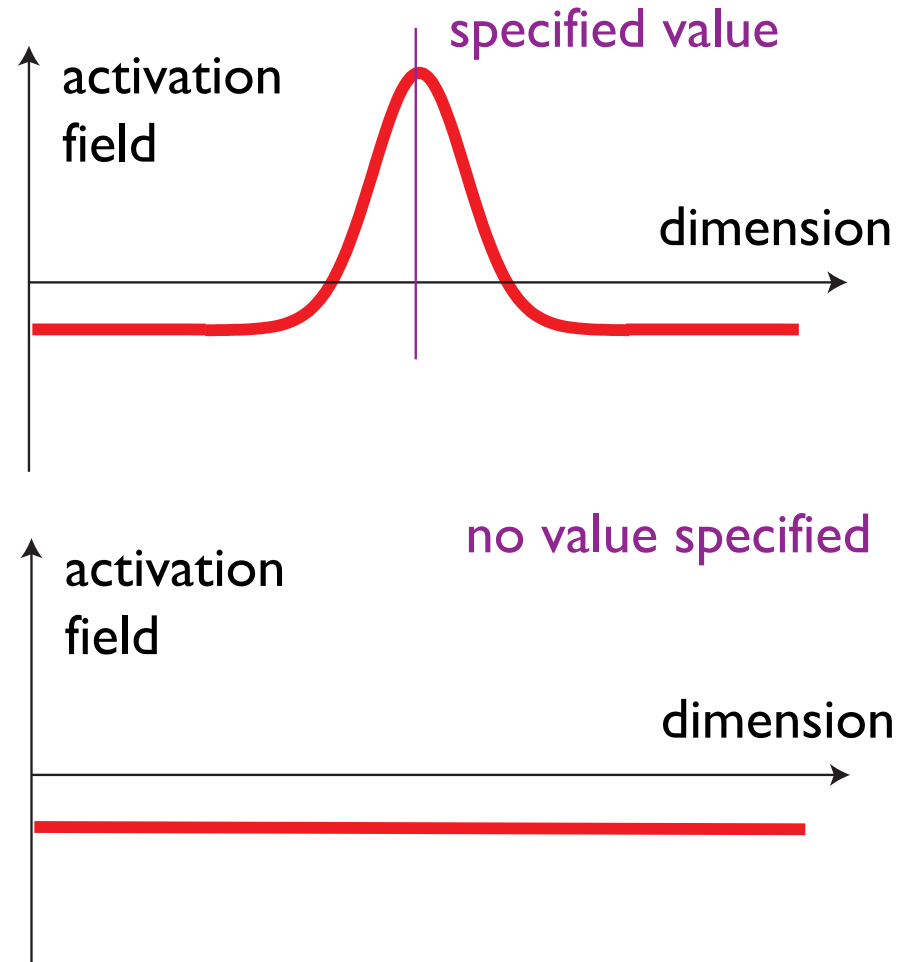
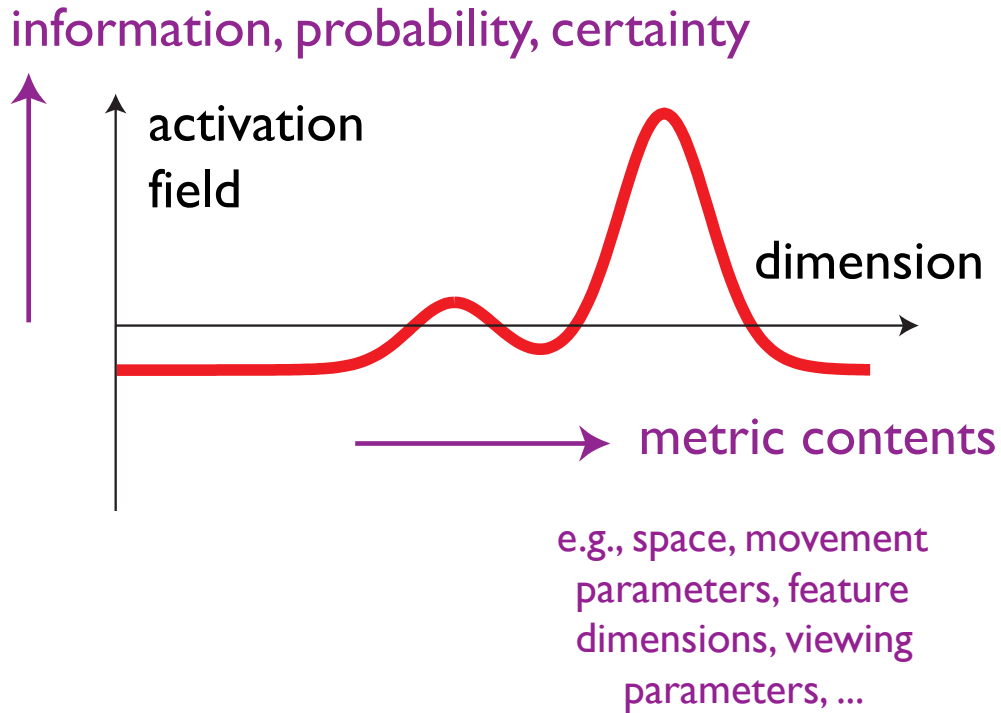


Dynamic Field Theory: Part 2: dynamics of activation fields

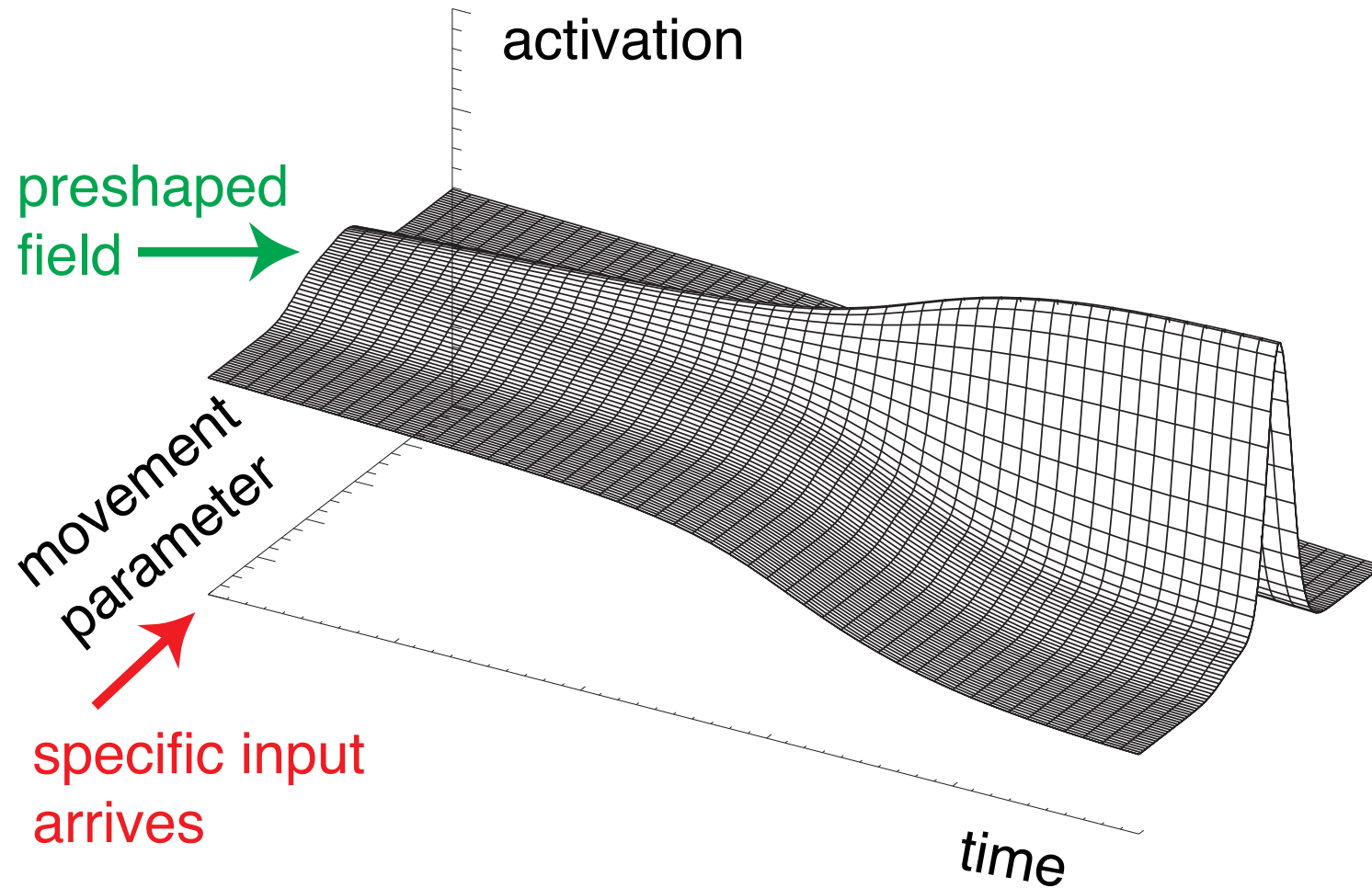
Raul Grieben

raul.grieben@ini.rub.de

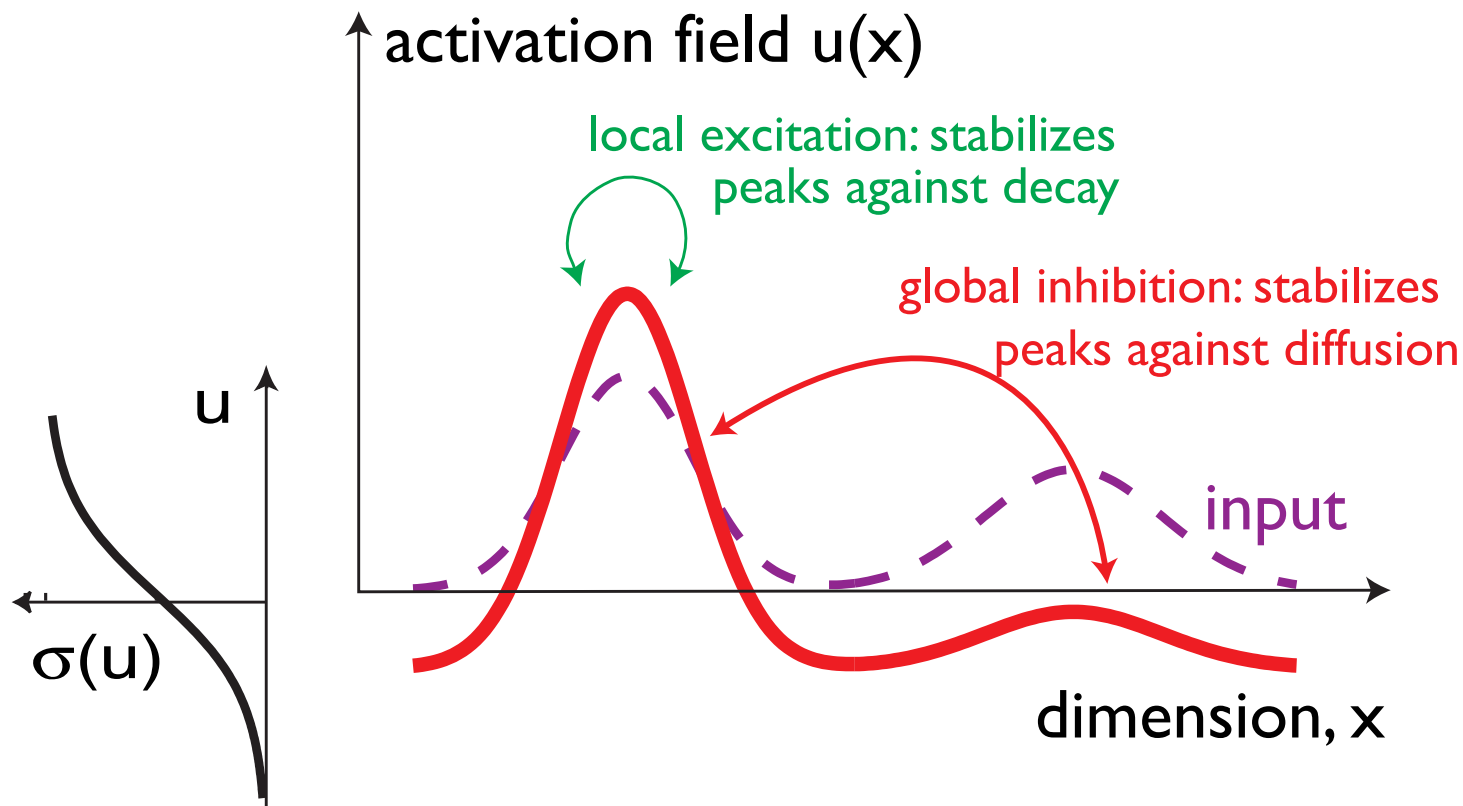
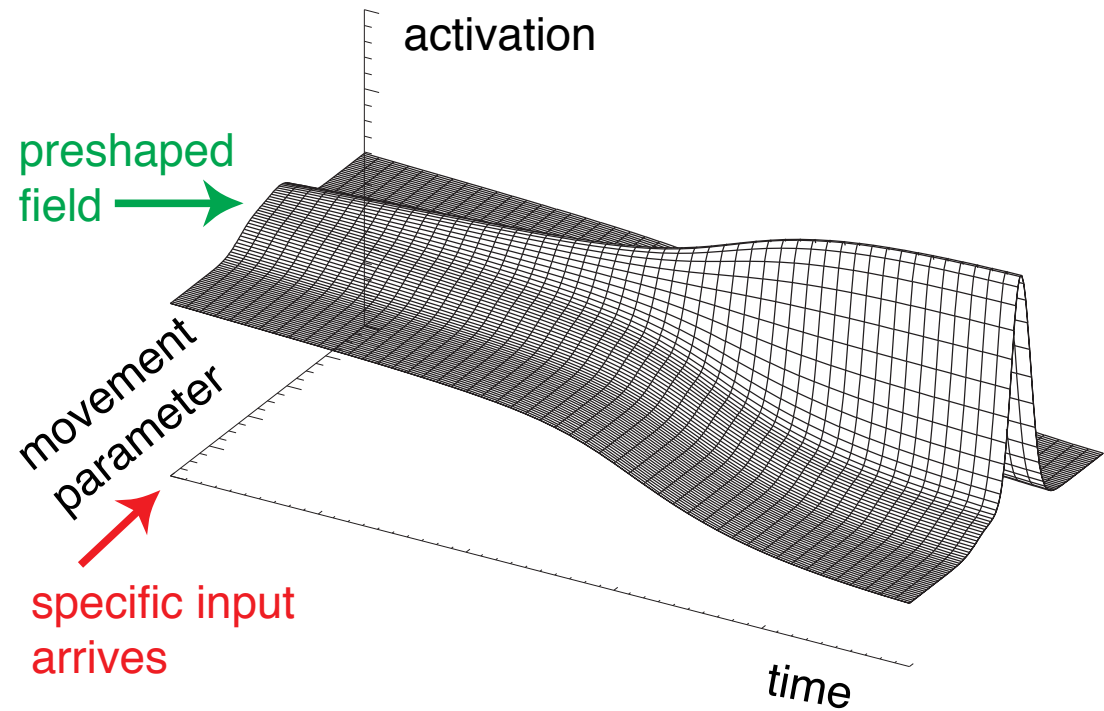
activation fields



evolution of activation fields in time: neuronal dynamics



the dynamics such activation fields is structured so that localized peaks emerge as attractor solutions



mathematical formalization

Amari equation

$$\tau \dot{u}(x, t) = -u(x, t) + h + S(x, t) + \int w(x - x') \sigma(u(x', t)) dx'$$

where

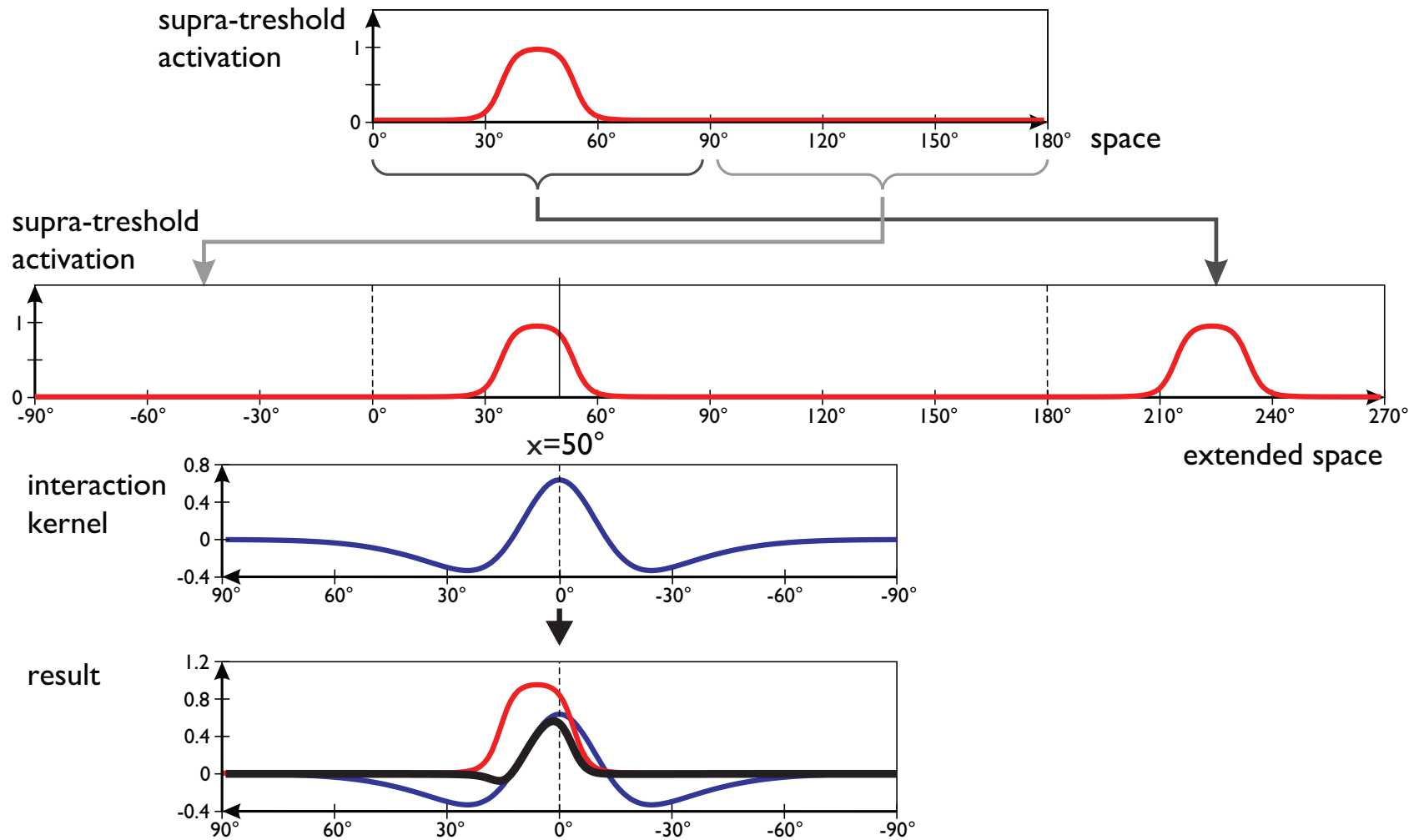
- time scale is τ
- resting level is $h < 0$
- input is $S(x, t)$
- interaction kernel is

$$w(x - x') = w_i + w_e \exp \left[-\frac{(x - x')^2}{2\sigma_i^2} \right]$$

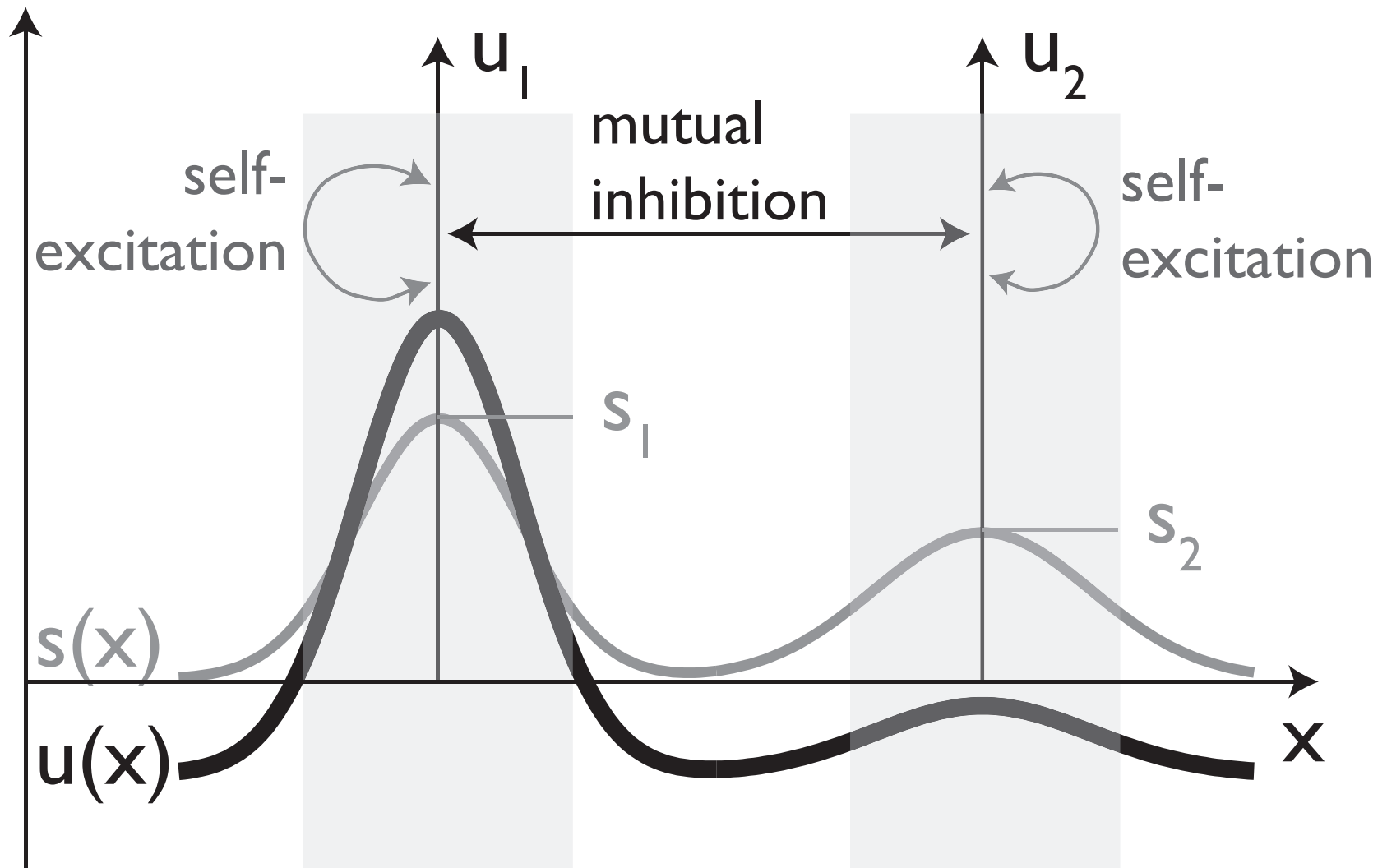
- sigmoidal nonlinearity is

$$\sigma(u) = \frac{1}{1 + \exp[-\beta(u - u_0)]}$$

Interaction: convolution



Relationship to the dynamics of discrete activation variables

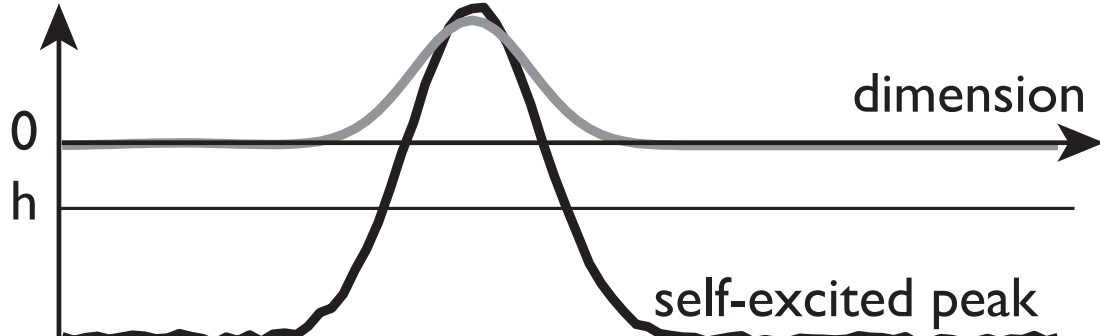
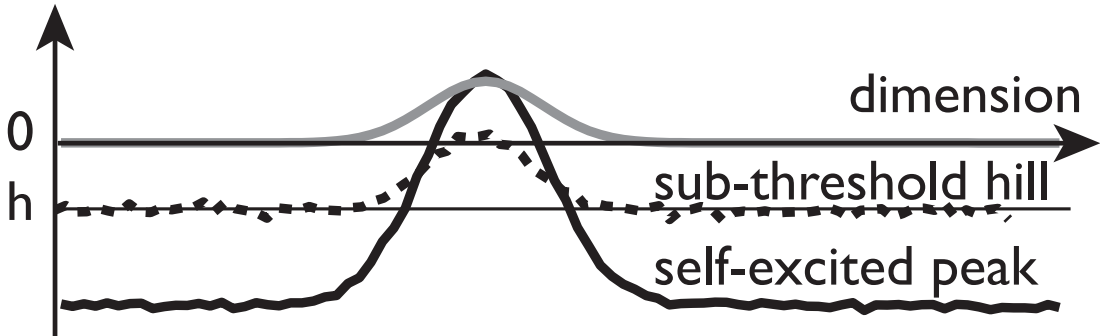
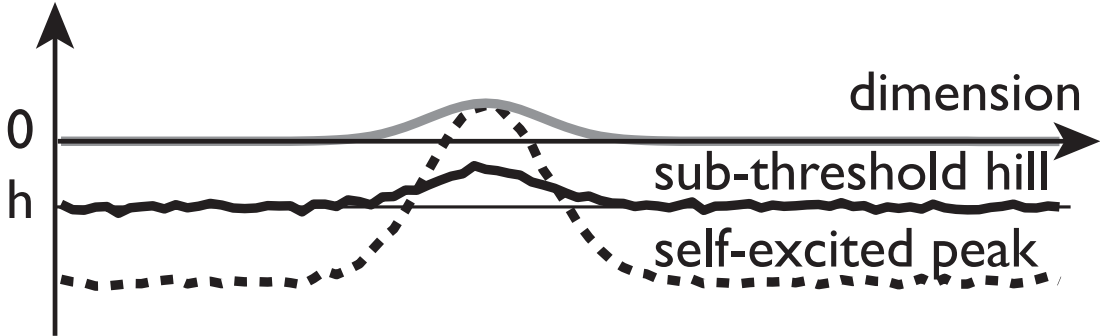
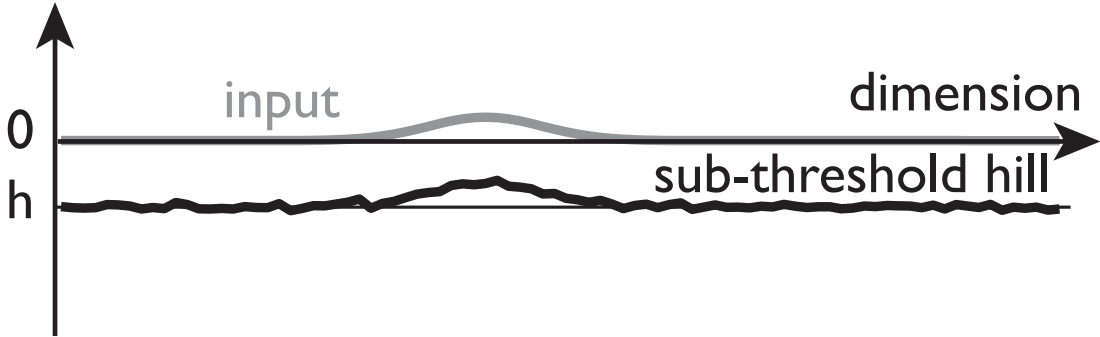


=> simulations

solutions and instabilities

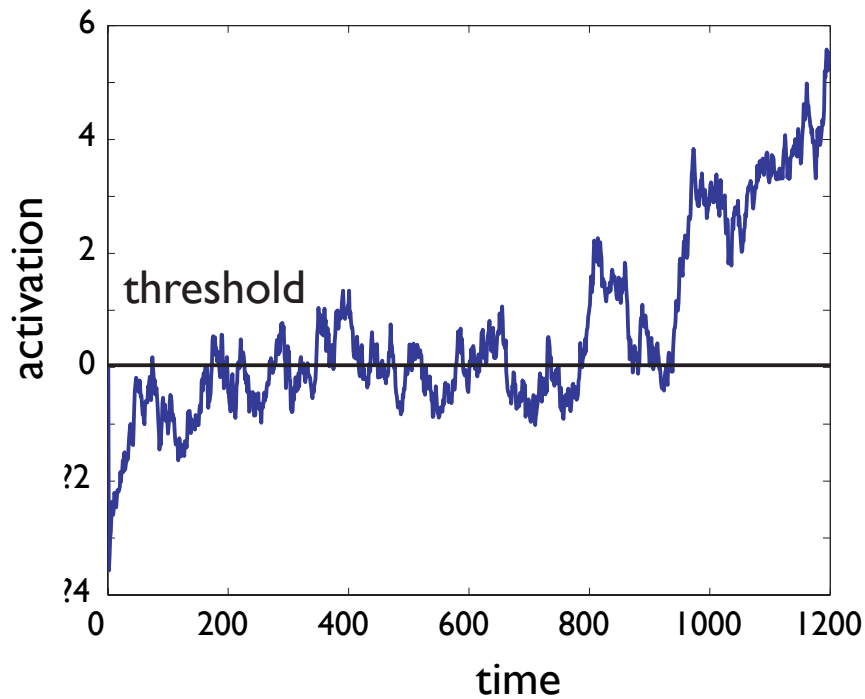
- input driven solution (sub-threshold) vs. self-stabilized solution (peak, supra-threshold)
- detection instability
- reverse detection instability
- selection
- selection instability
- memory instability
- detection instability from boost

Detection instability

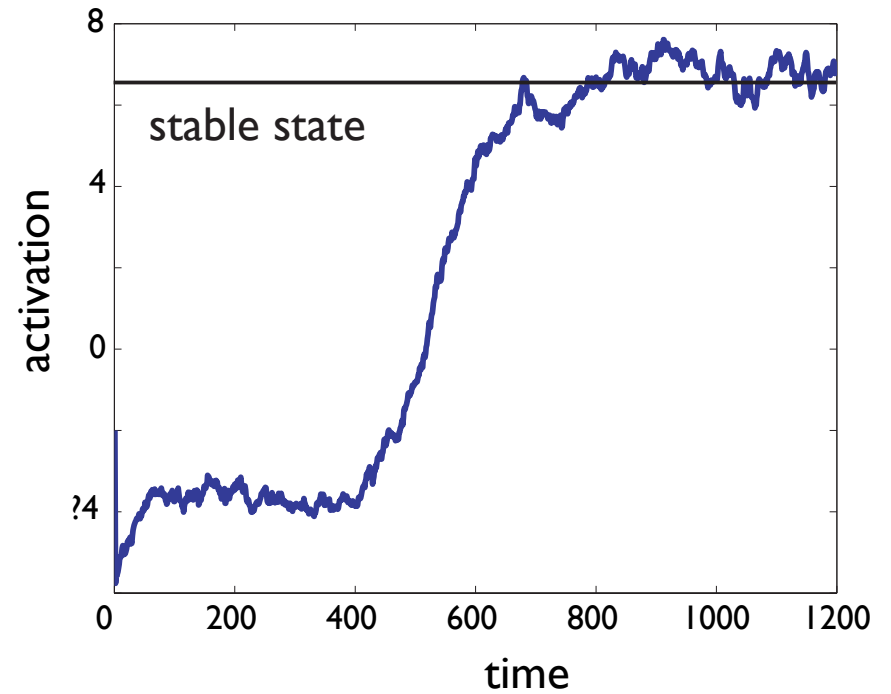


the detection instability helps stabilize decisions

threshold piercing



detection instability



the detection instability helps stabilize decisions

- self-stabilized peaks are macroscopic neuronal states, capable of impacting on down-stream neuronal systems
- (unlike the microscopic neuronal activation that just exceeds a threshold)

emergence of time-discrete events

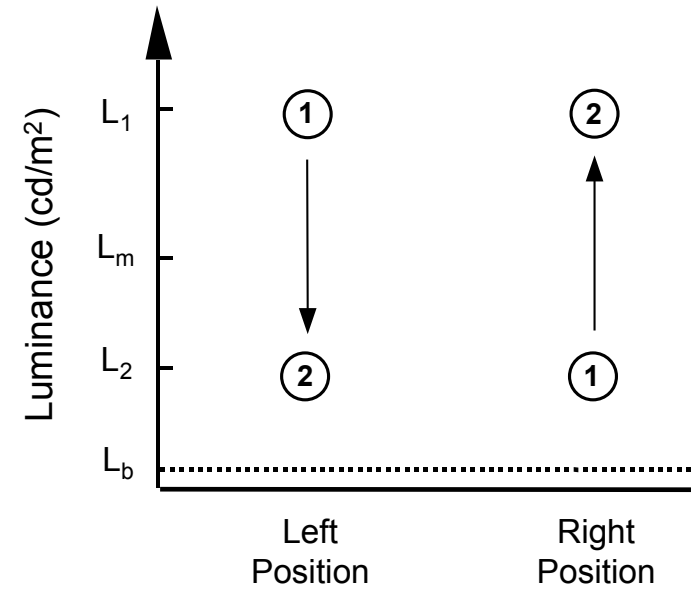
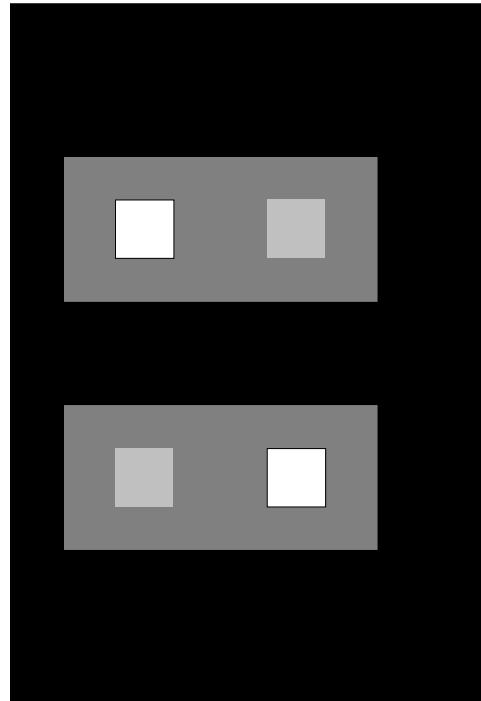
- the detection instability also explains how a time-continuous neuronal dynamics may create macroscopic, time-discrete events

behavioral signatures of detection decisions

- detection in psychophysical paradigms is rife with hysteresis
- but: minimize response bias

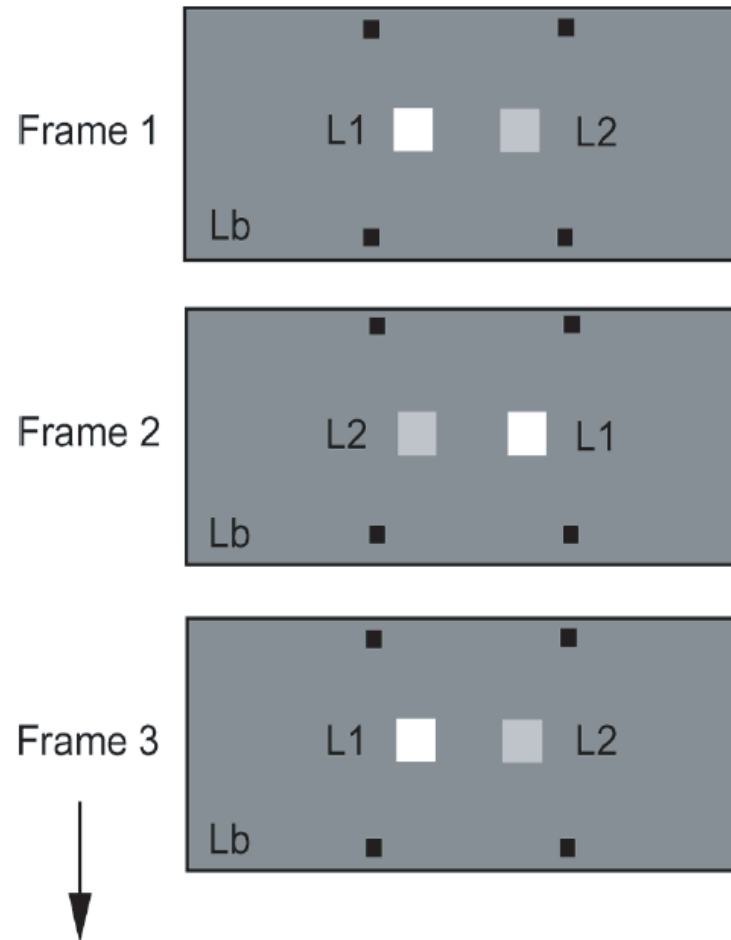
Detection instability

■ in the detection of Generalized Apparent Motion



Detection instability

 varying
BRLC



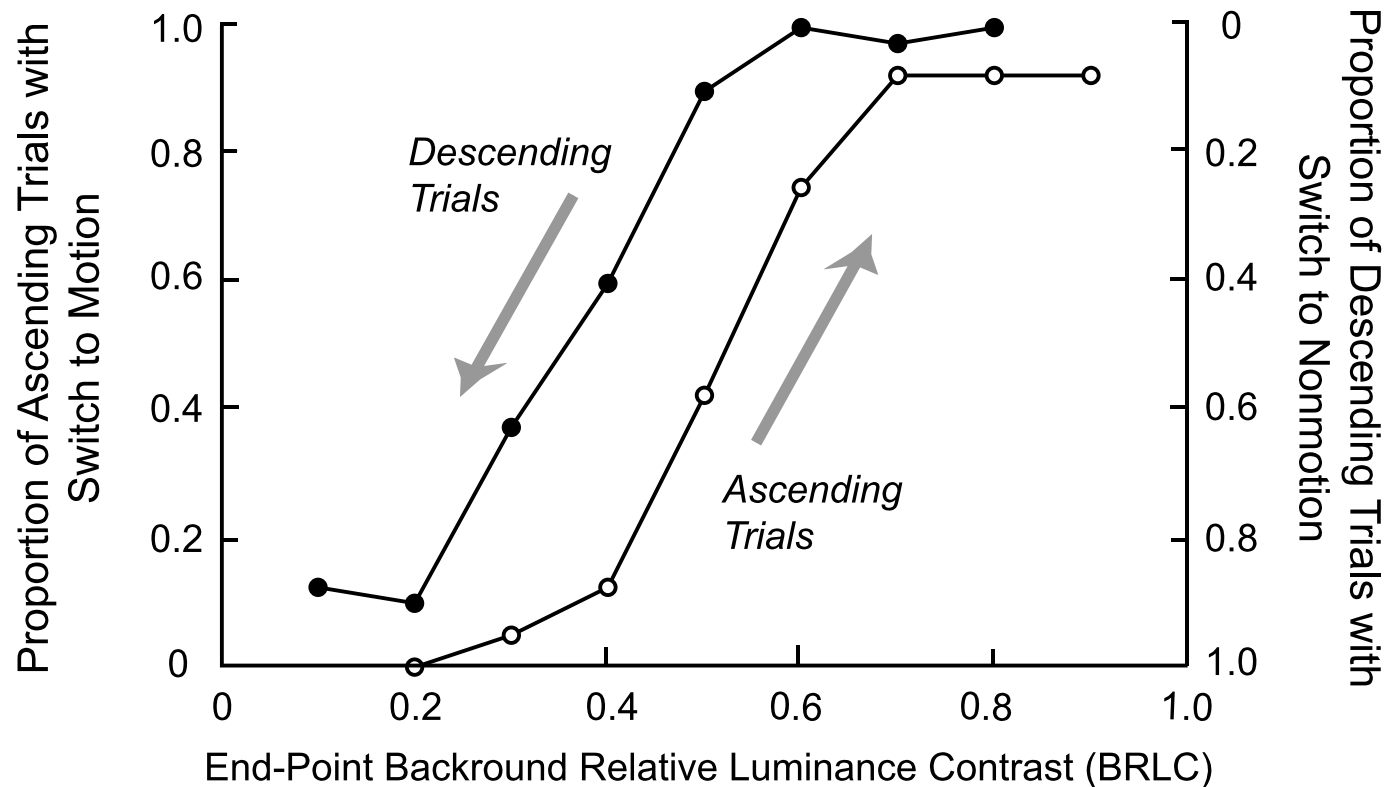
$$L_m = \frac{L_1 + L_2}{2}$$

$$\text{Background-Relative Luminance Change (BRLC)} = \frac{L_1 - L_2}{L_m - L_b}$$

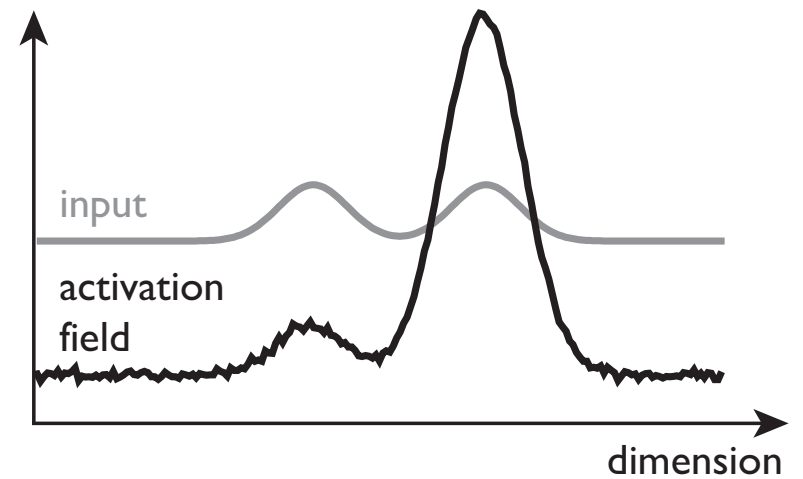
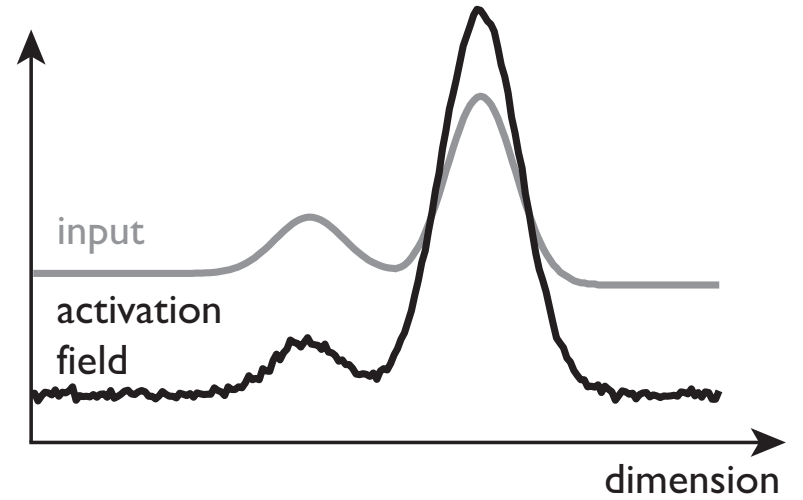
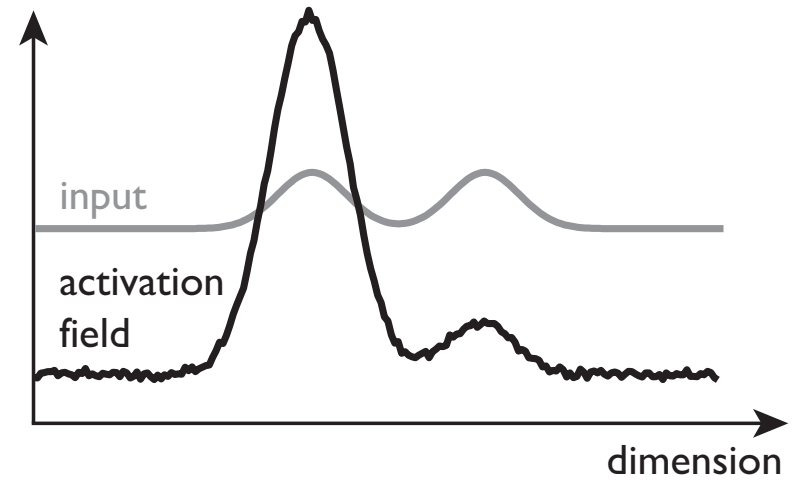
Detection instability

- hysteresis of motion detection as BRLC is varied
- (while response bias is minimized)

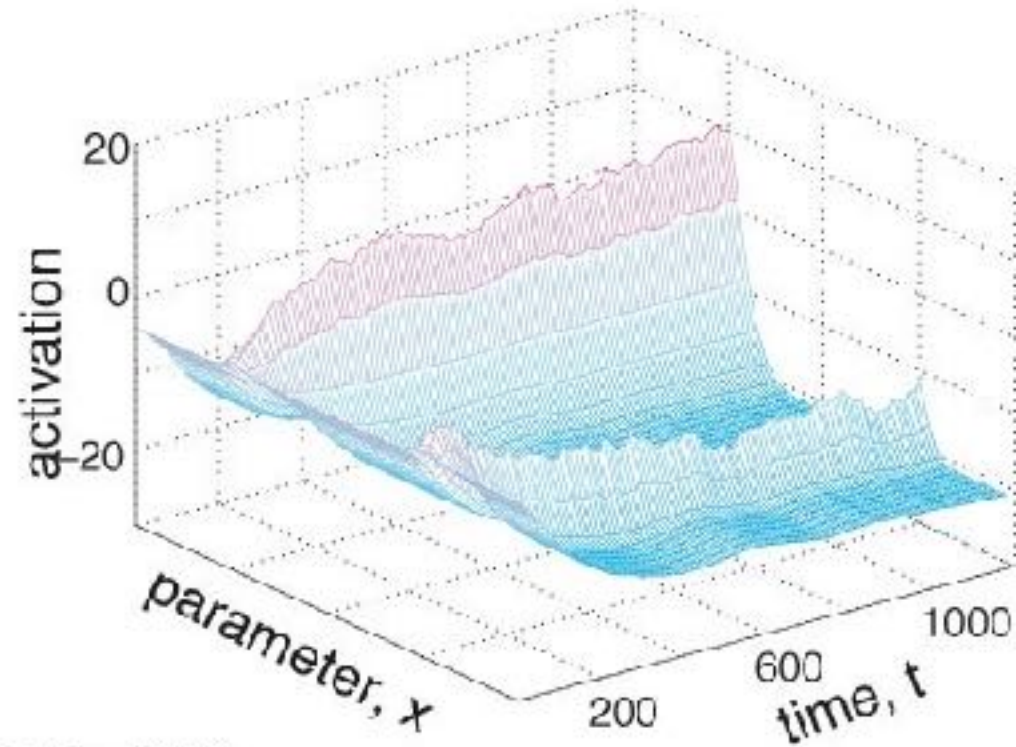
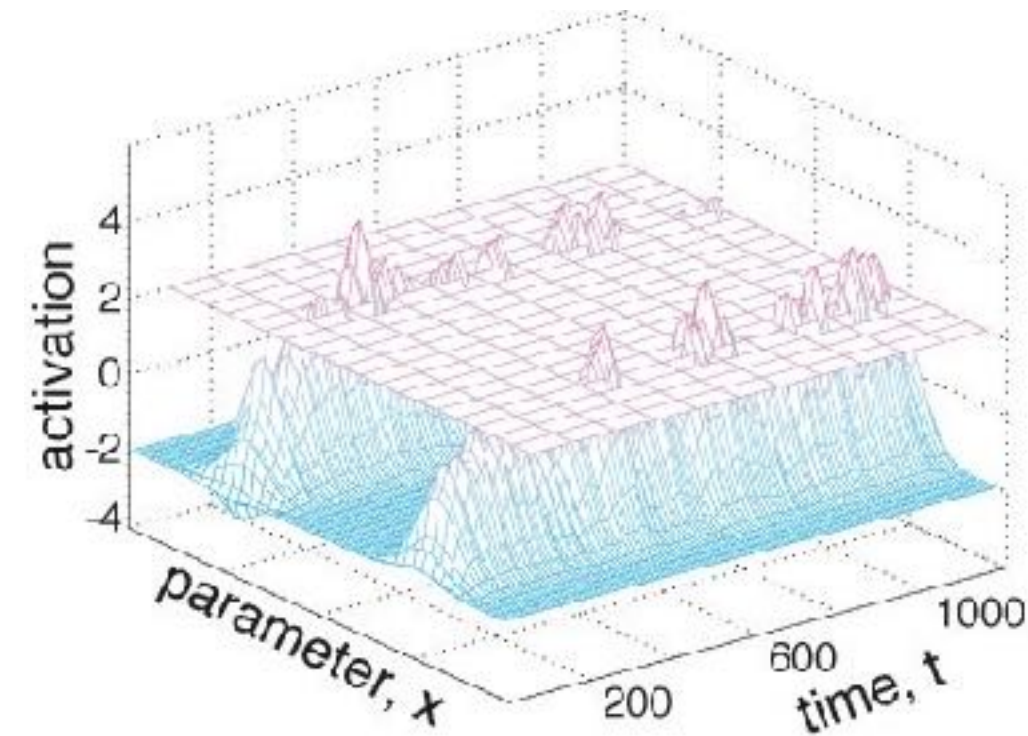
H. S. Hock, G. Schöner / Seeing and Perceiving 23 (2010) 173–195



selection instability



stabilizing selection decisions



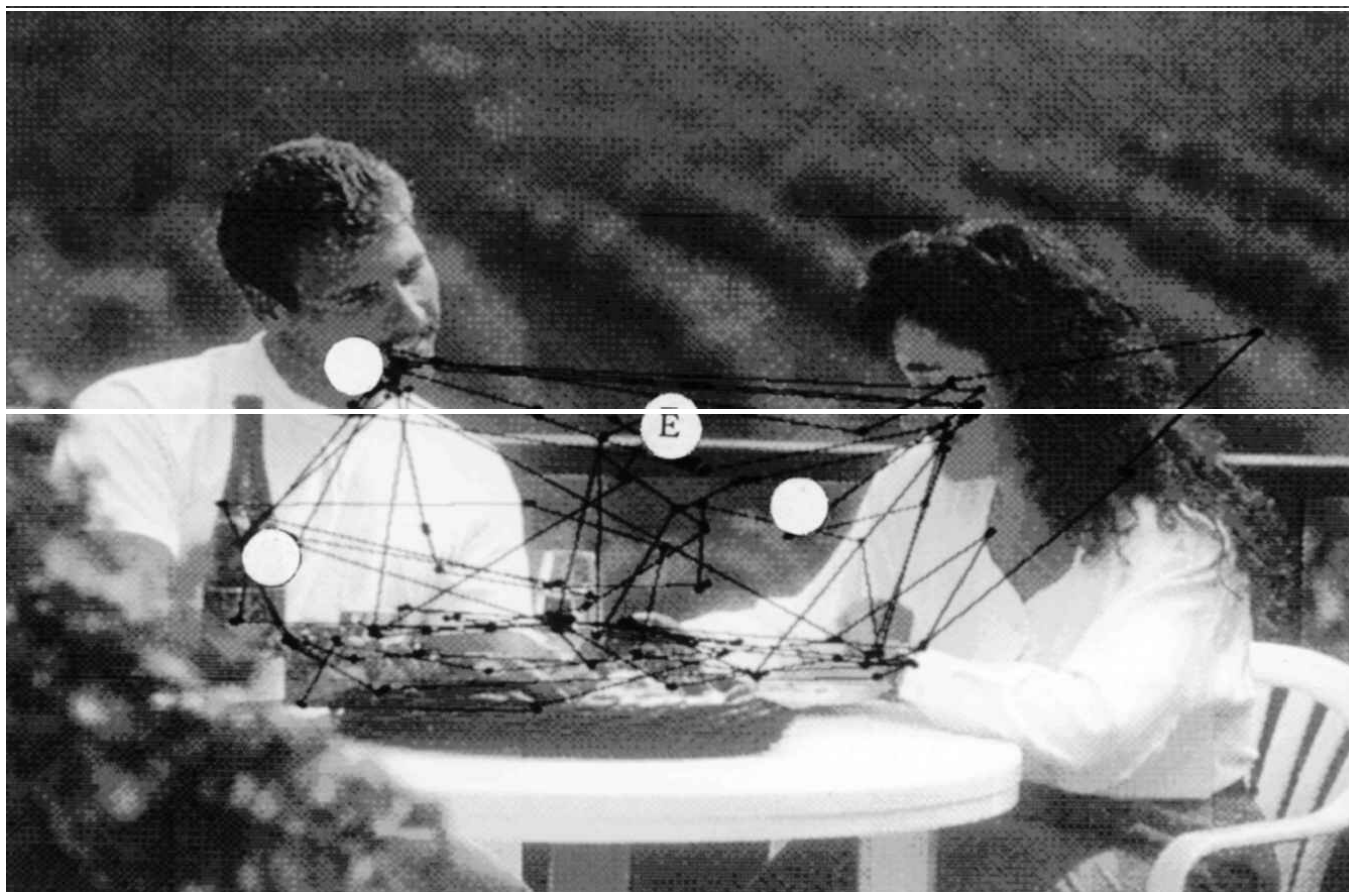
[Wilimzig, Schöner, 2006]

behavioral signatures of selection decisions

- in most experimental situations, the correct selection decision is cued by an “imperative signal” leaving no actual freedom of “choice” to the participant (only the freedom of “error”)
- reasons are experimental
- when performance approaches chance level, then close to “free choice”
- because task set plays a major role in such tasks, I will discuss these only a little later

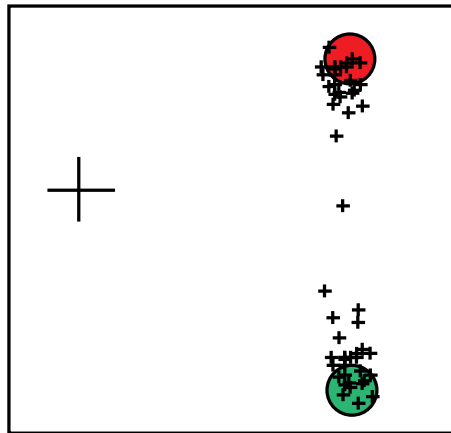
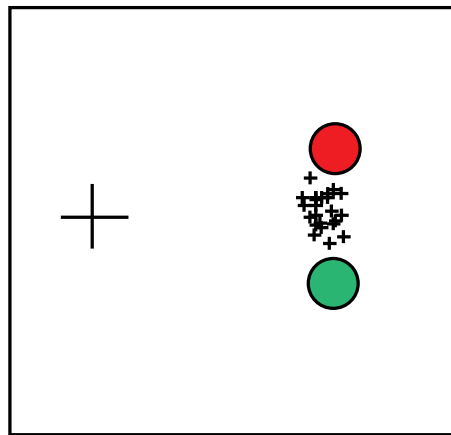
one system of “free choice”

- selecting a new saccadic location



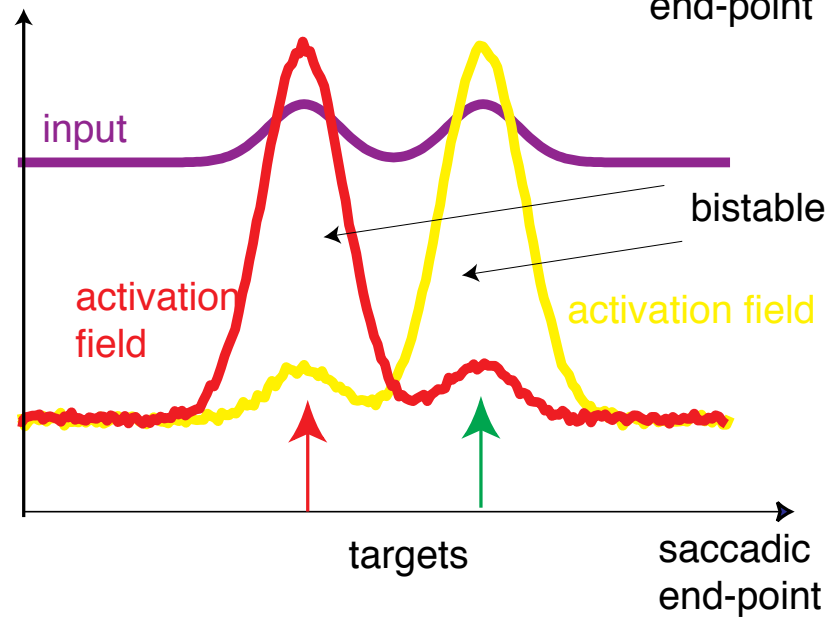
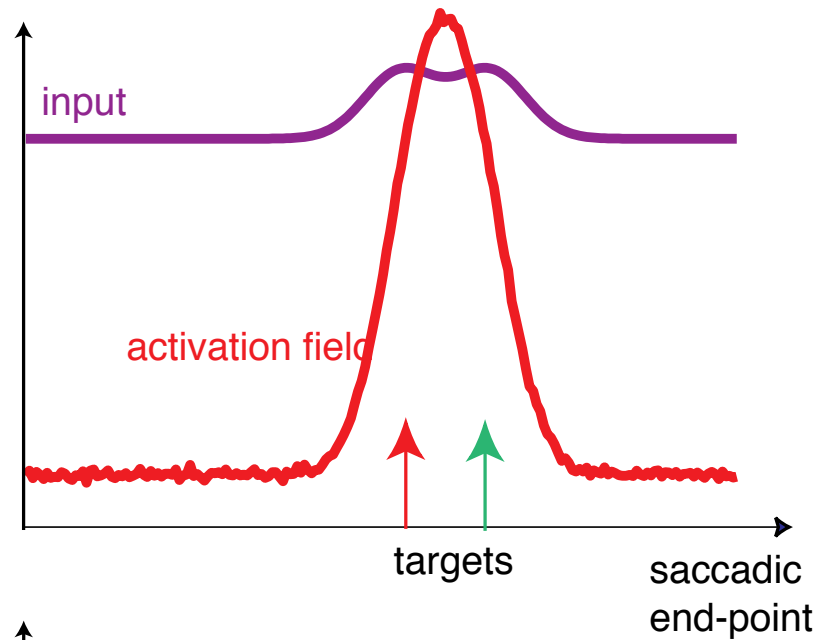
[O'Reagan et al., 2000]

saccade generation



initial
fixation

visual
targets

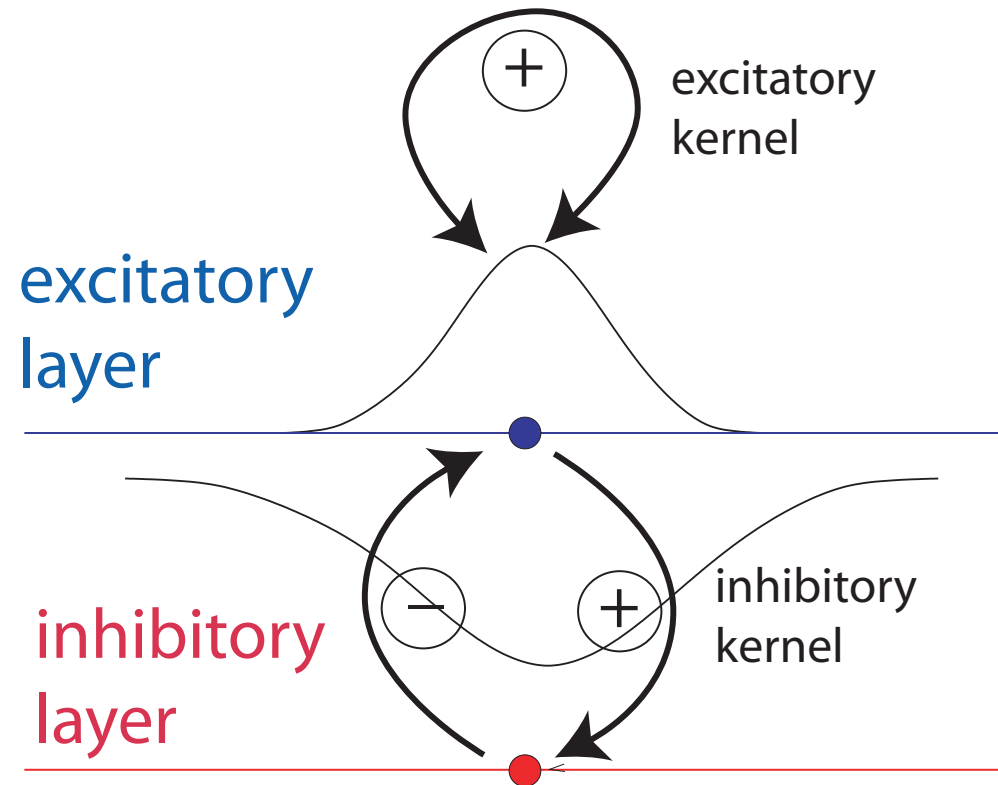


[after: Ottes et al., Vis. Res. 25:825 (85)]

[after Kopecz, Schöner: Biol Cybern 73:49 (95)]

2 layer Amari fields

- to comply with Dale's law
- and account for difference in time course of excitation (early) and inhibition (late)



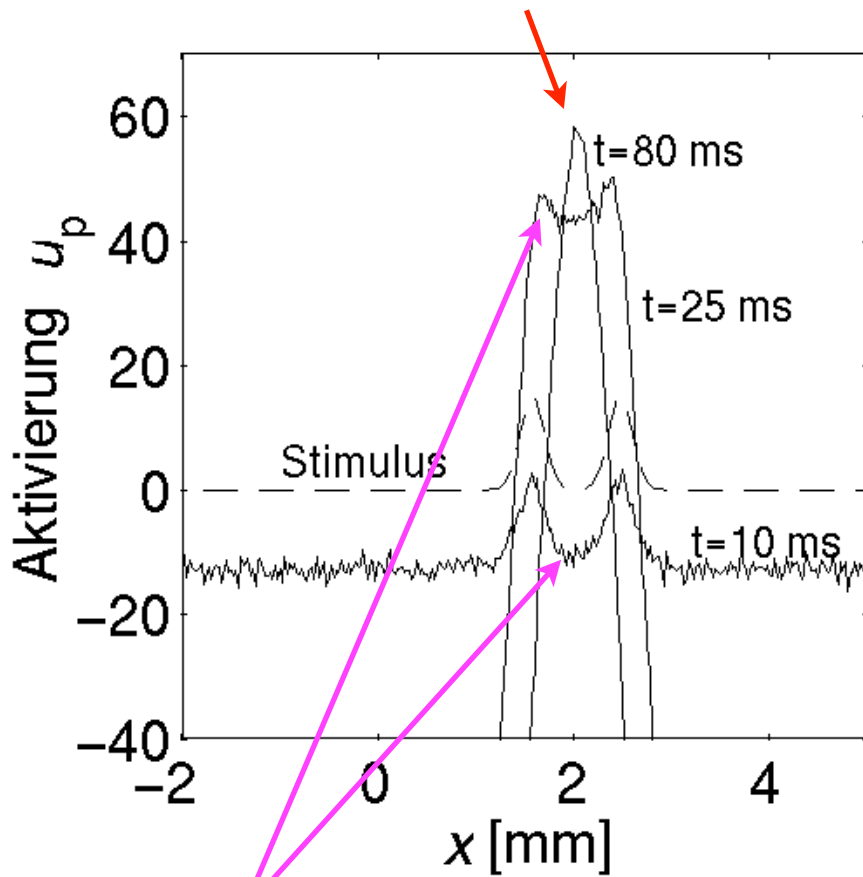
2 layer Amari model

$$\begin{aligned}\tau \dot{u}(x, t) &= -u(x, t) + h_u + S(x, t) + \int dx' c_{uu}(x - x') \sigma(u(x', t)) \\ &\quad - \int dx' c_{uv}(x - x') \sigma(v(x', t)) \\ \tau \dot{v}(x, t) &= -v(x, t) + h_v + \int dx' c_{vu}(x - x') \sigma(u(x', t))\end{aligned}$$

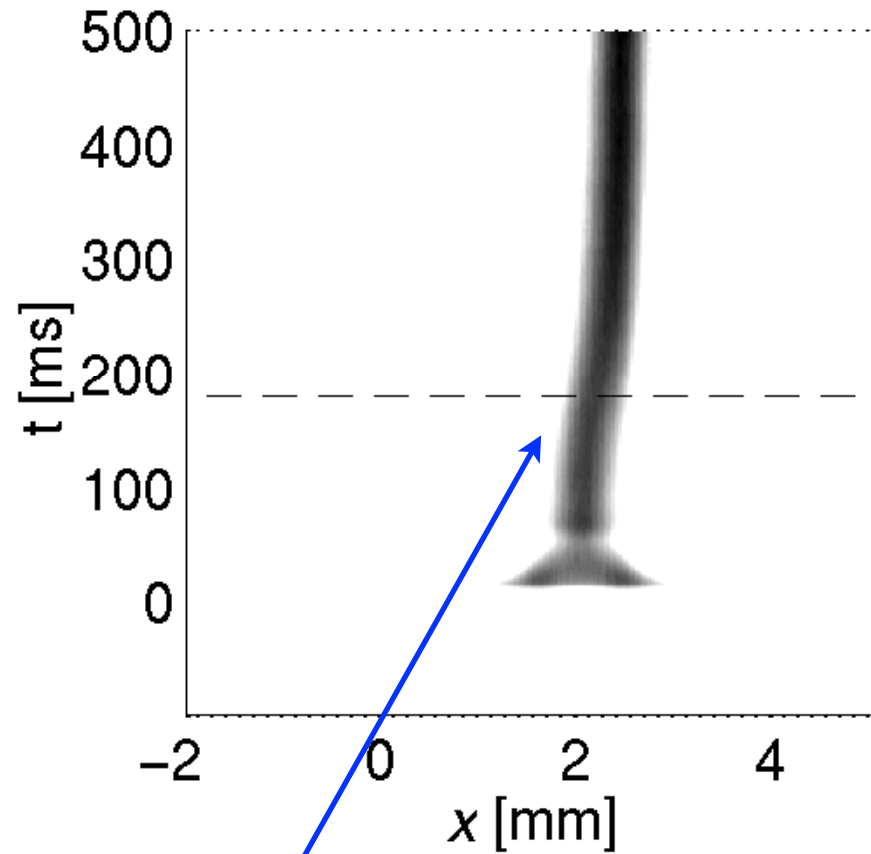
$$c_{ij}(x - x') = c_{i,j,\text{strength}} \exp \left[-\frac{(x - x')^2}{2\sigma_{ij}^2} \right]. \quad \sigma(u) = \frac{1}{1 + \exp[-\beta u]}.$$

time course of selection

intermediate: dominated by excitatory interaction

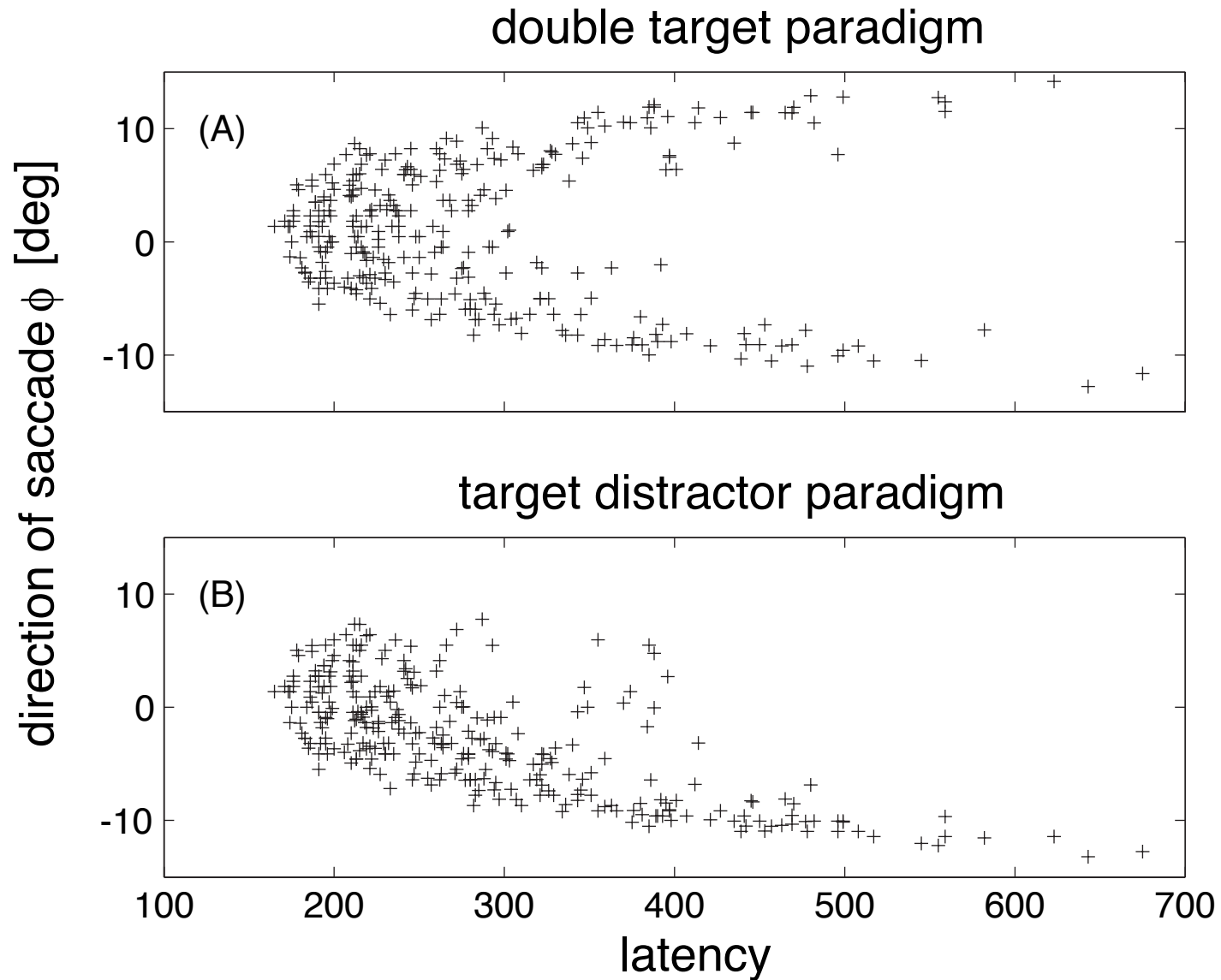


early: input driven



late: inhibitory interaction drives selection

=> early fusion, late selection



studying selection decisions in the laboratory

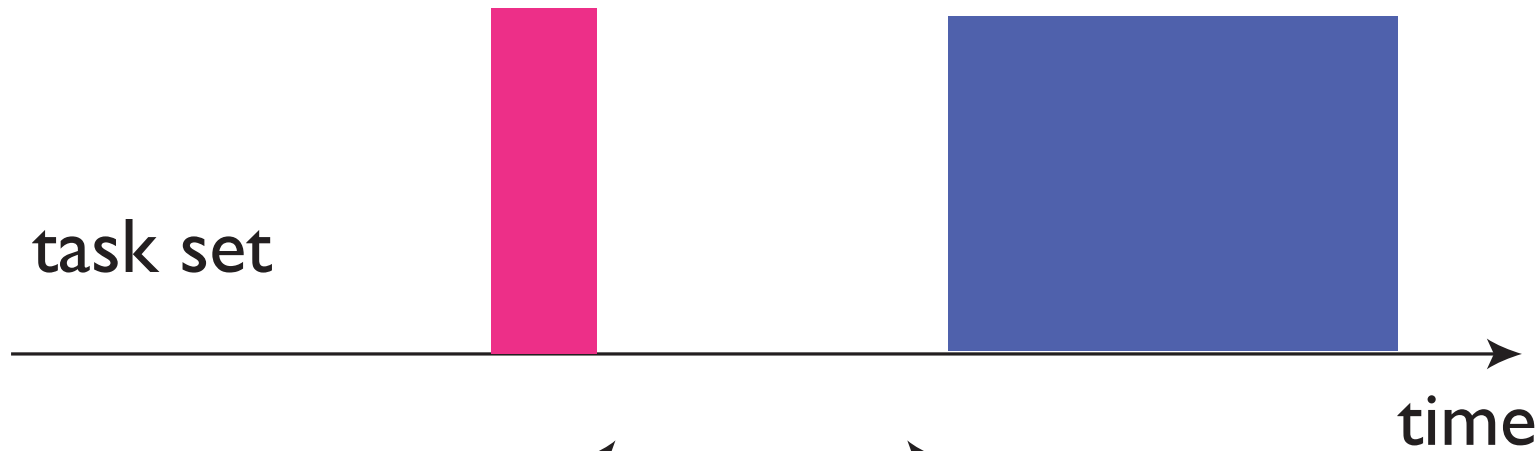
- using an imperative signal...

reaction time (RT) paradigm

imperative
signal=
go signal

response

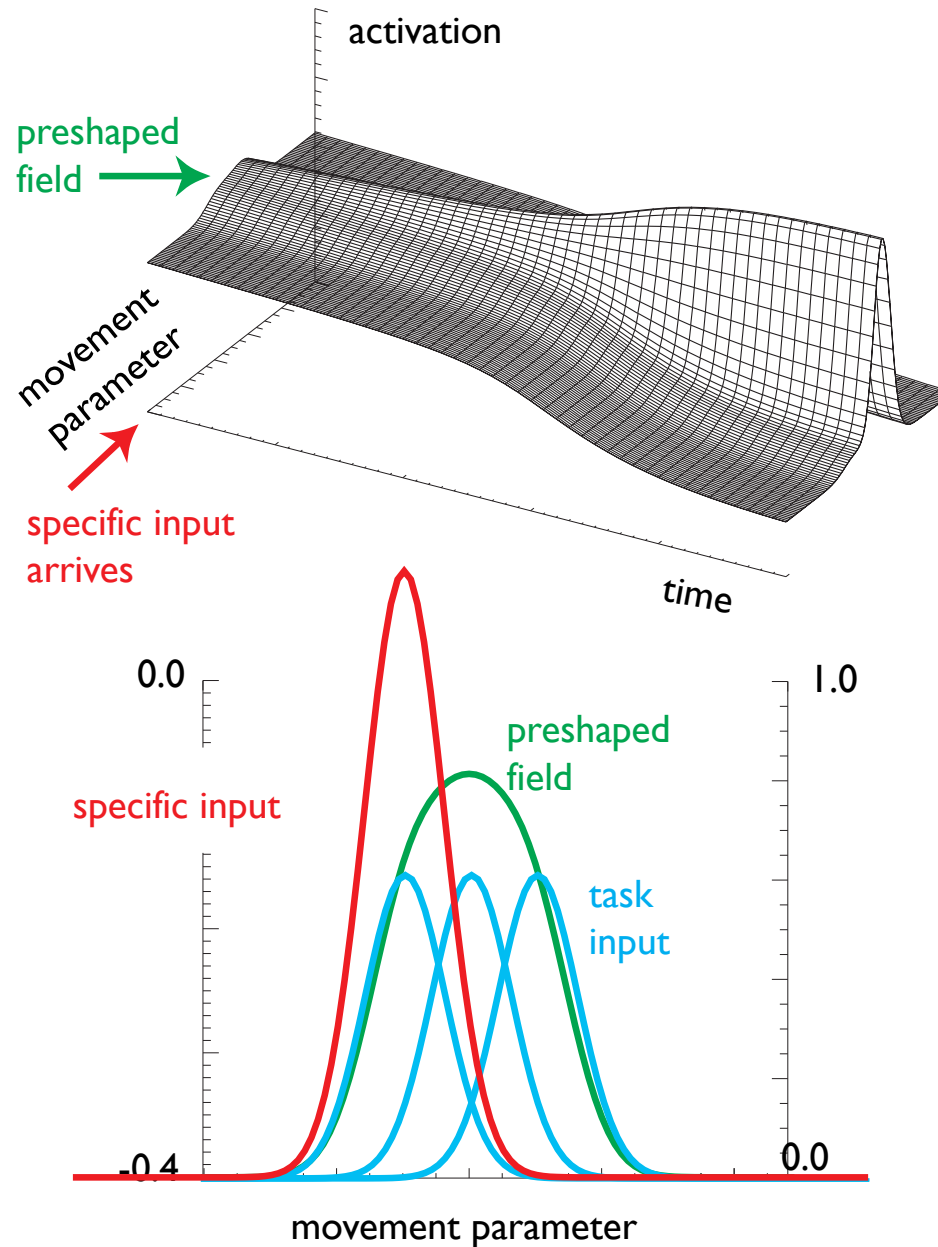
task set



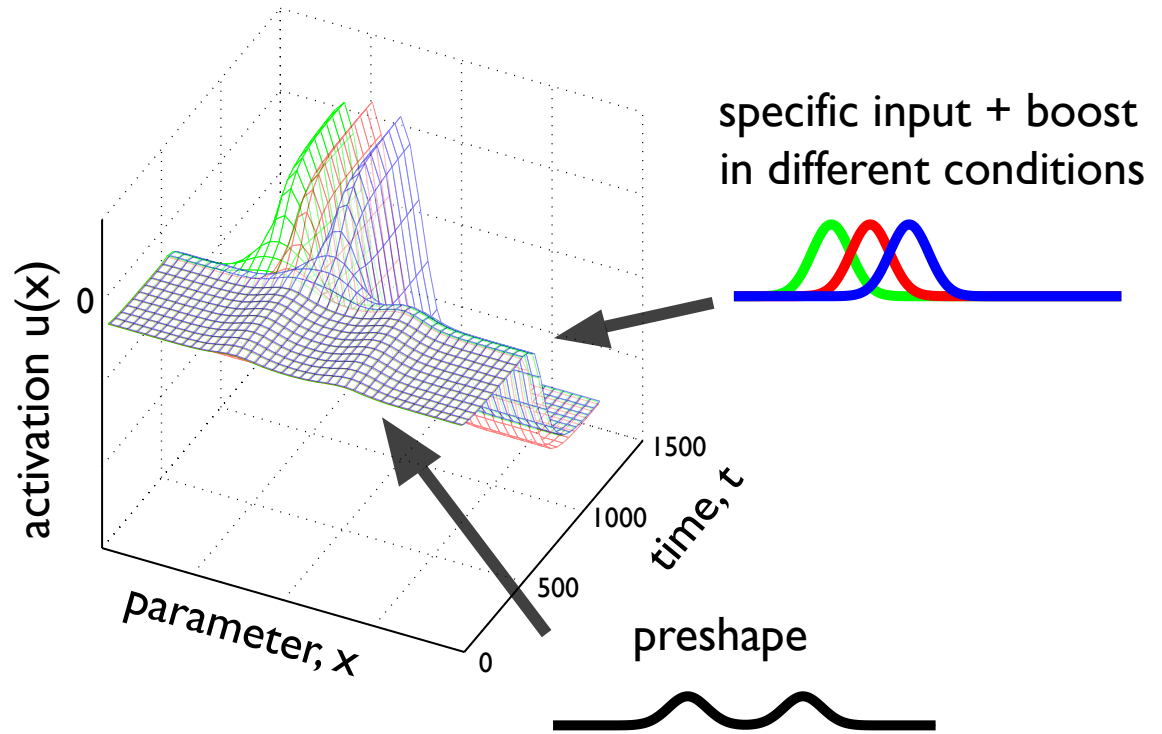
task set

- that is the critical factor in most studies of selection!
 - for example, the classical Hick law, that the number of choices affects RT, is based on the task set specifying a number of choices
- (although the form in which the imperative signal is given is varied as well...)
- how do neuronal representations reflect the task set?

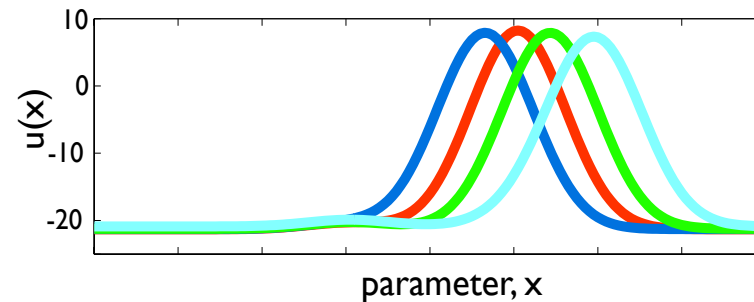
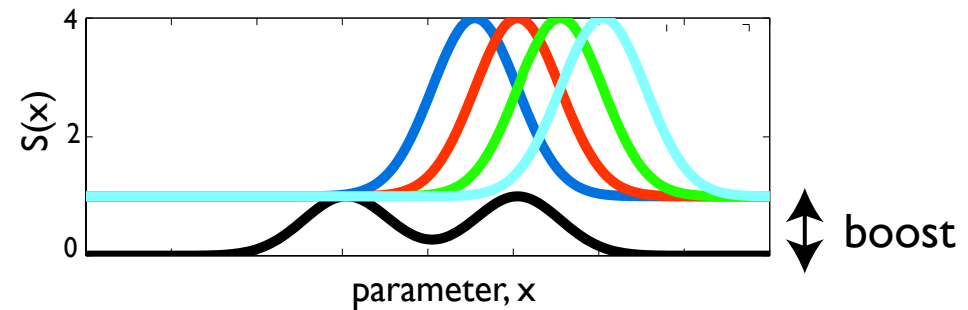
notion of preshape



weak preshape in selection

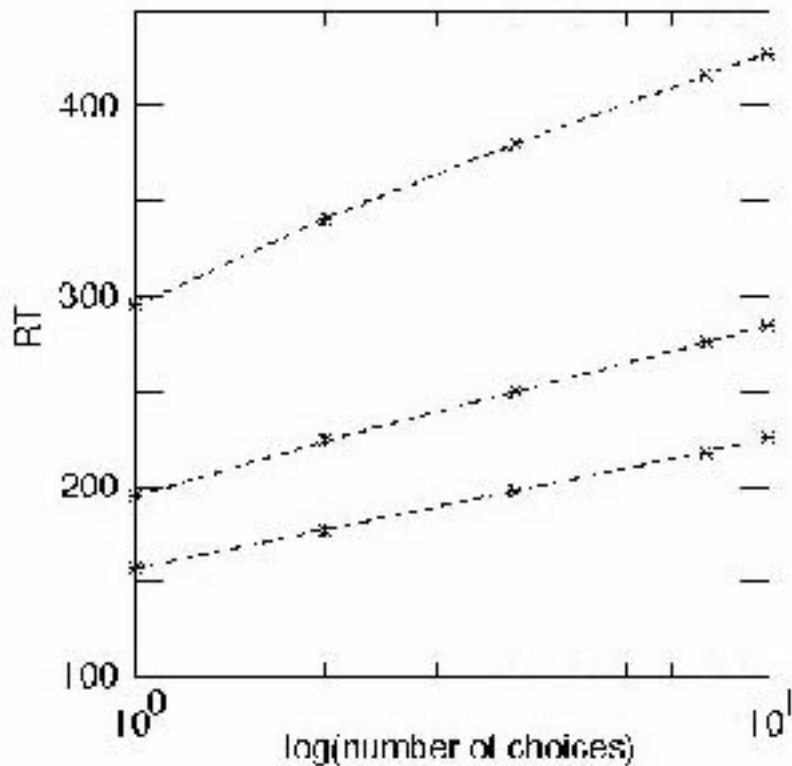


- specific (imperative) input dominates and drives detection instability

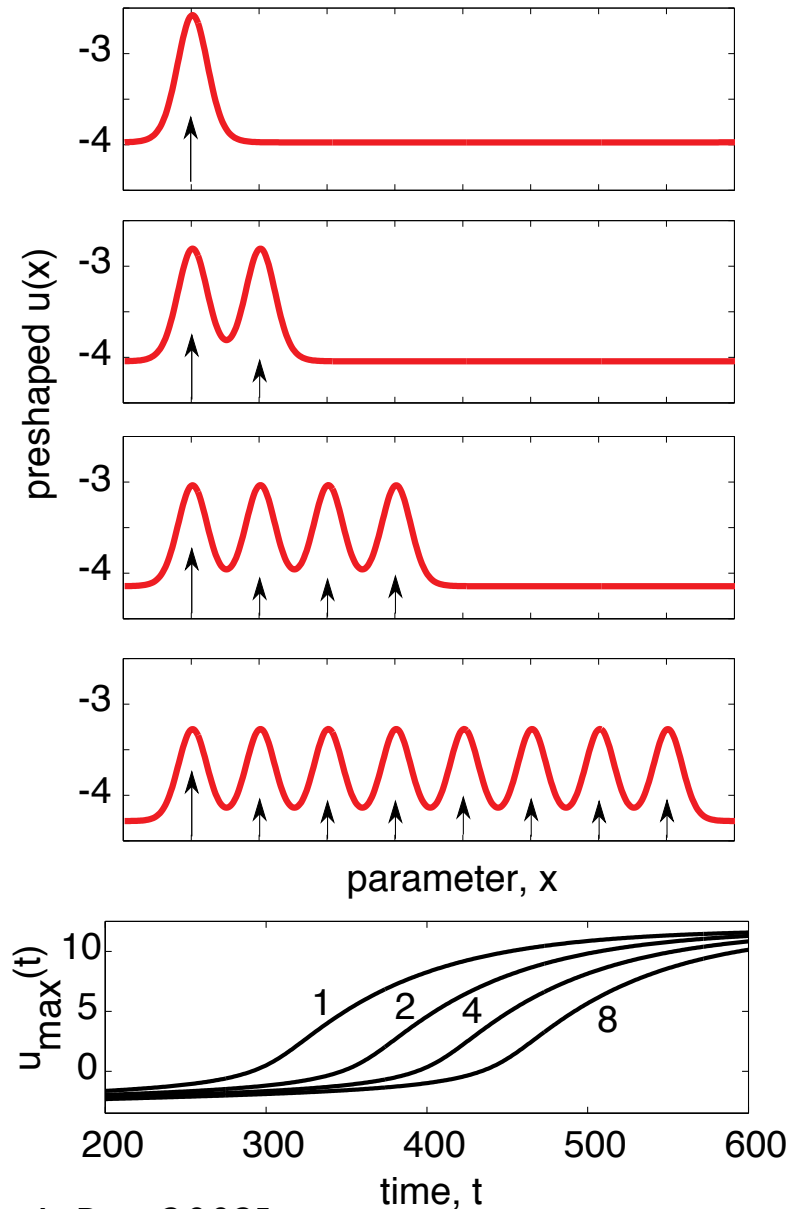


using preshape to account for classical RT data

- Hick's law: RT increases with the number of choices

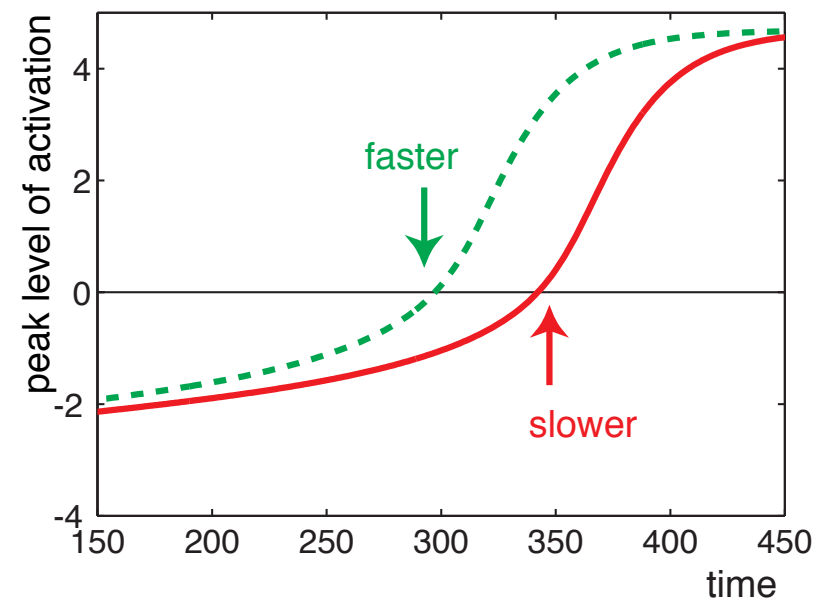
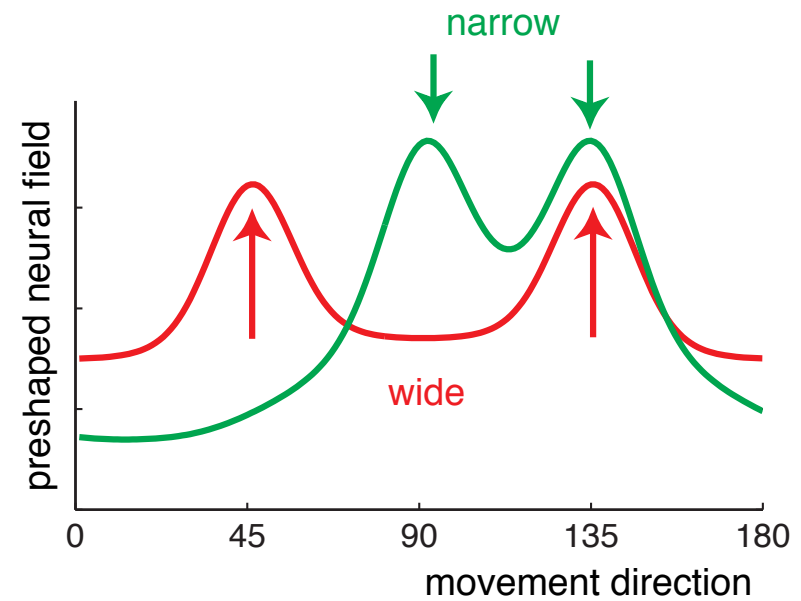


[Erlhagen, Schöner, Psych Rev 2002]



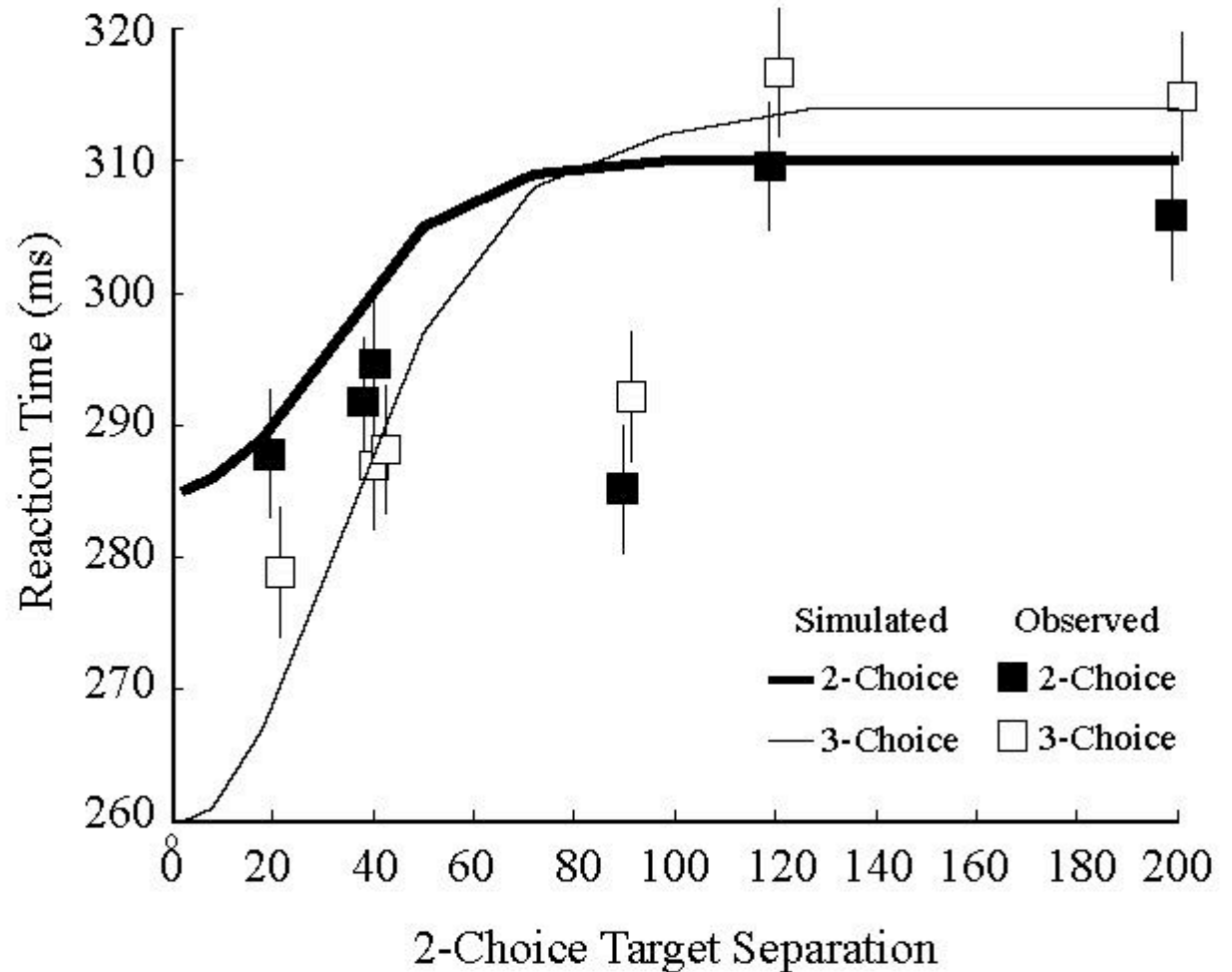
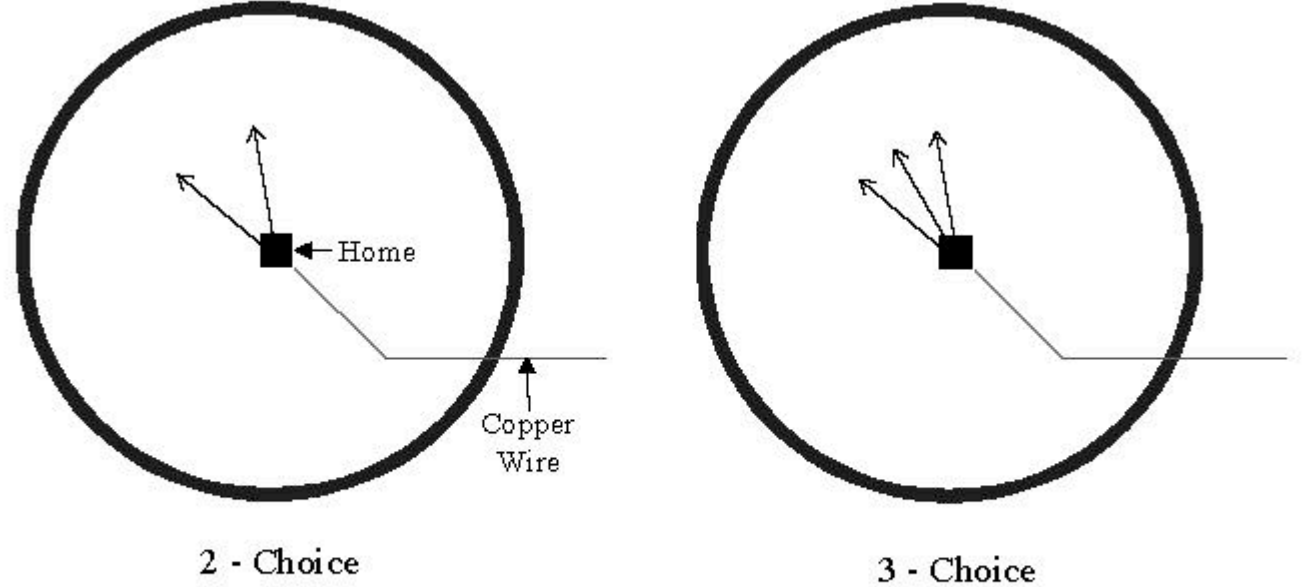
metric effect

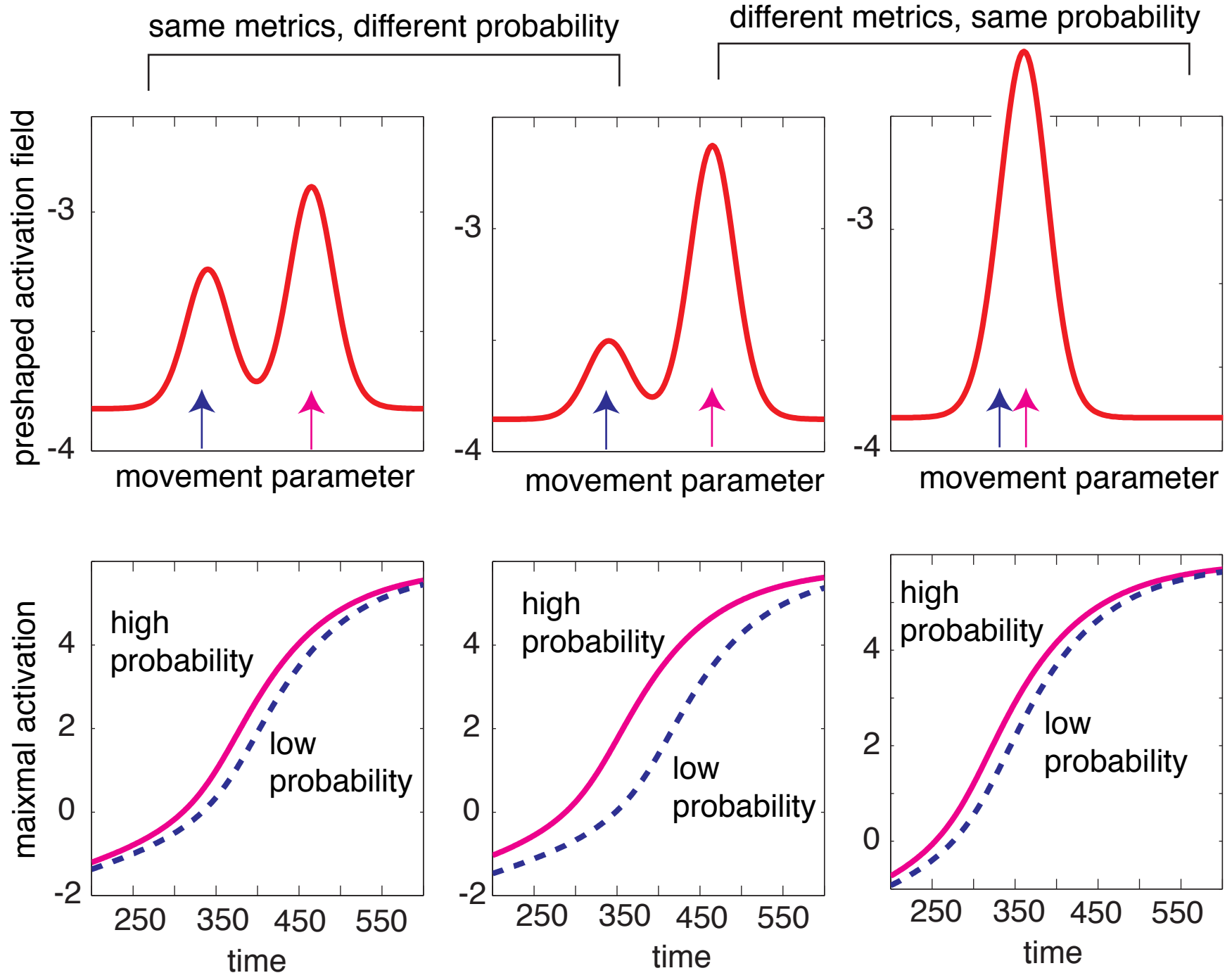
- predict faster response times for metrically close than for metrically far choices



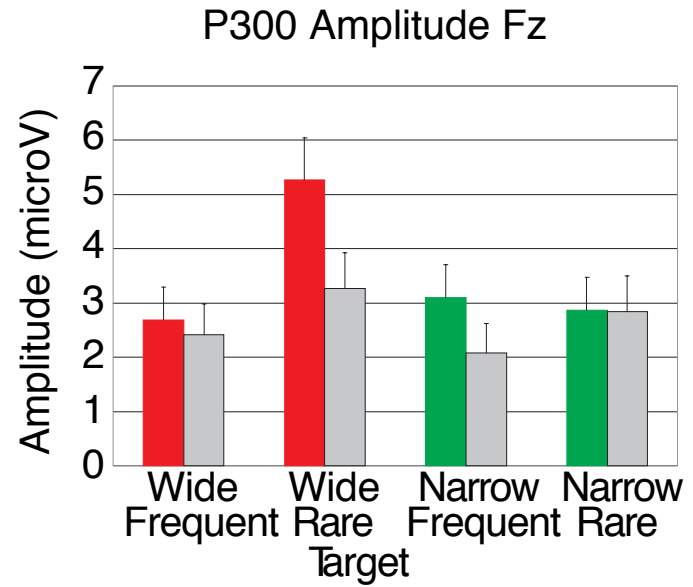
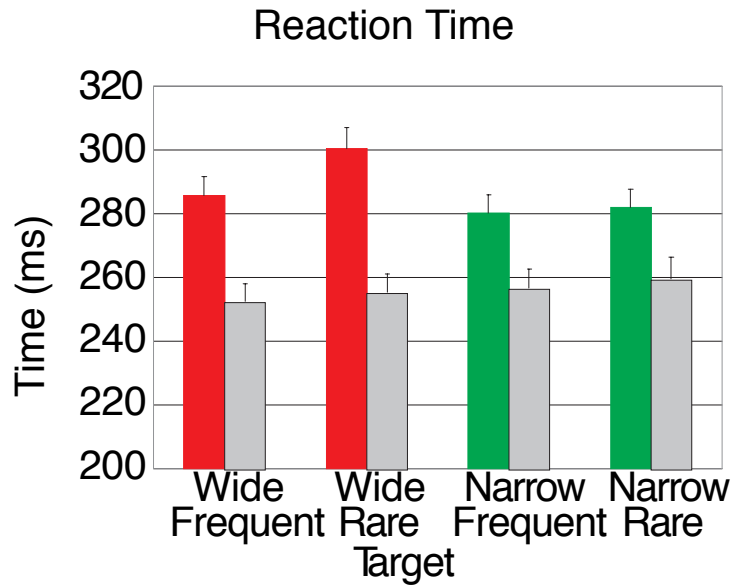
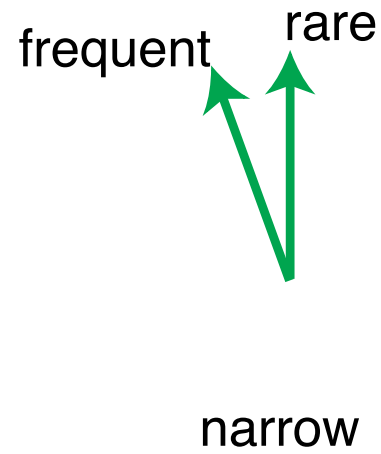
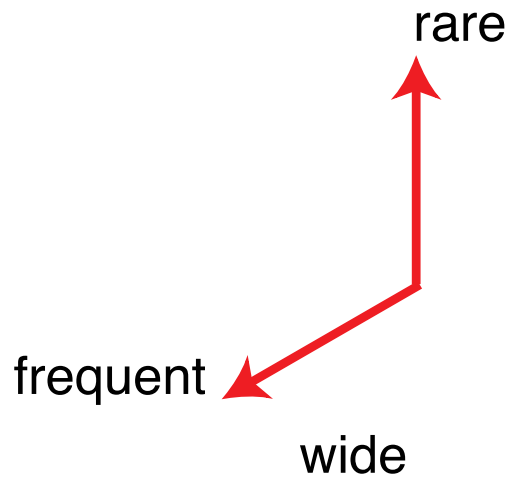
[from Schöner, Kopecz, Erlhagen, 1997]

experiment: metric effect



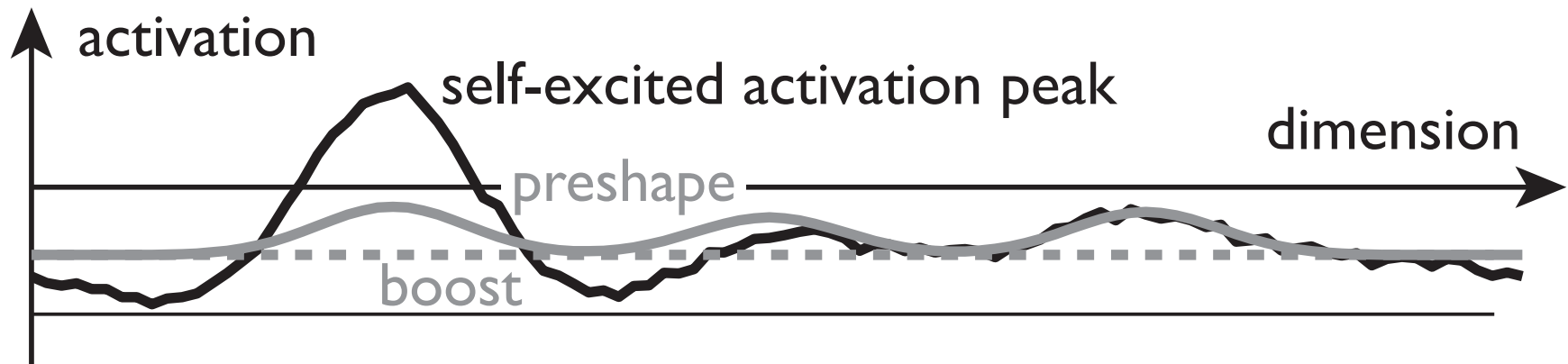
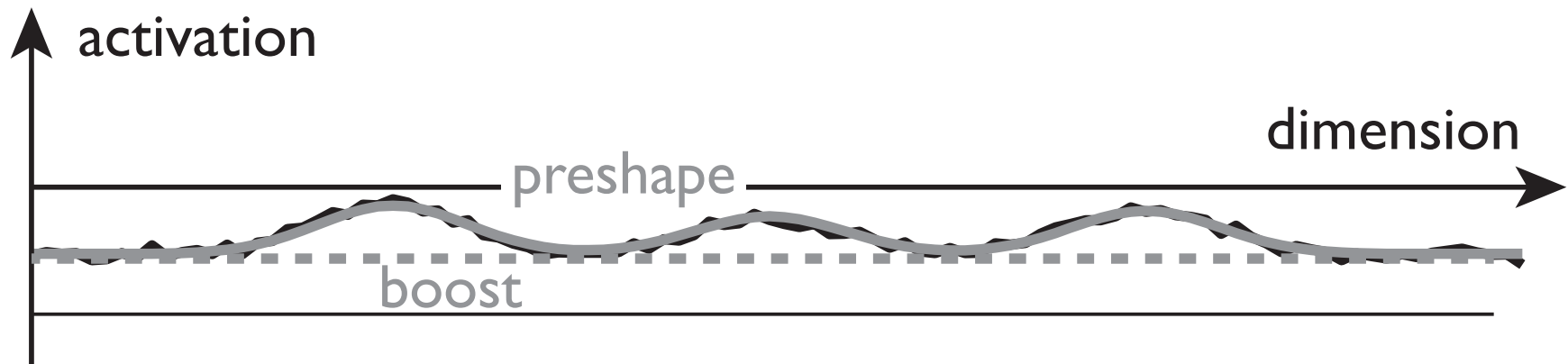
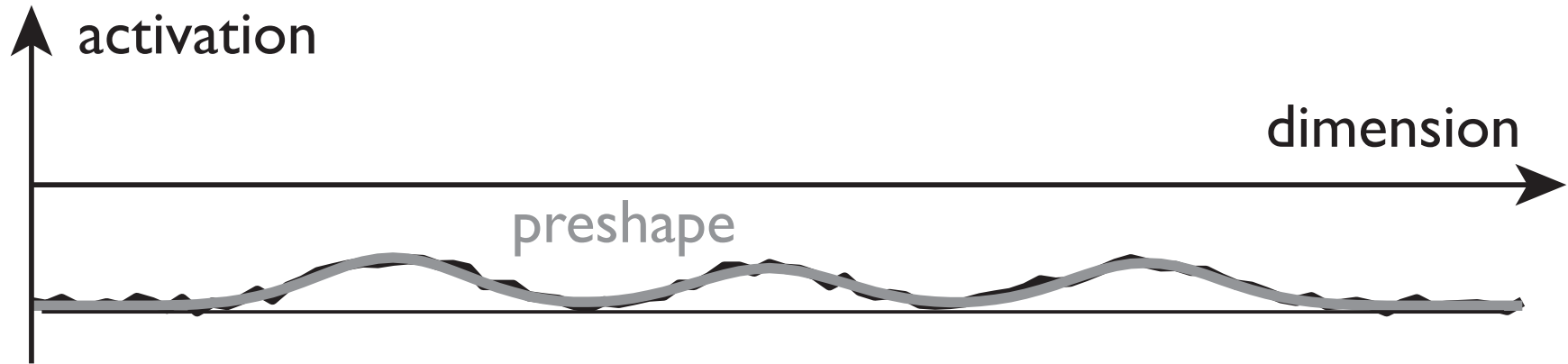


[from Erlhagen, Schöner: Psych. Rev. 2002]



[from McDowell, Jeka, Schöner, Hatfield, 2002]

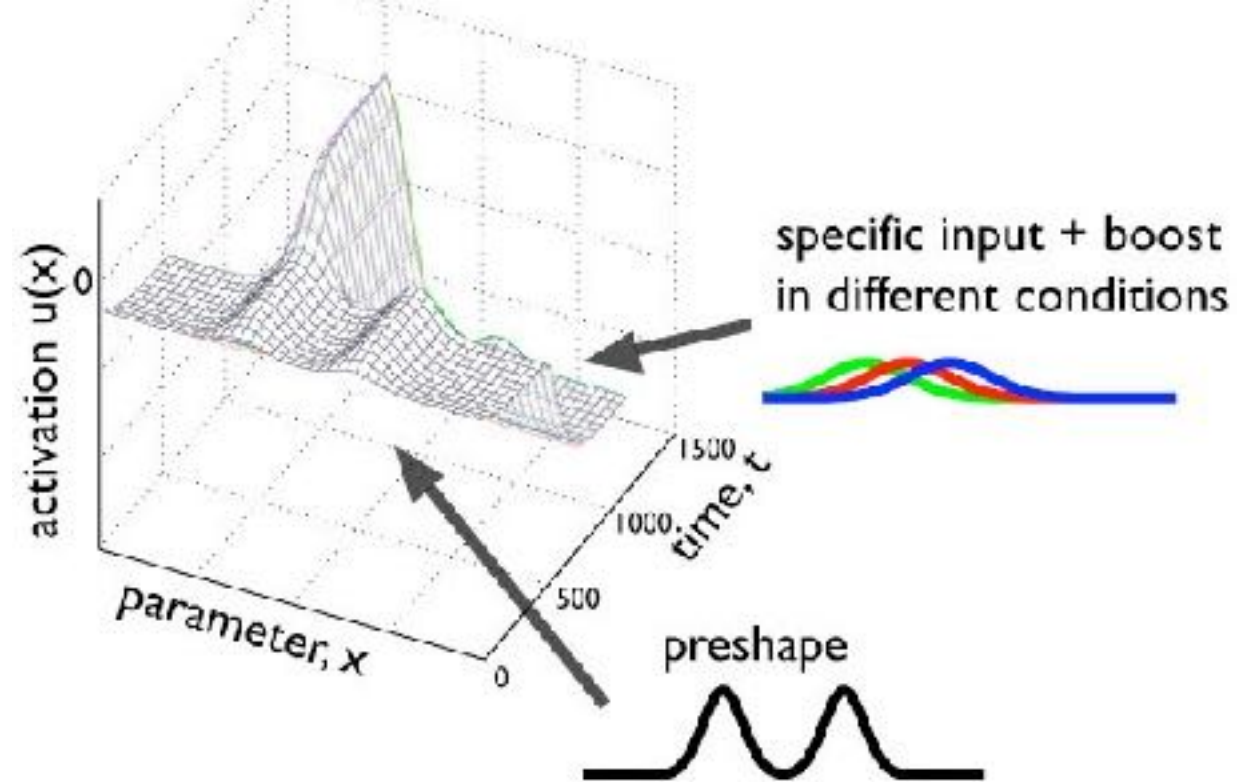
boost-induced detection instability



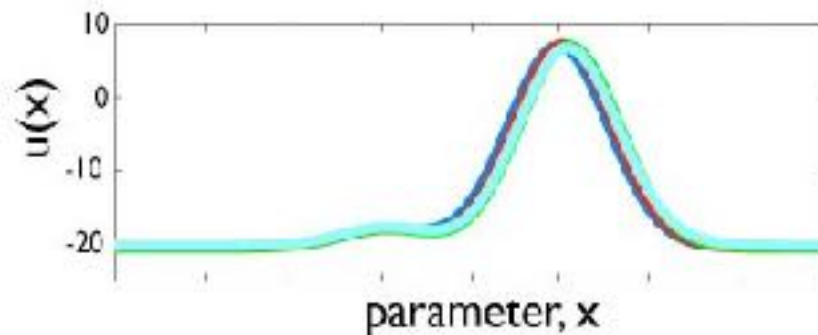
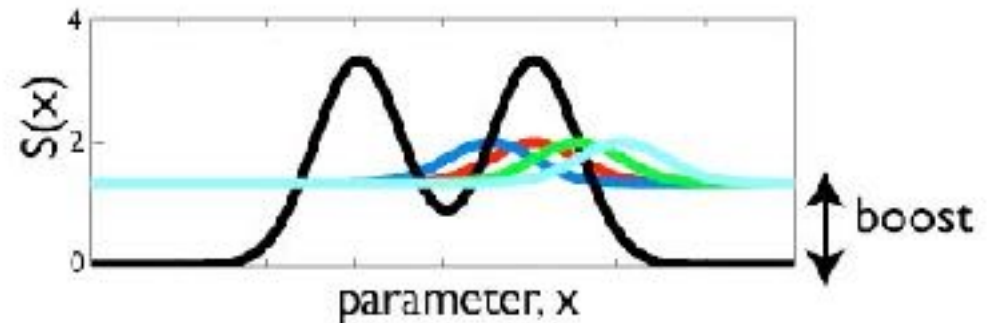
boost-driven detection instability

- inhomogeneities in the field existing prior to a signal/stimulus that leads to a macroscopic response=“preshape”
- the boost-driven detection instability amplifies preshape into macroscopic selection decisions

this supports
categorical
behavior

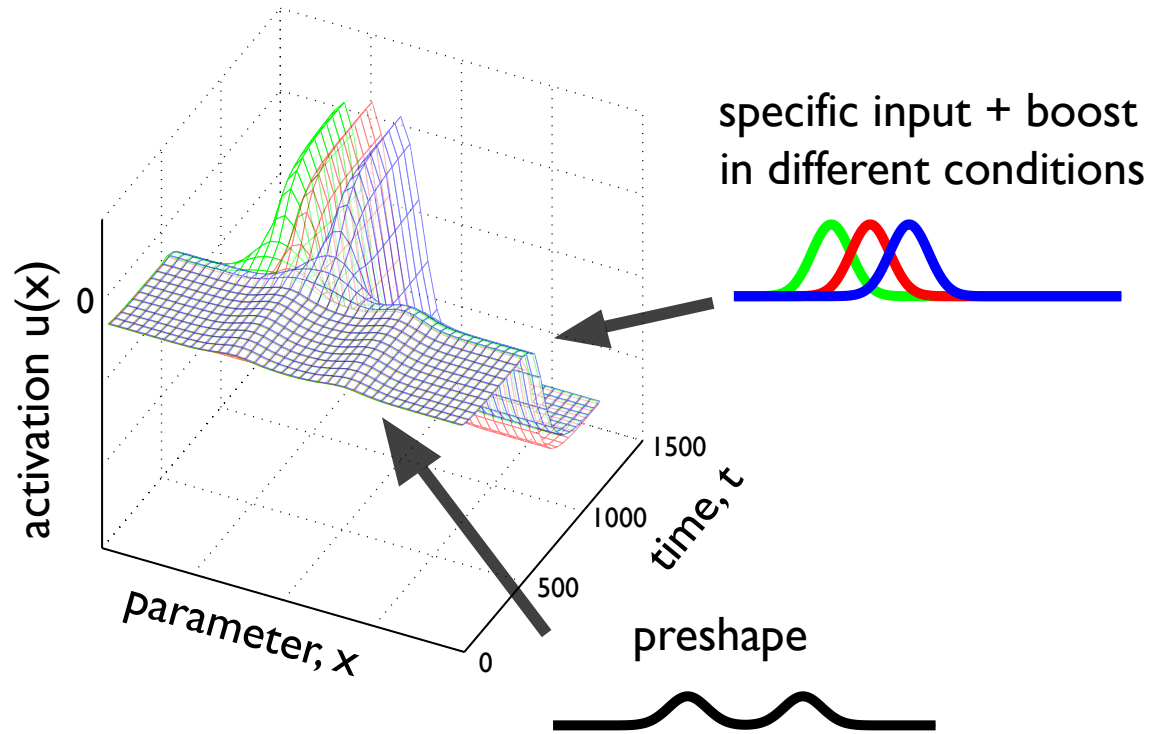


■ when preshape
dominates

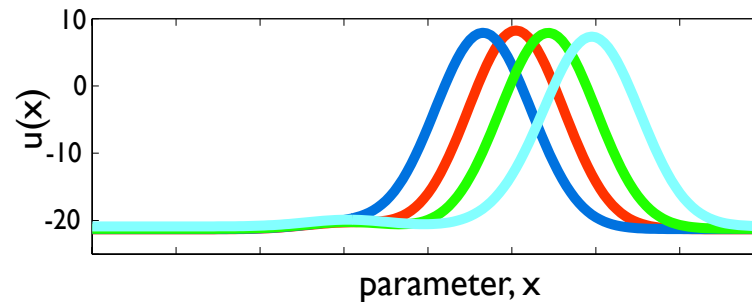
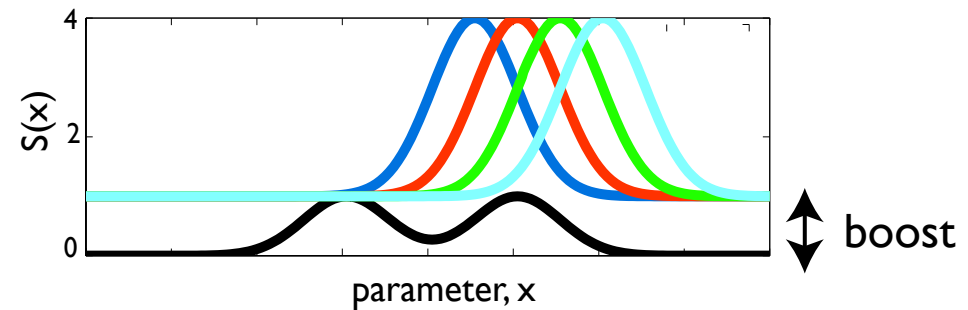


[Wilimzig, Schöner, 2006]

weak preshape in selection



- specific (imperative) input dominates and drives detection instability



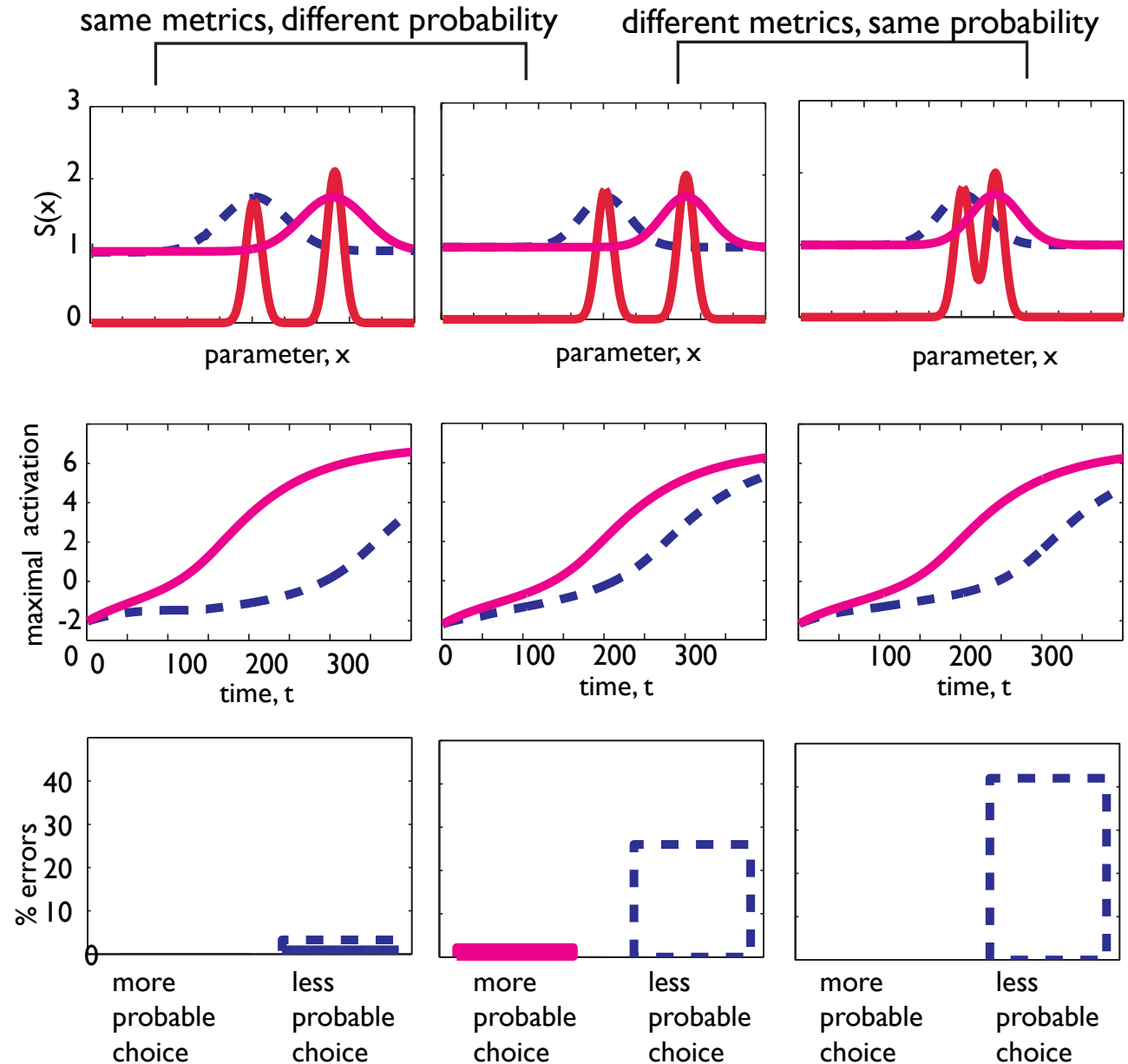
distance effect

- common in categorical tasks

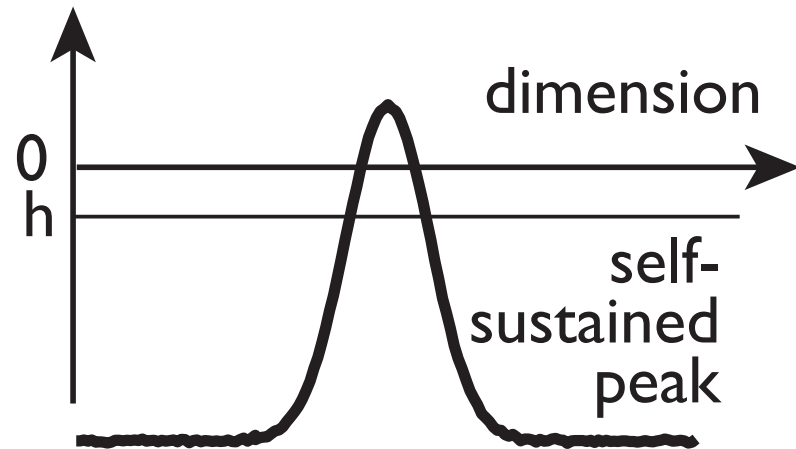
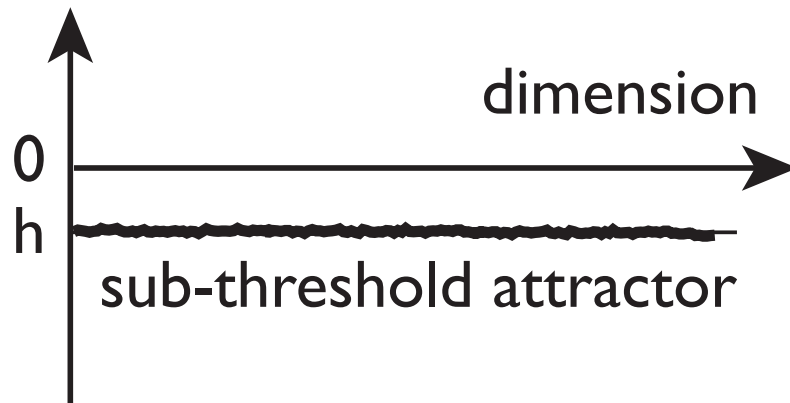
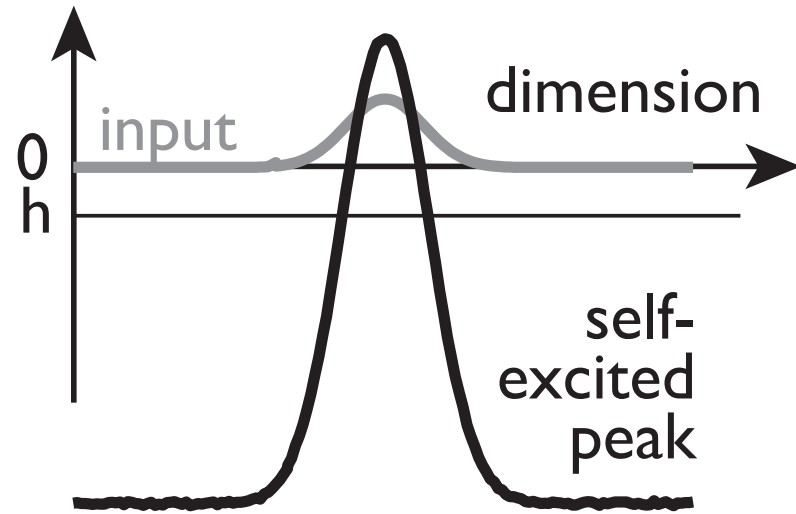
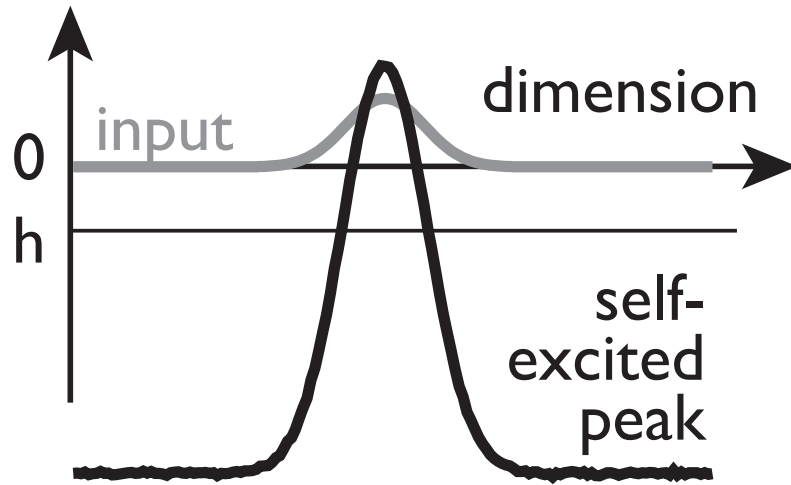
- e.g., decide which of two sticks is longer... RT is larger when sticks are more similar in length

interaction metrics-probability

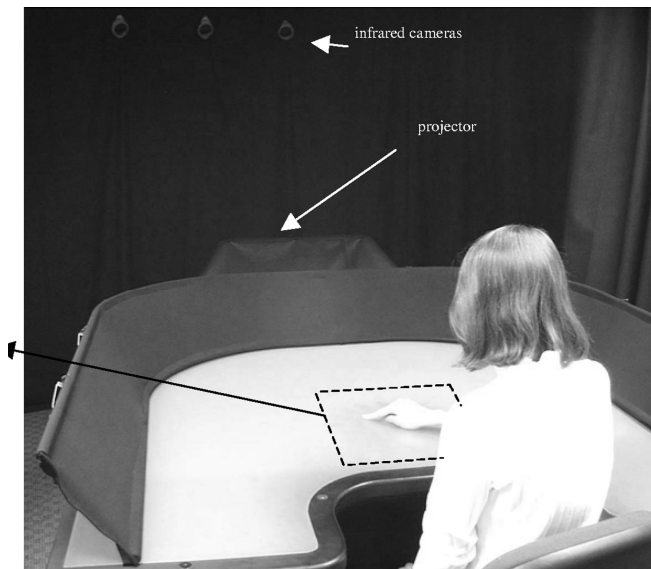
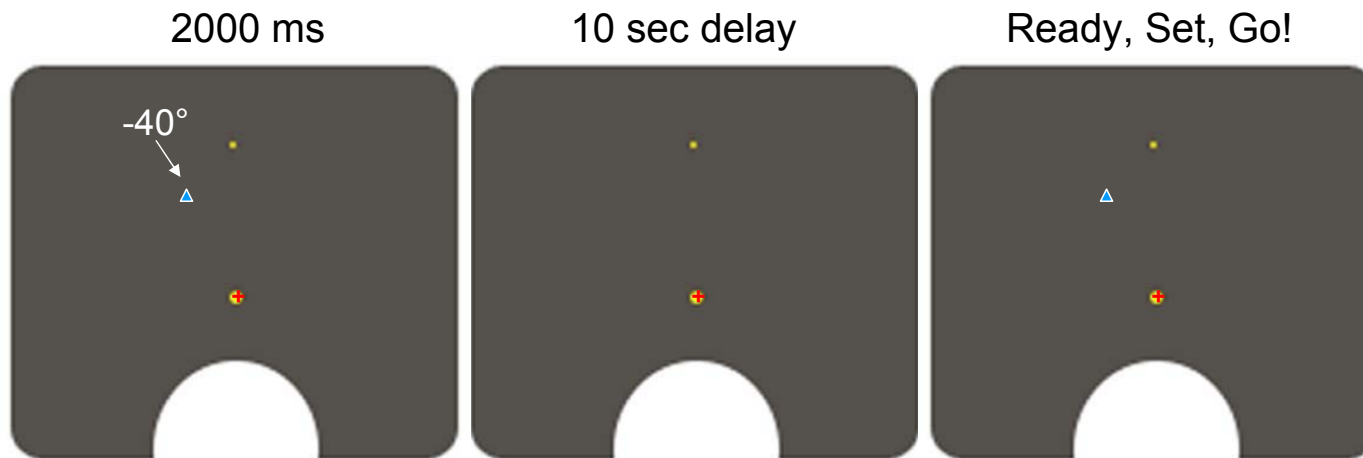
- opposite to that predicted for input-driven detection instabilities:
- metrically close choices show larger effect of probability



Memory instability

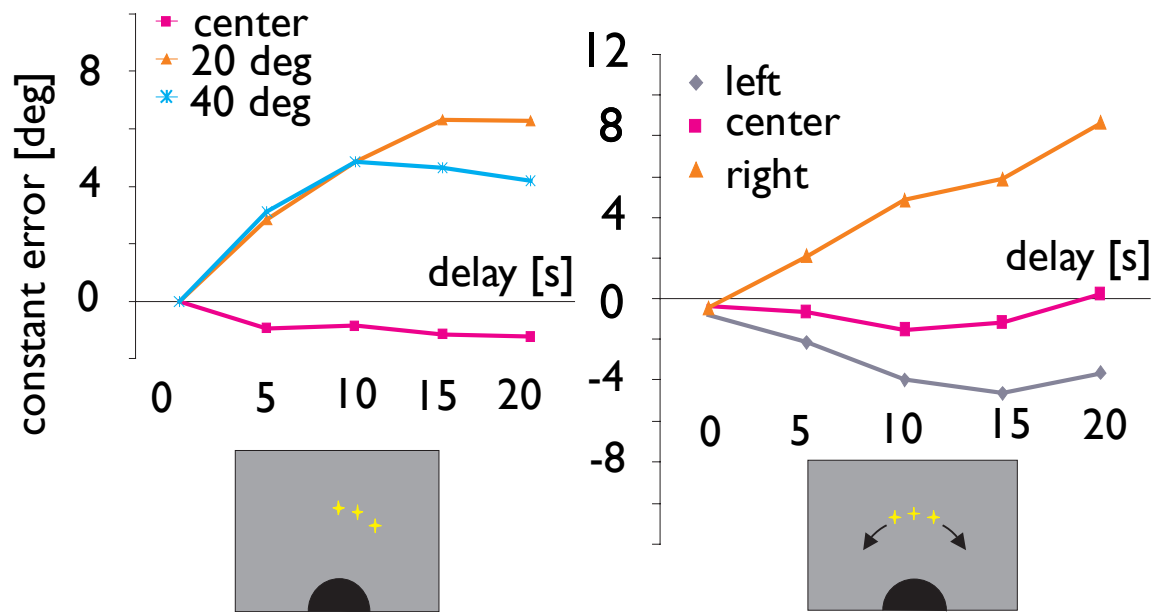
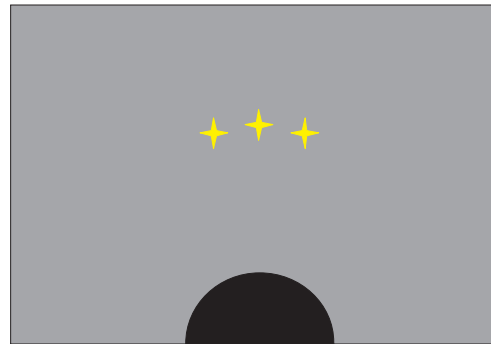


■ “space ship” task probing spatial working memory

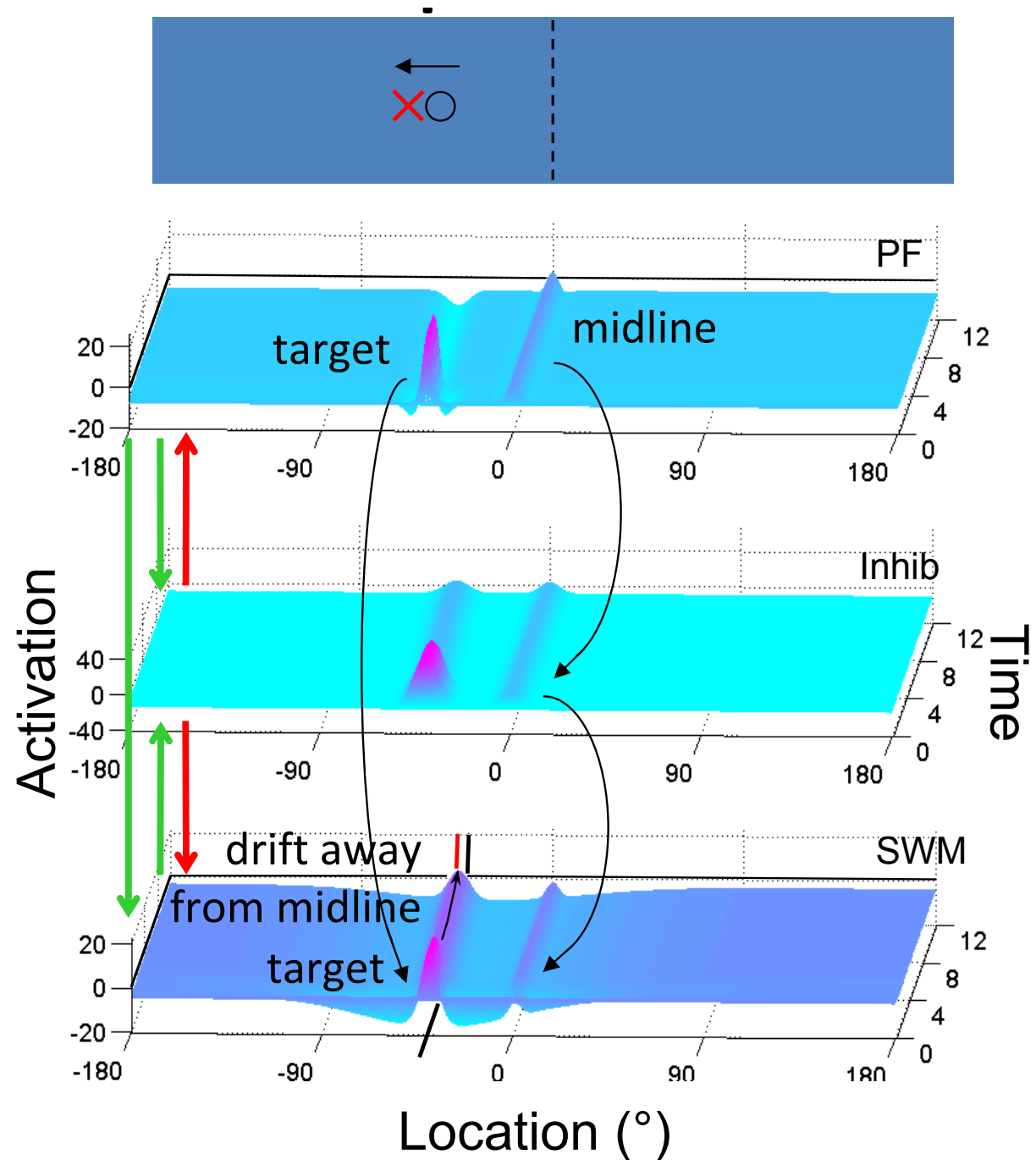


[Schutte, Spencer, JEP:HPP 2009]

■ repulsion from midline/landmarks



- DFT account of repulsion: inhibitory interaction with peak representing landmark



Working memory as sustained peaks

- implies metric drift of WM, which is a marginally stable state (one direction in which it is not asymptotically stable)
- => empirically real..