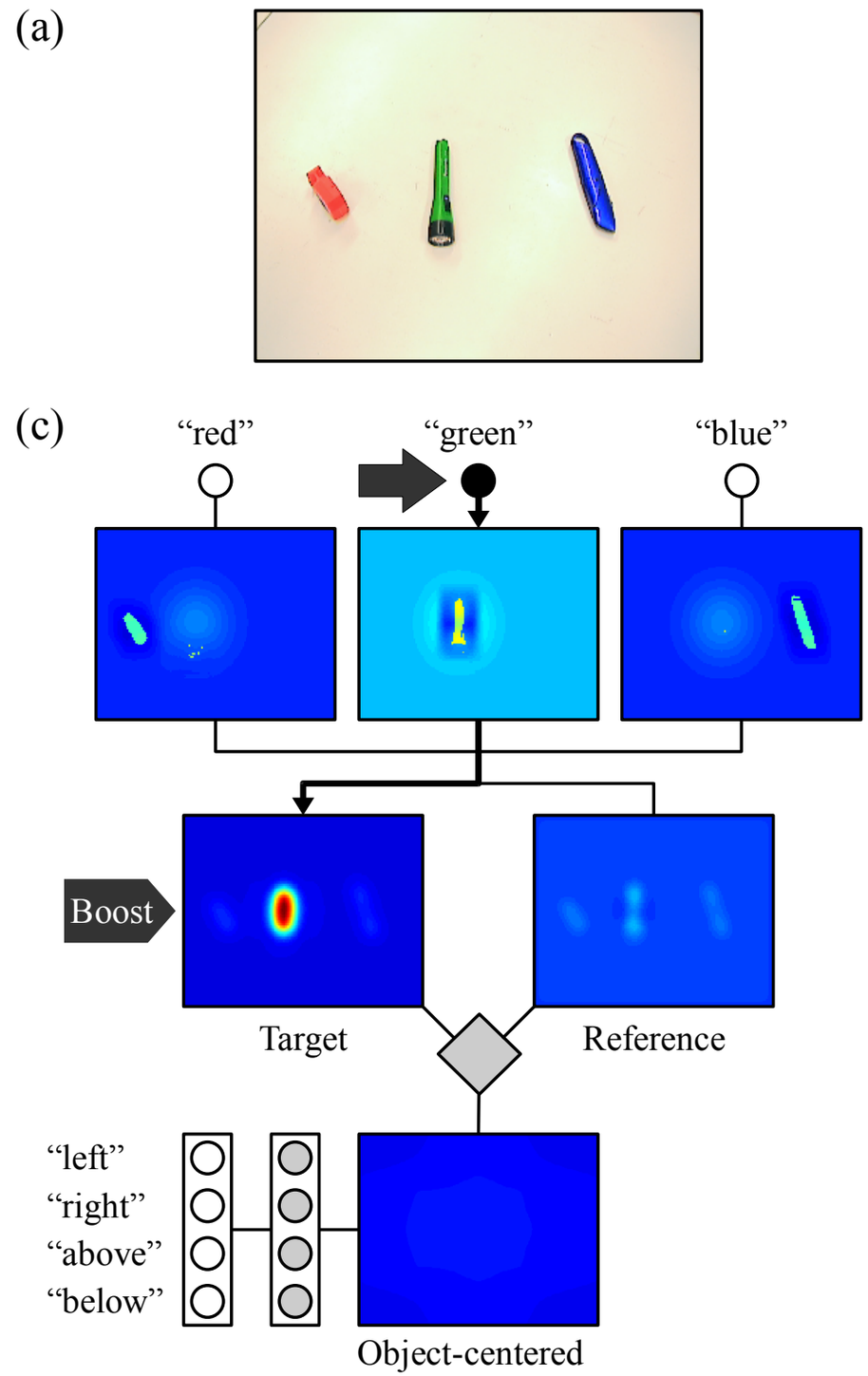

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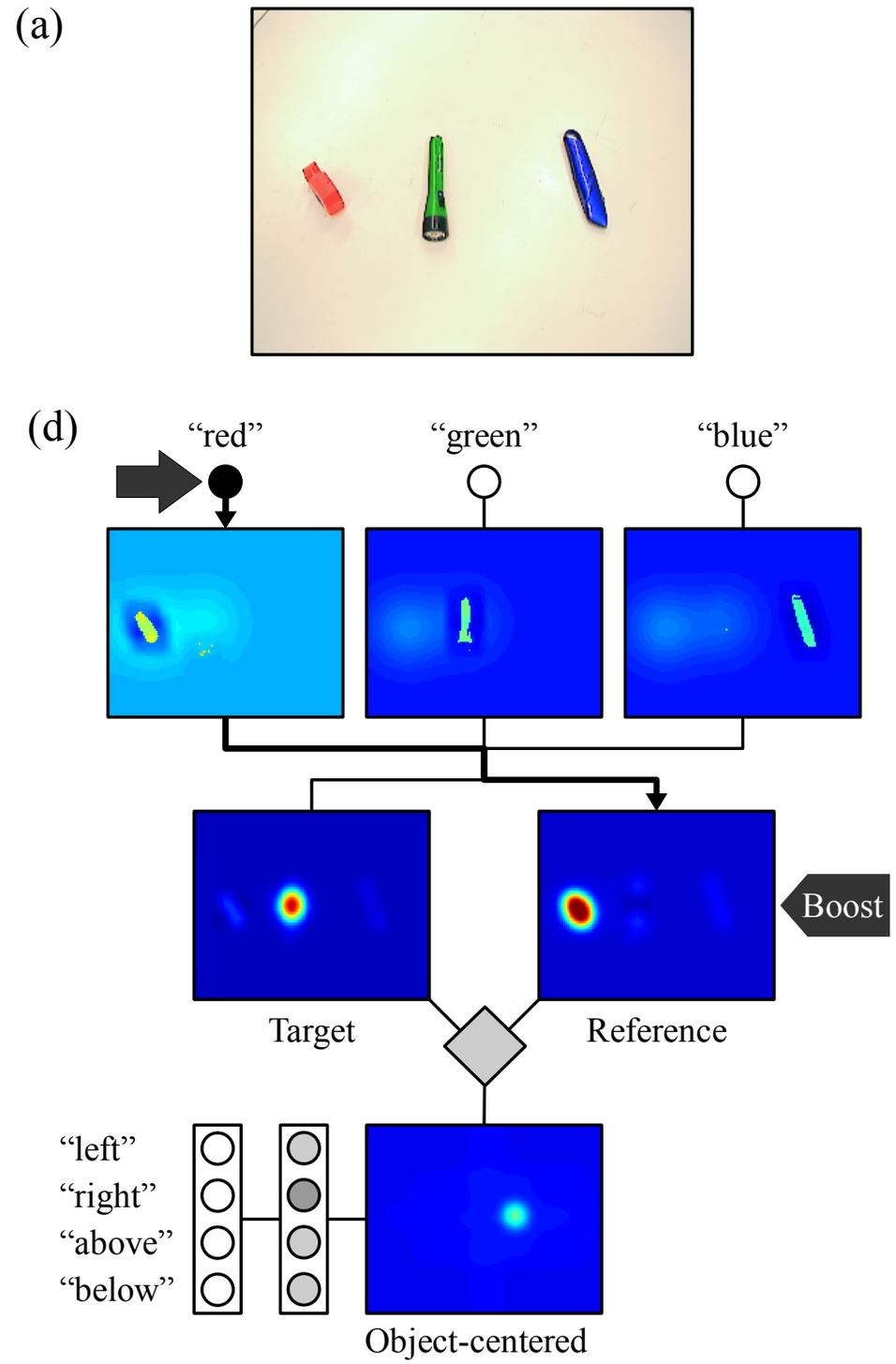

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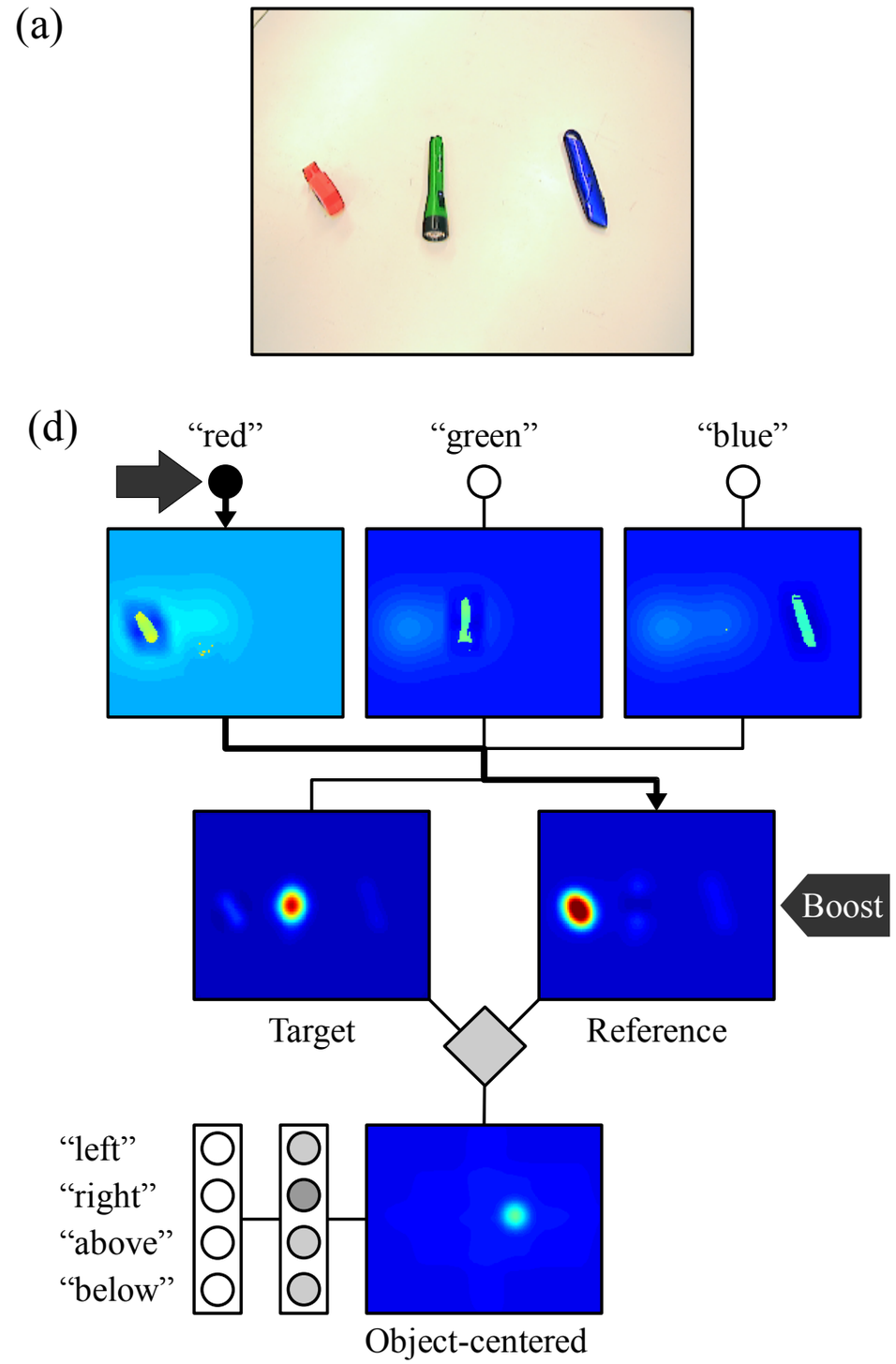

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Spatial comparison in DFT

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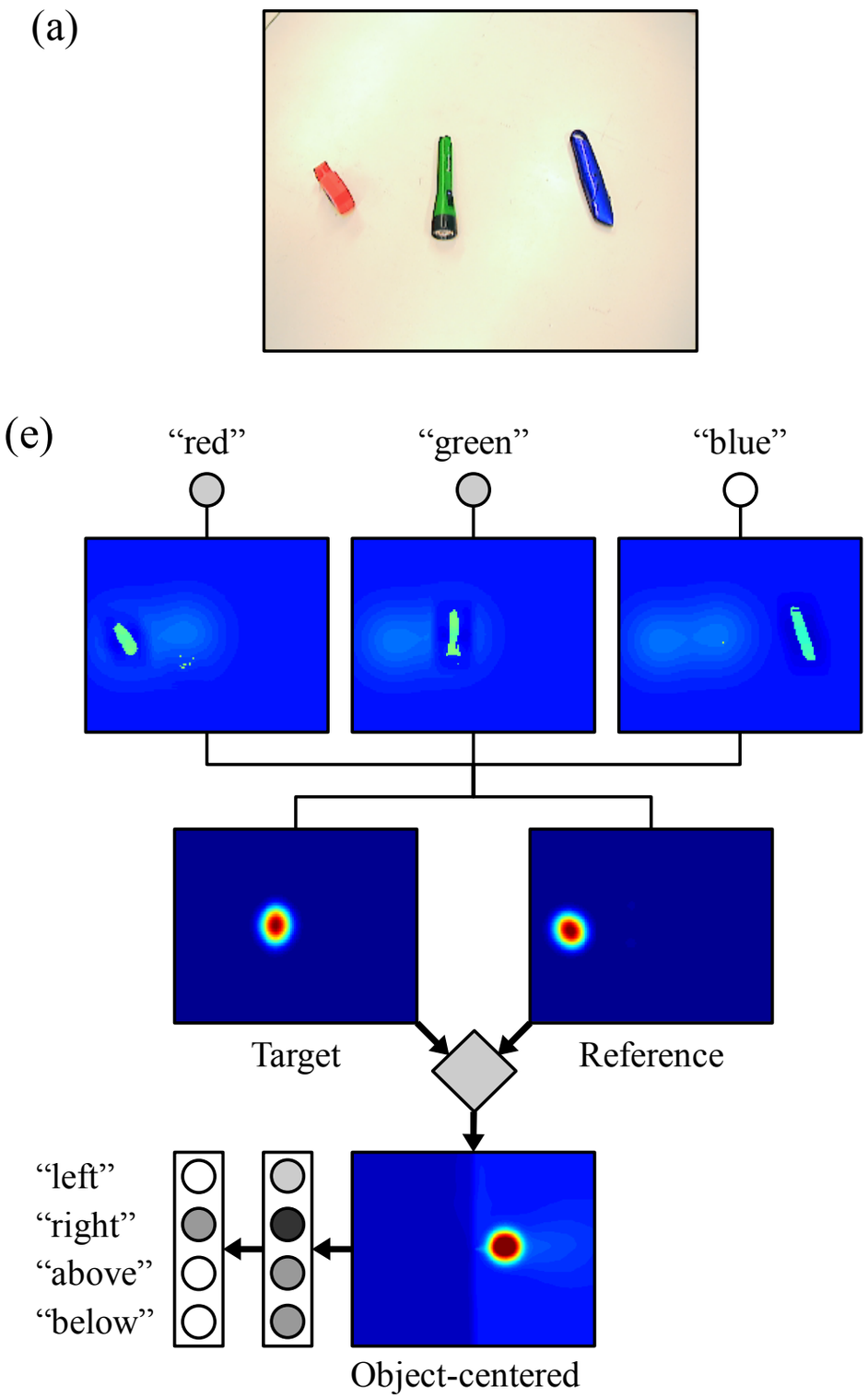
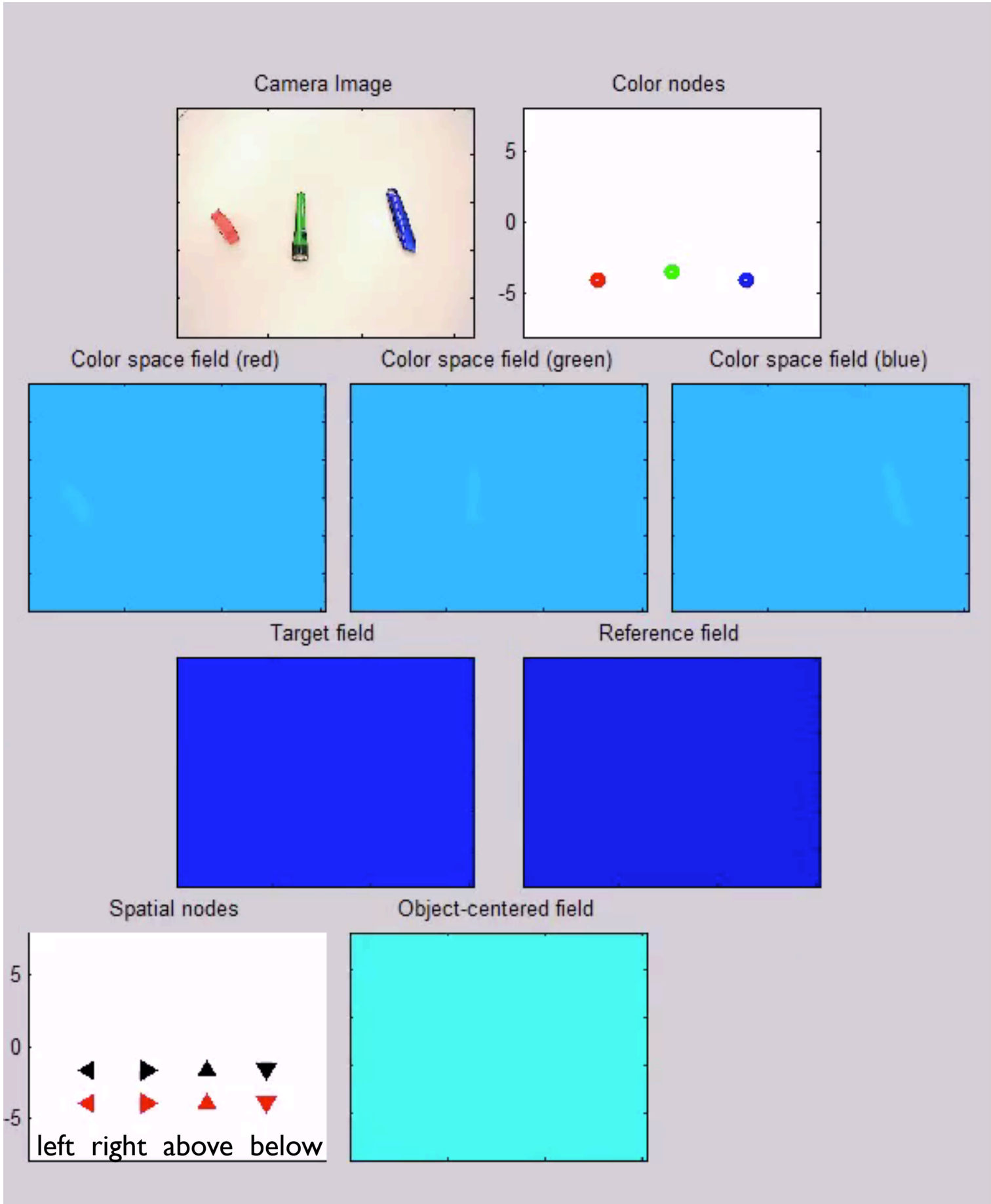


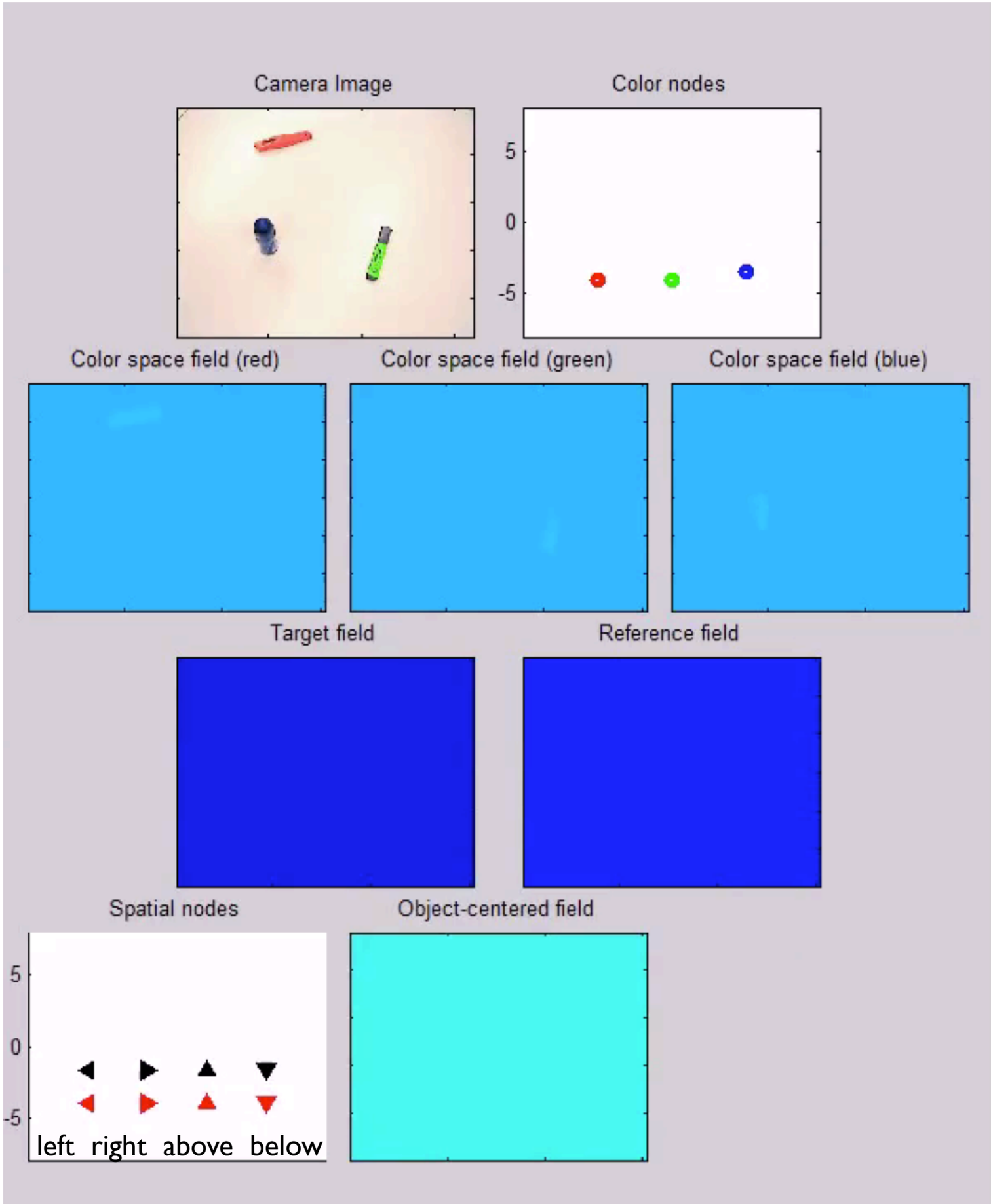
[Lipinski et al: JEP:LMC (2011)]

- "where is the green object relative to the red object?"



[Lipinski et al: JEP:LMC (2011)]

- "which object is above the blue object?"



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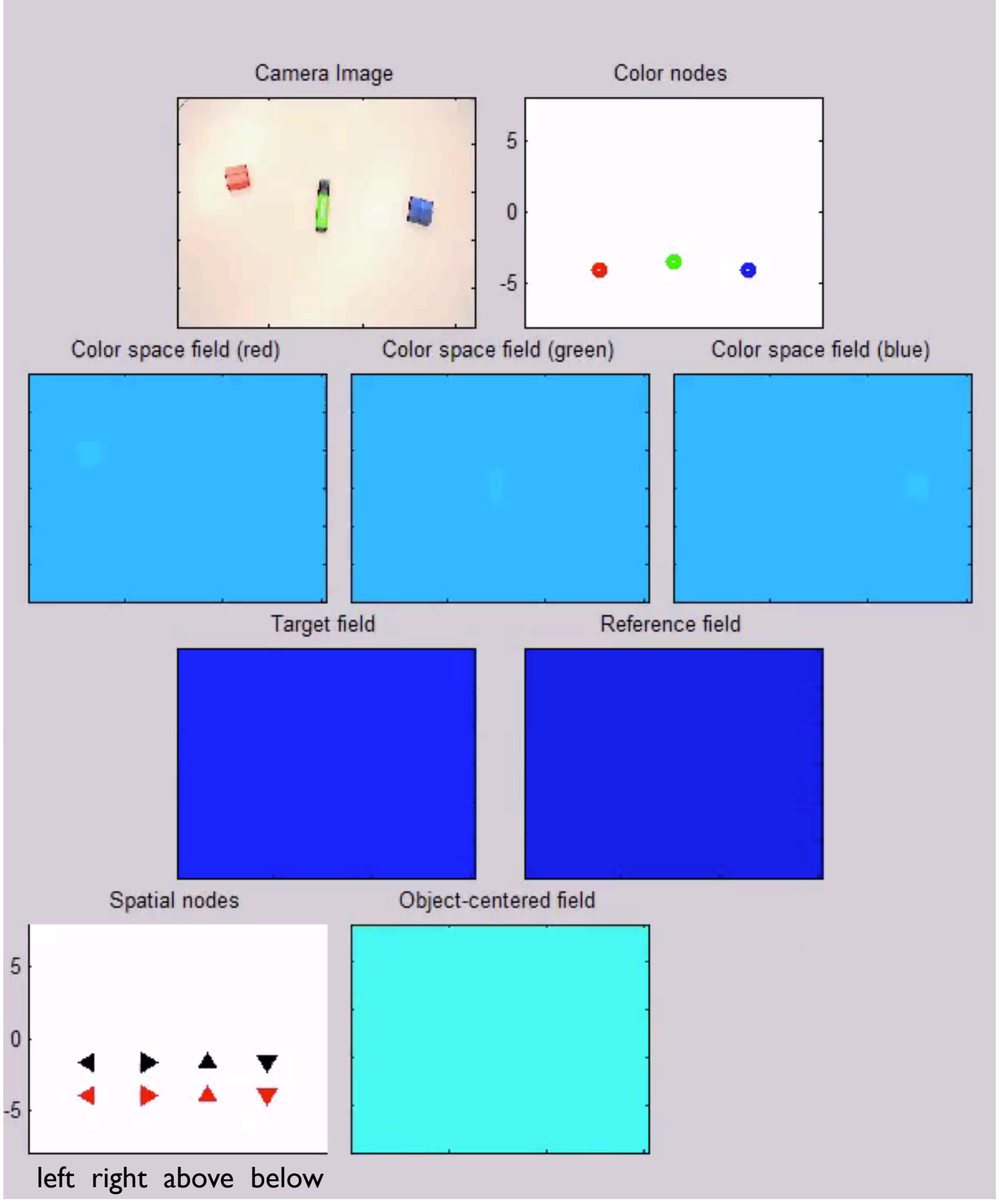

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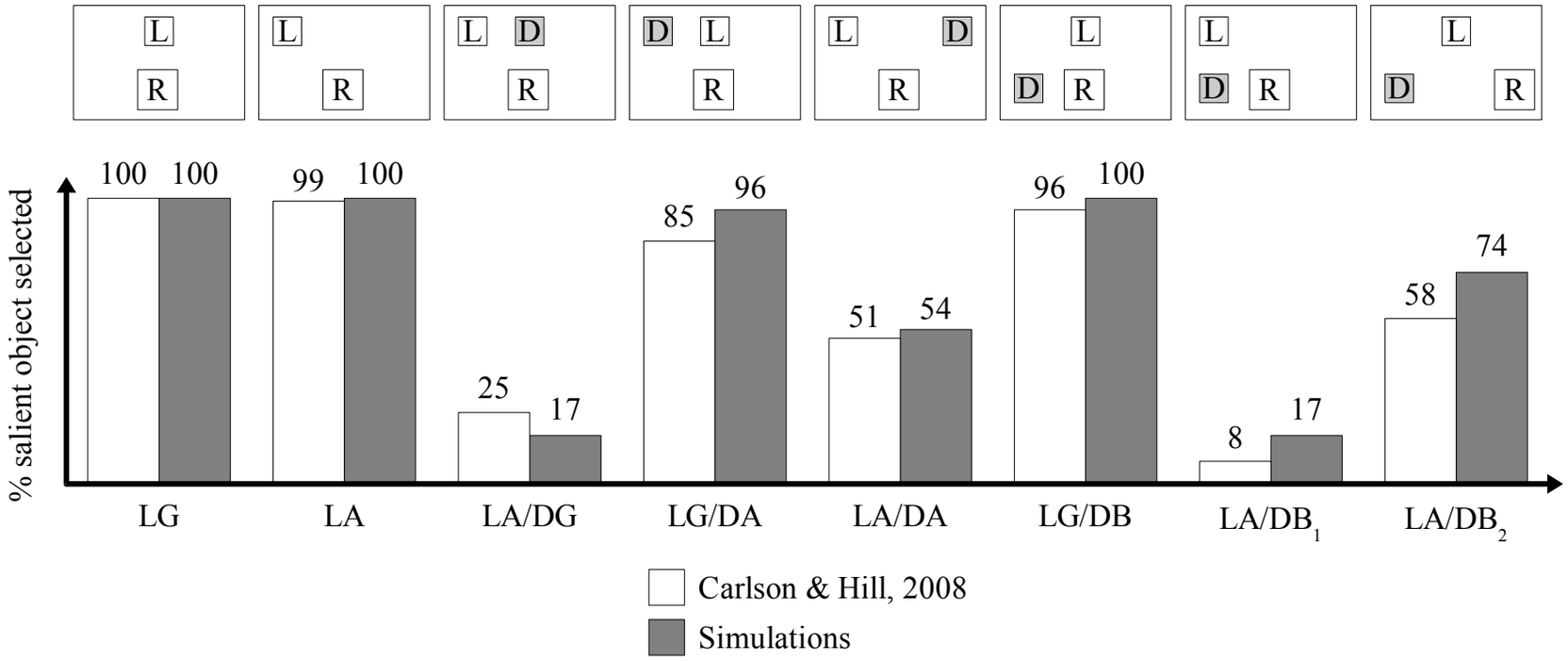
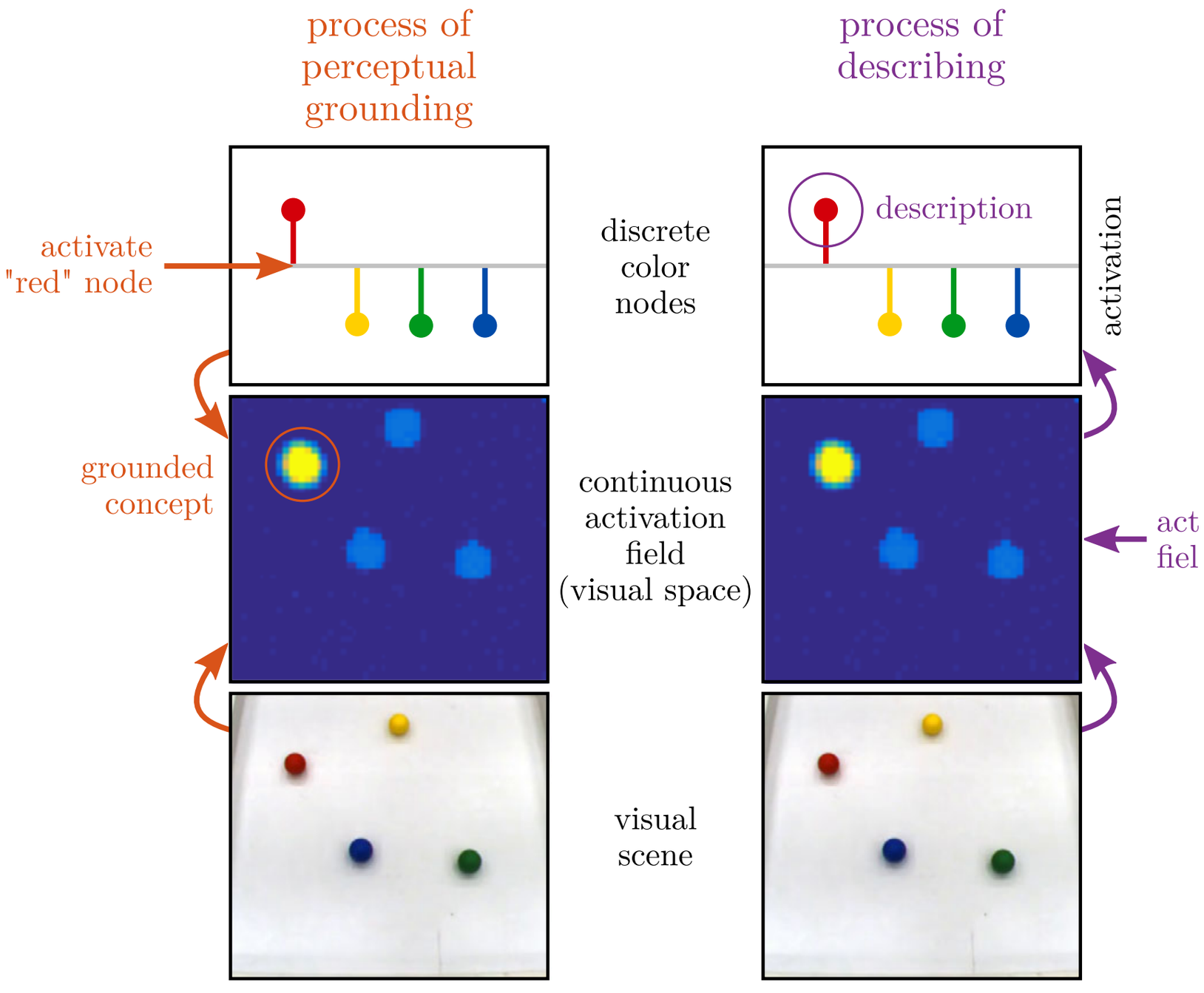
Spatial comparison in DFT

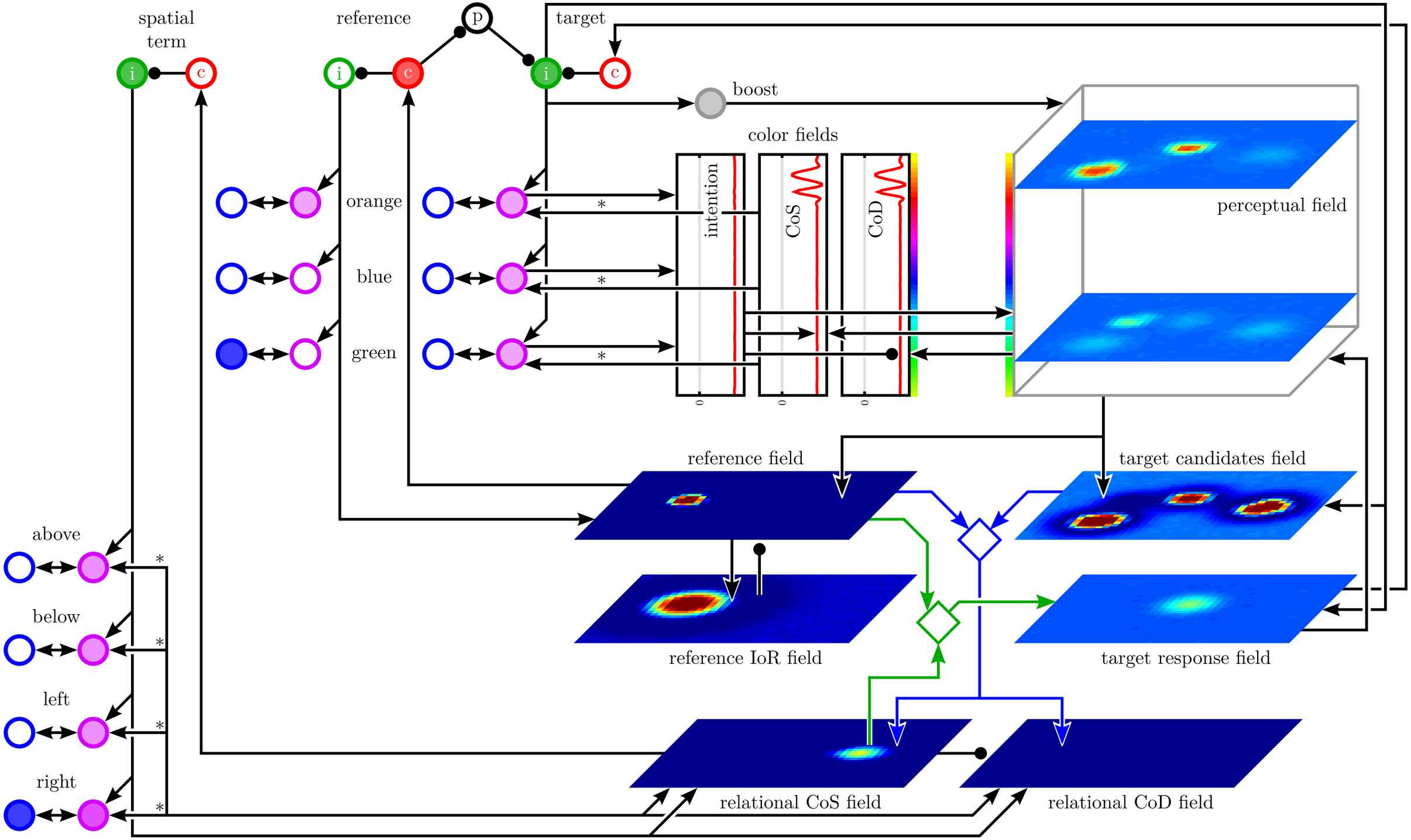
- accounts for human data



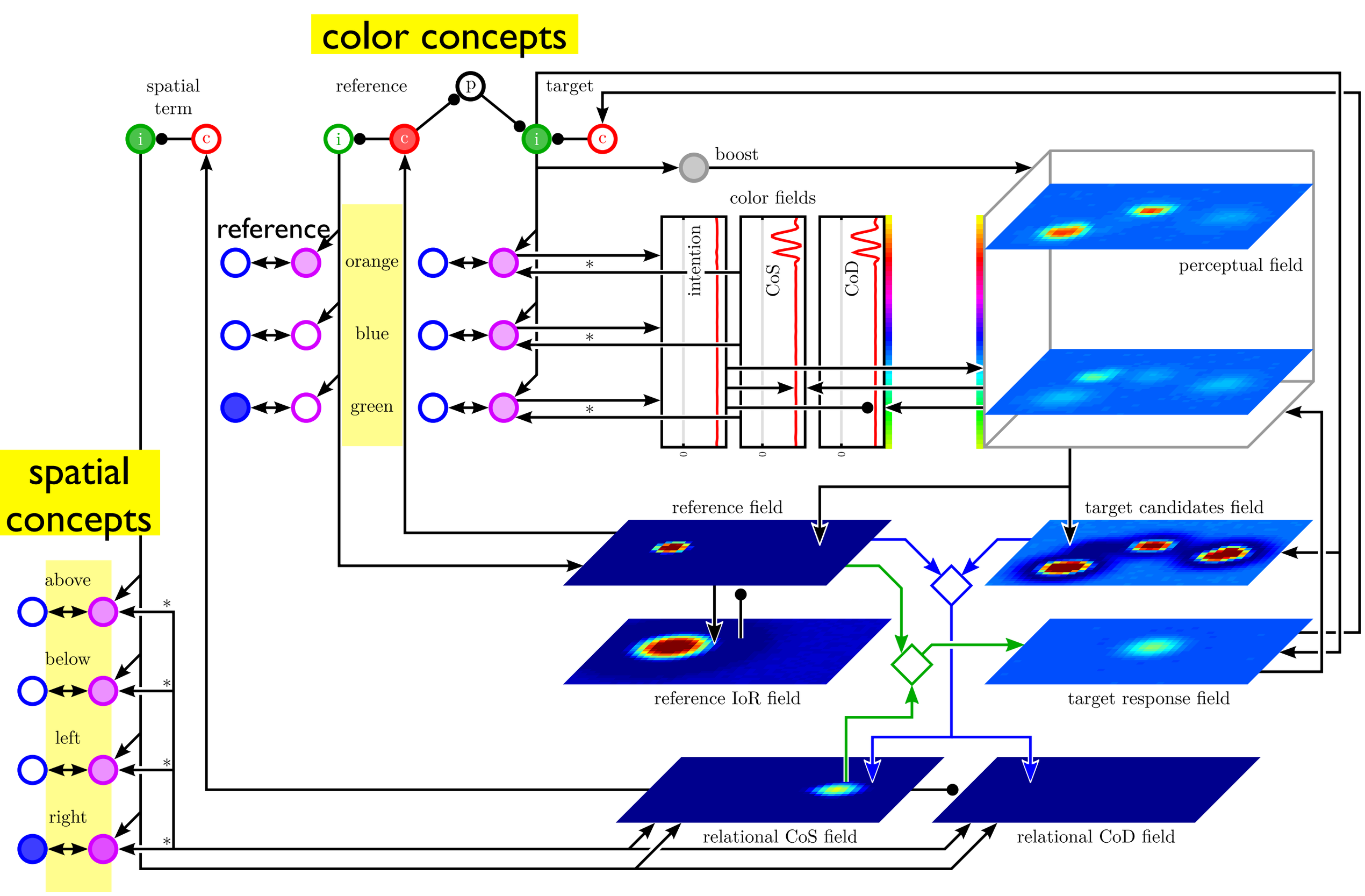
[Lipinski et al: JEP:LMC (2011)]

A DFT architecture that does both grounding and describing





[Richter, Lins et al. ICANN 2014]



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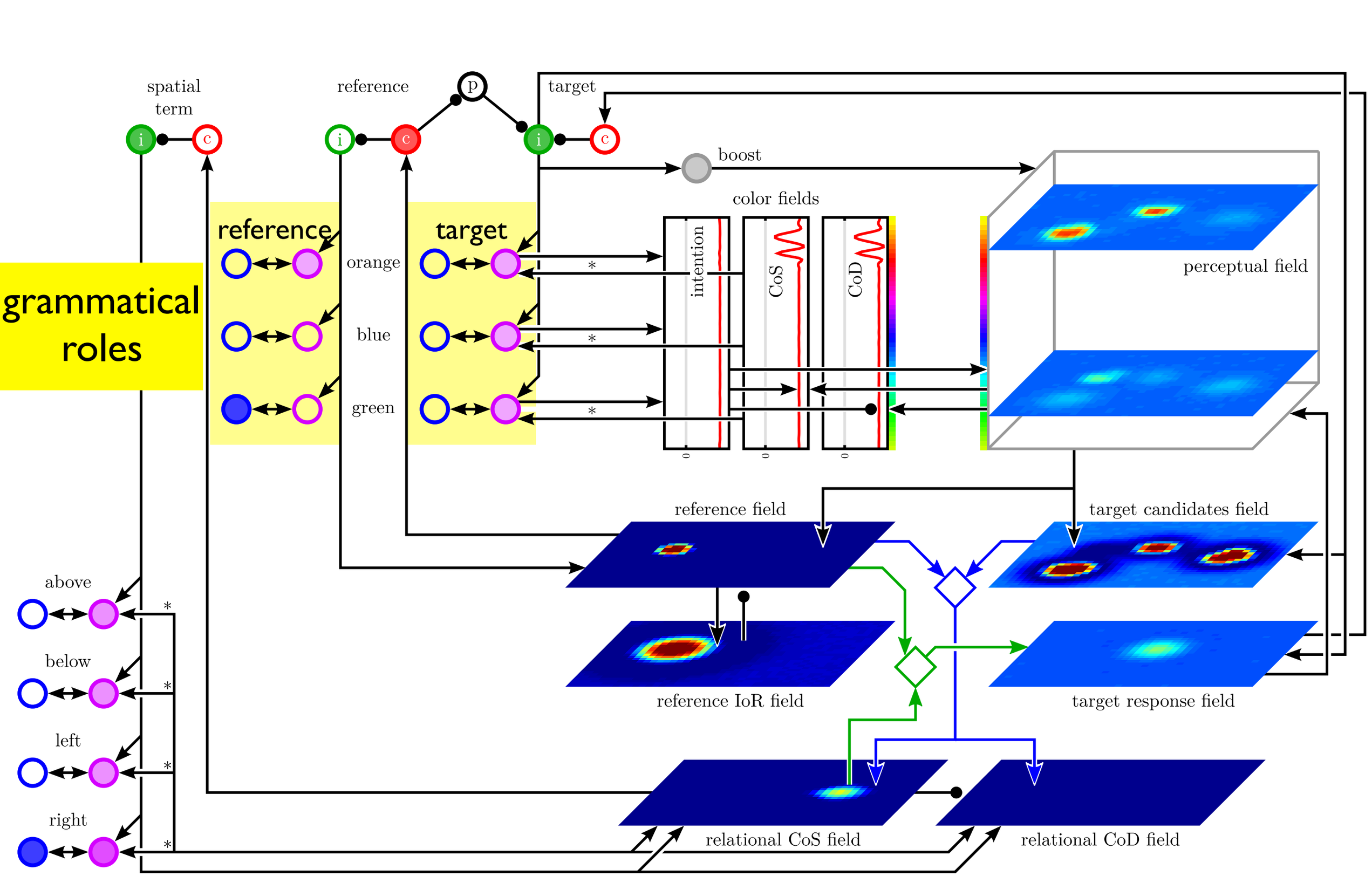

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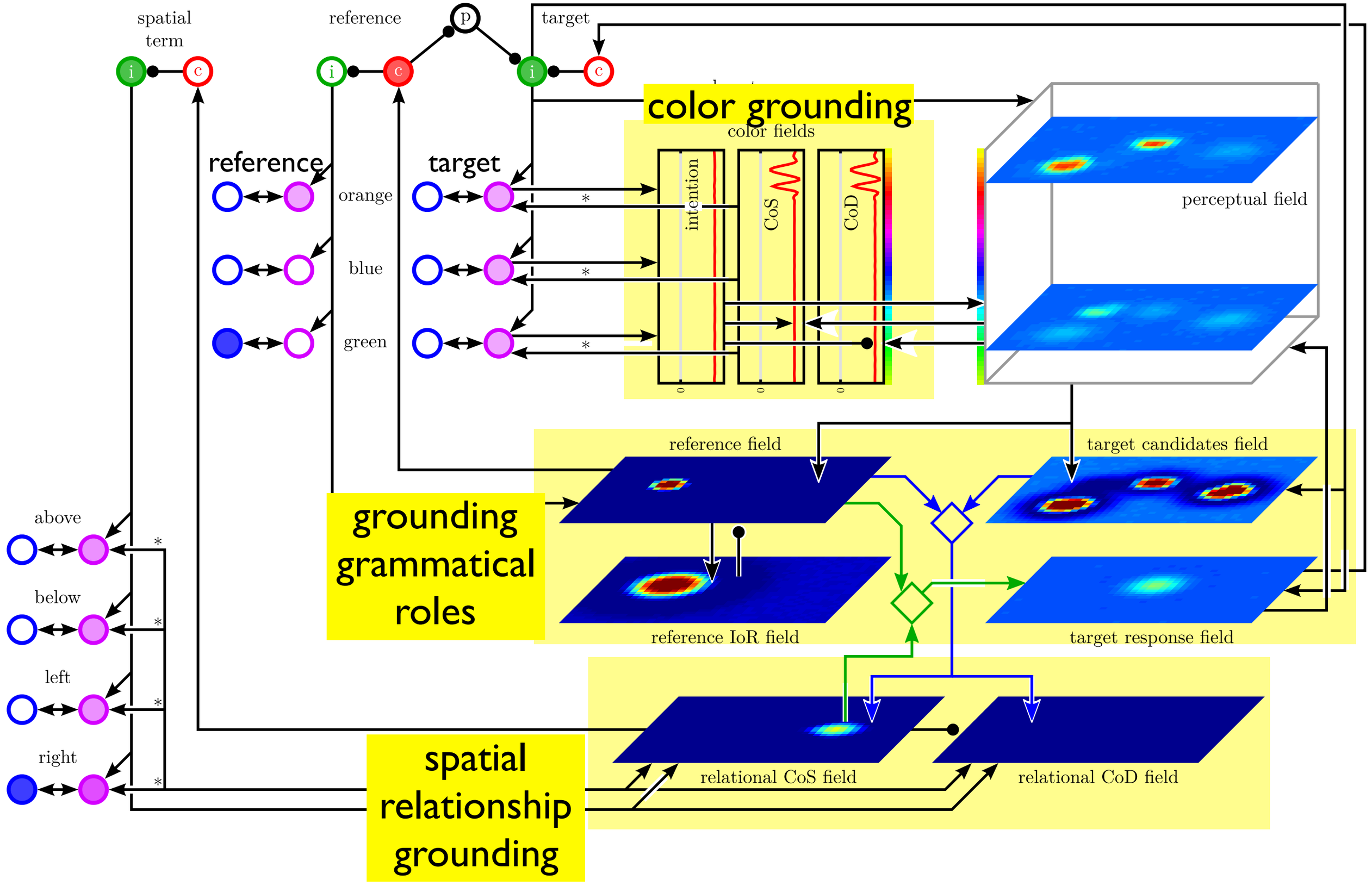

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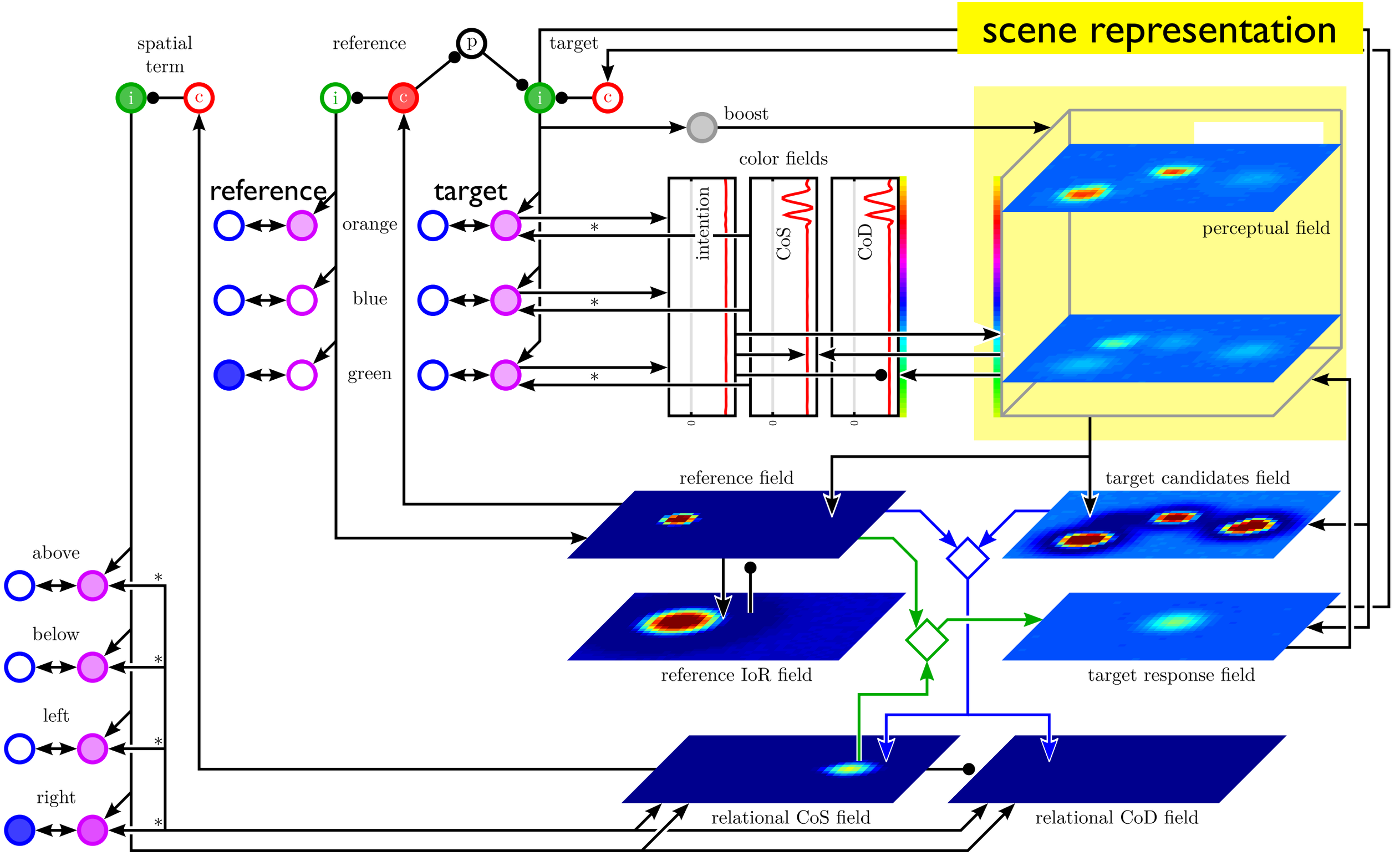
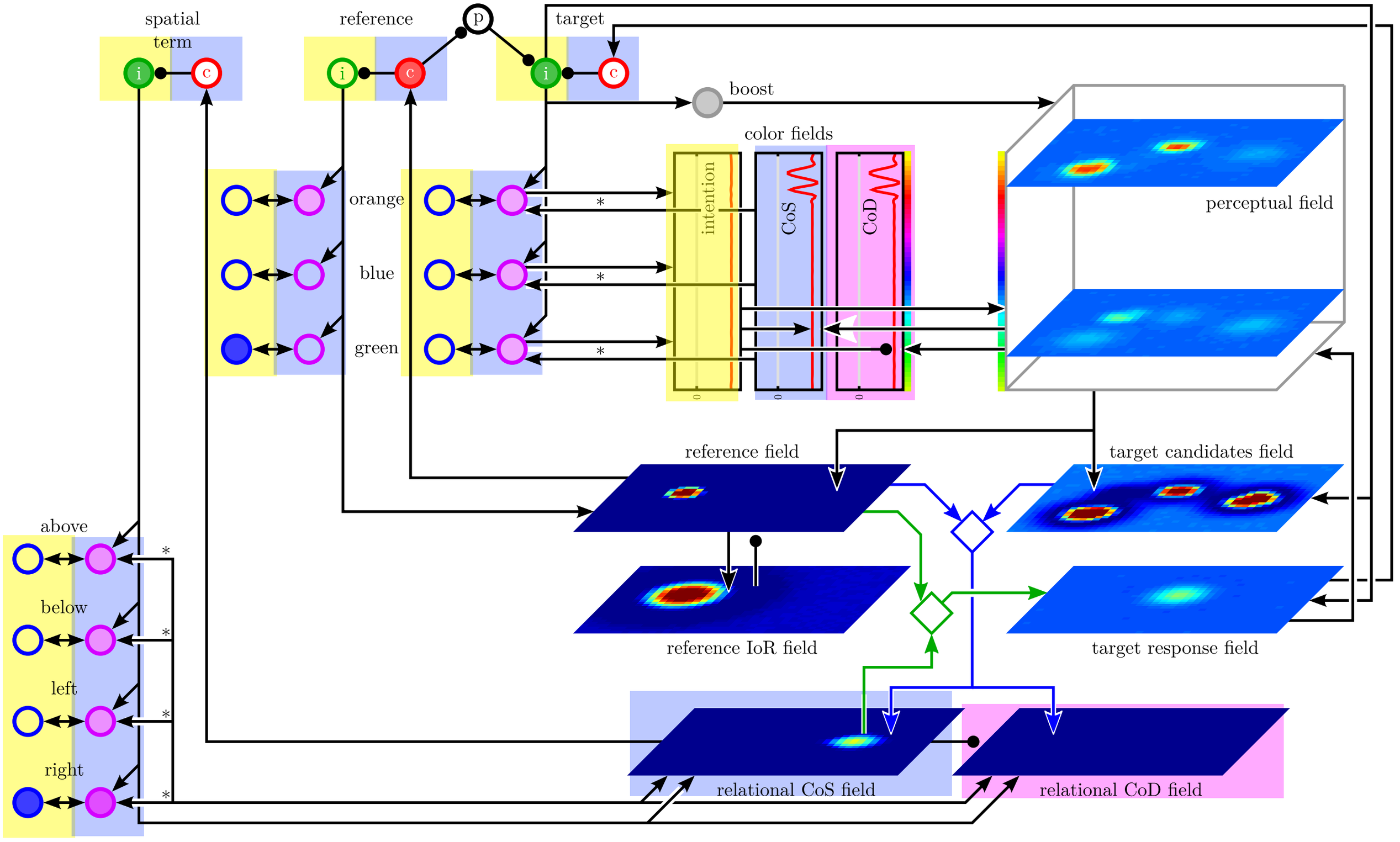


[Richter, Lins et al. ICANN 2014]

Intention

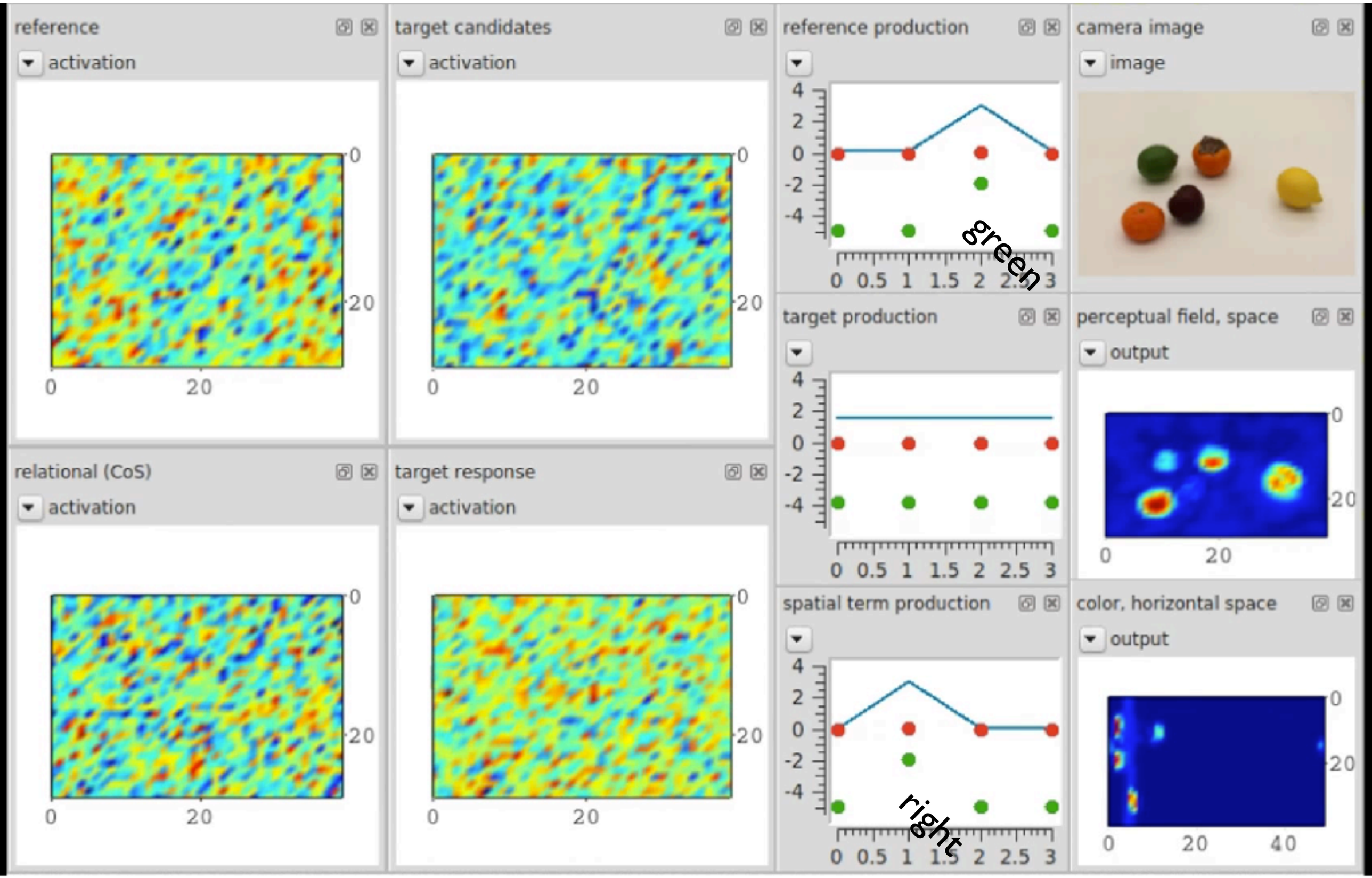
Condition of Satisfaction

Condition of Dissatisfaction

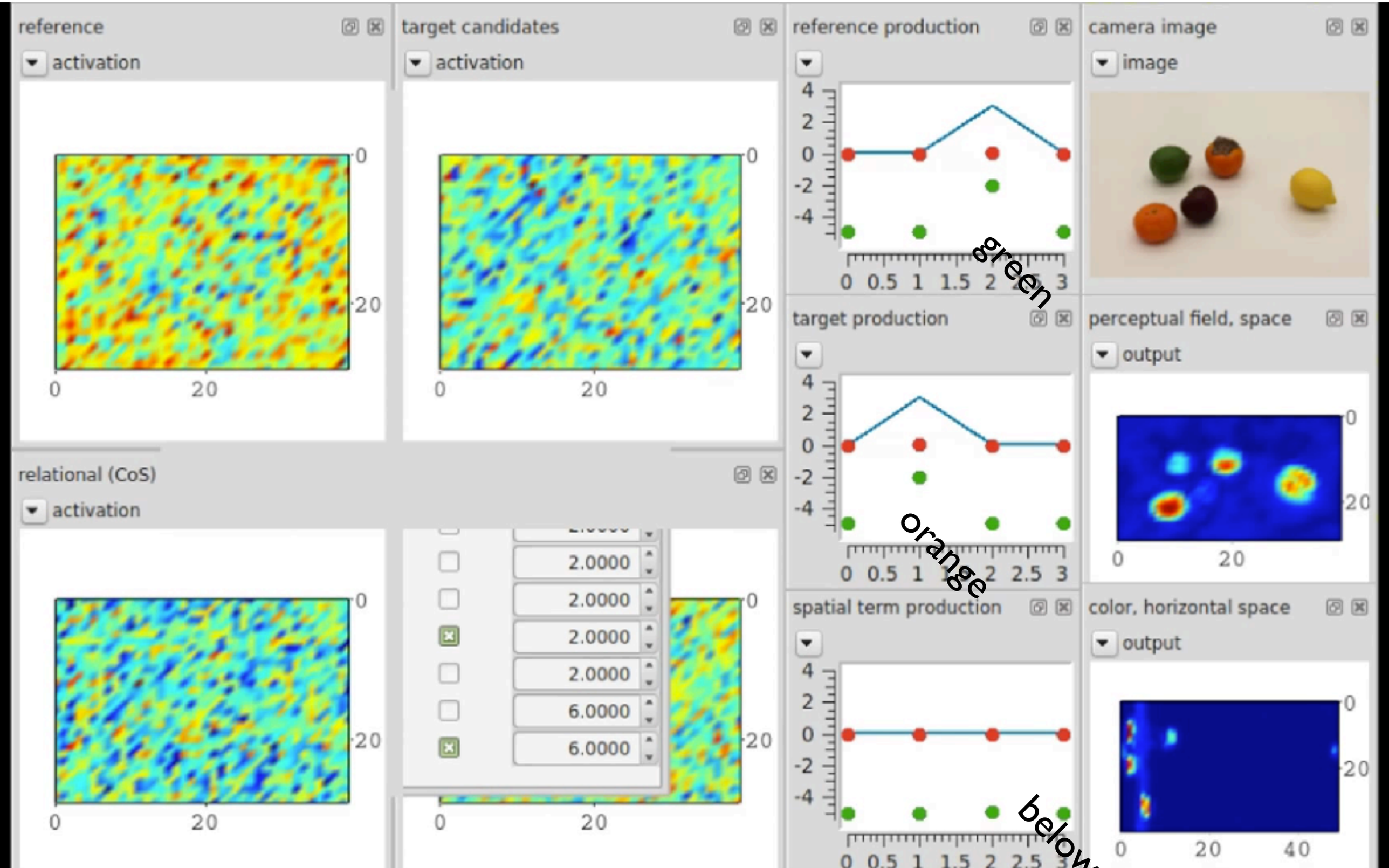


[Richter, Lins et al. ICANN 2014]

- what is to the right of the green object?



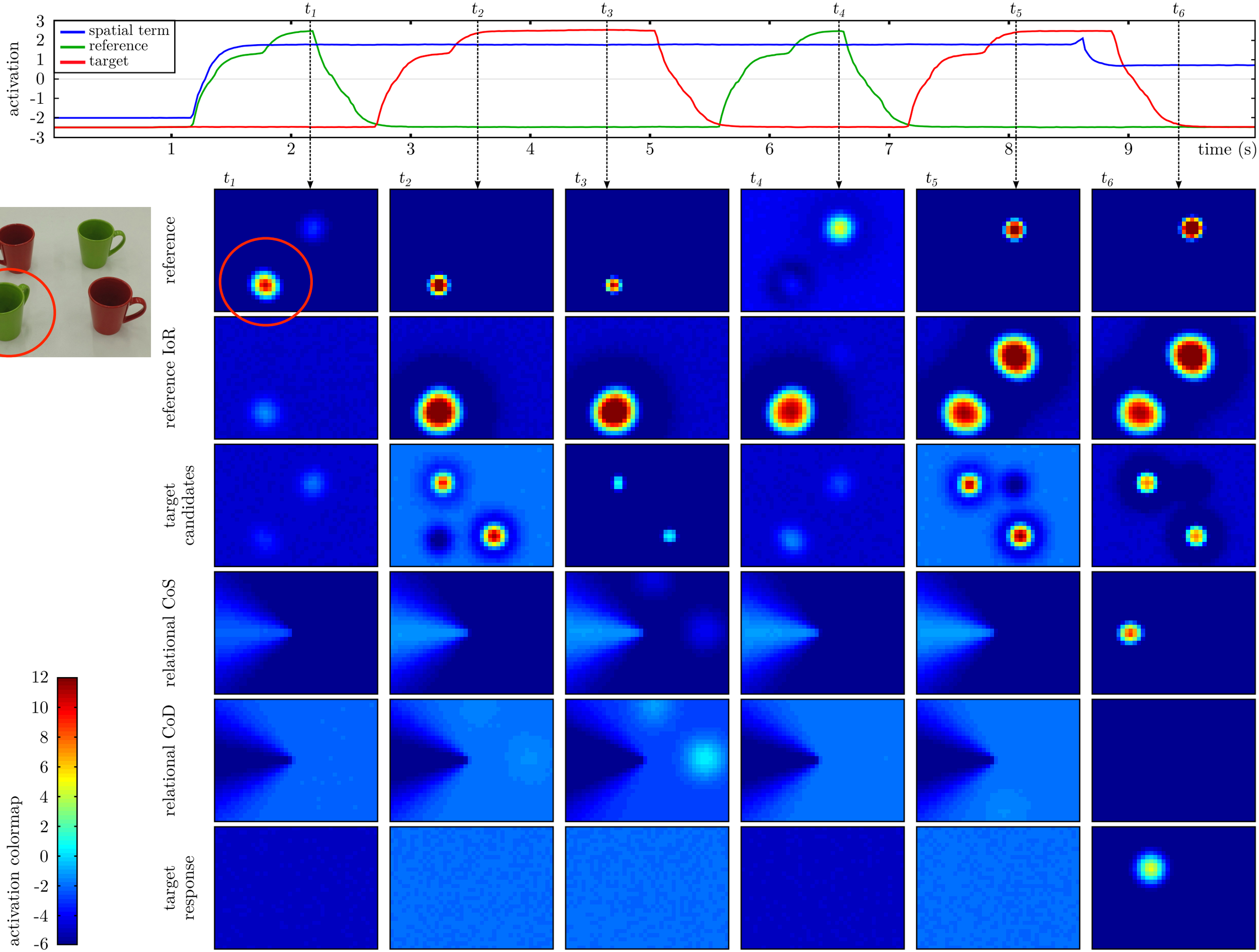
- where is the orange relative to the green object



Autonomous hypothesis testing

"the cup that is to the left of the green cup"

[Richter, Lins et al, CogSci 2014]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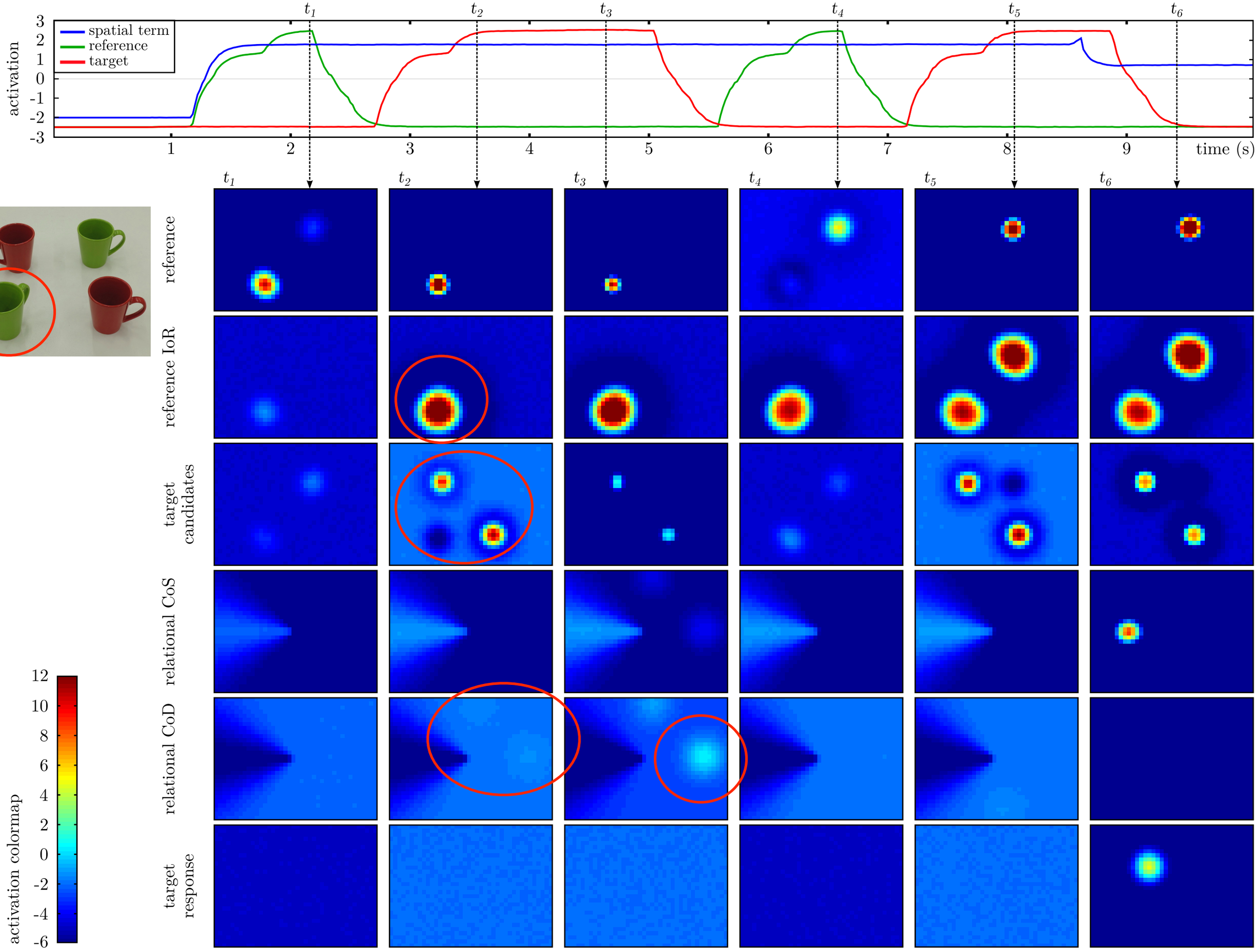
reference
target
time (s)
t_1
t_2
t_3
t_4
t_5
t_6
reference
reference IoR
target candidates
relational CoS
relational CoD
target response
activation colormap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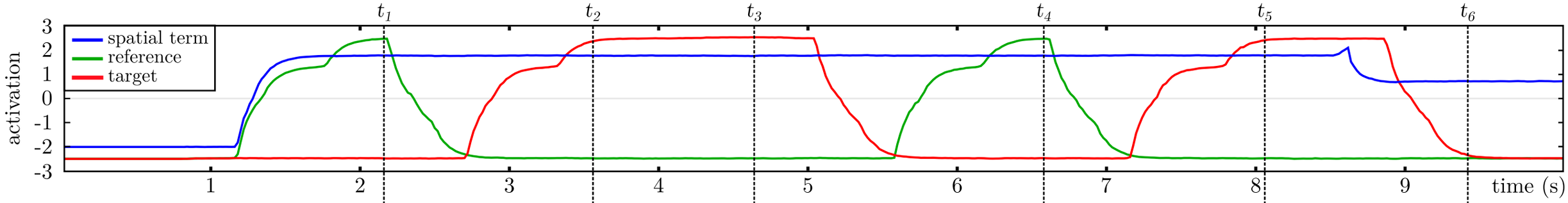
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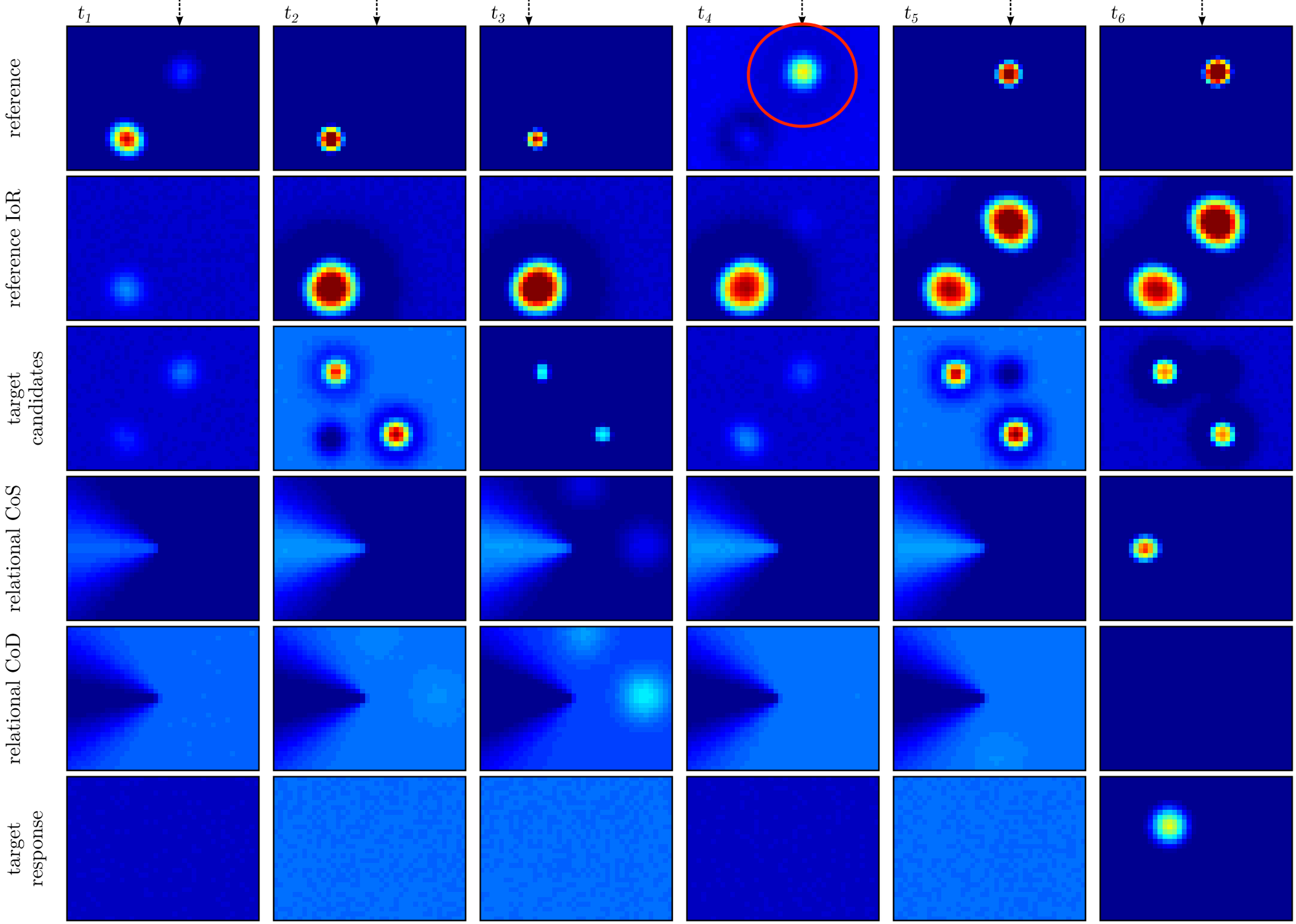
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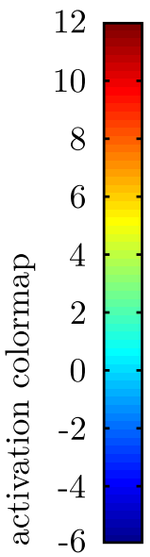
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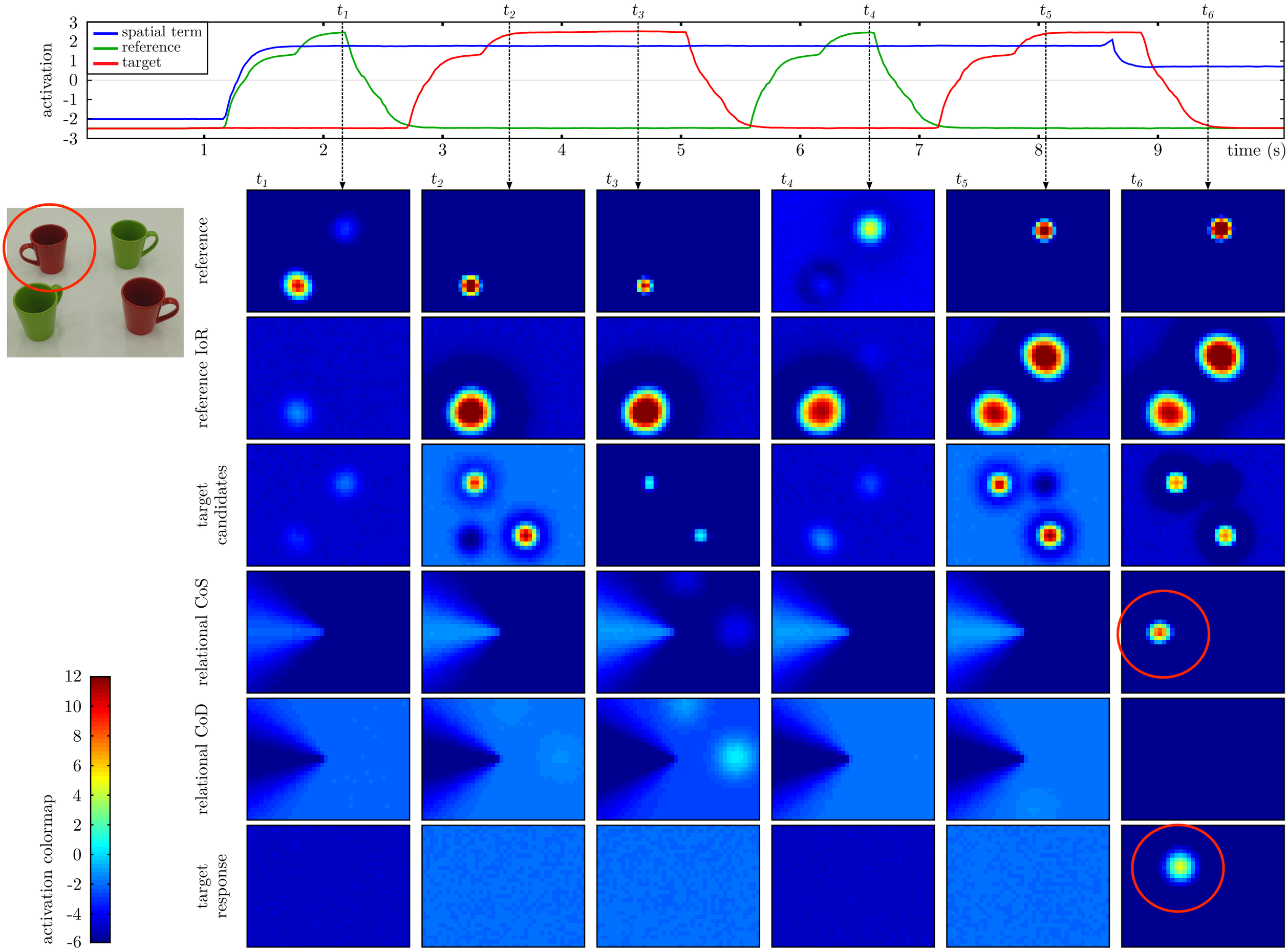
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"find red to the left of green"