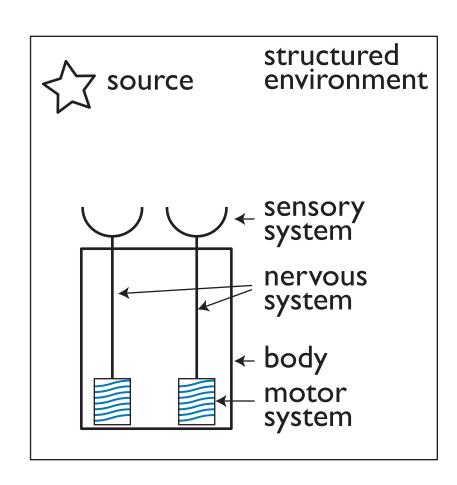
Embodied nervous systems

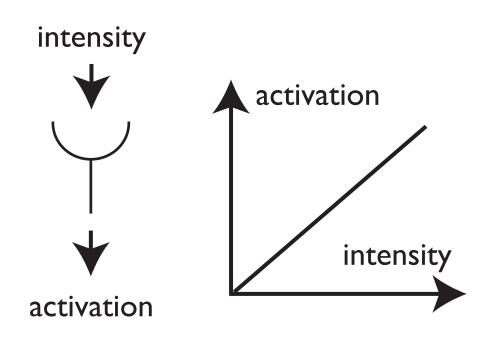
Braitenberg vehicles

- =embodied nervous systems with:
 - effectors
 - sensors
 - a nervous system
 - a body
- + situated in a structured environment
- = emergent function



Sensors

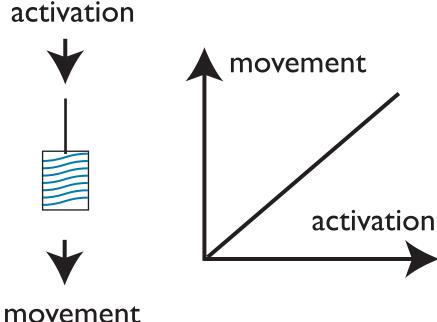
- defined by sensor characteristic =relationship between
- the physical stimulus intensity
 - e.g., sound, luminance, chemical concentration, mechanical pressure....
- and an activation variable



Effectors

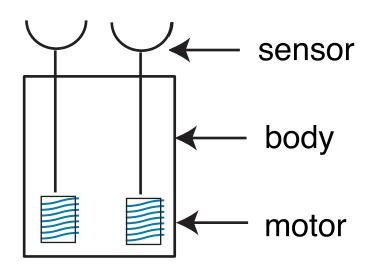
- defined by the motor characteristic =functional relationship between
- an activation level
- and a physical effect generated

for example: turning rate (rotations per minute rmp), force level, stiffness, ...)



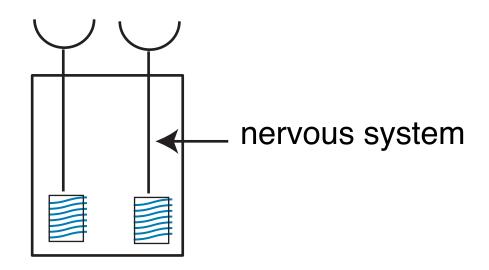
Body

the body links the sensors and effectors mechanically

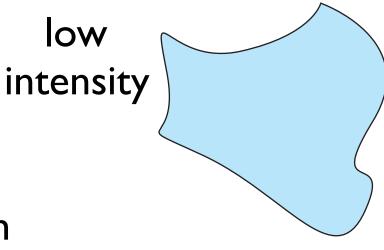


Nervous system

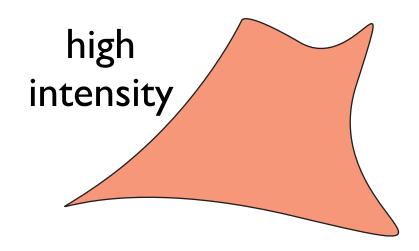
links sensors to effectors



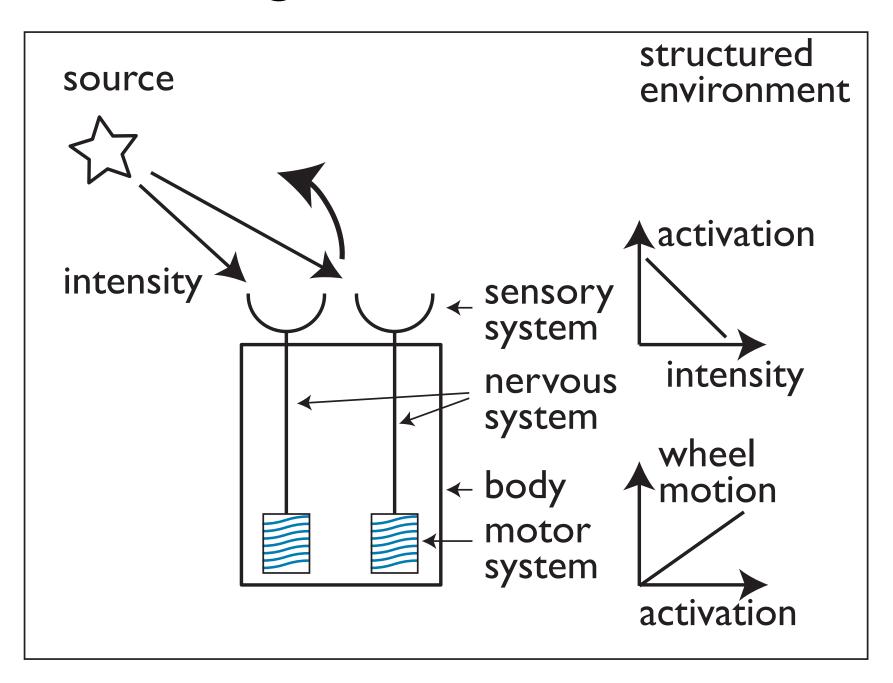
Environment



non-homogeneous with respect to the physical intensity sensed

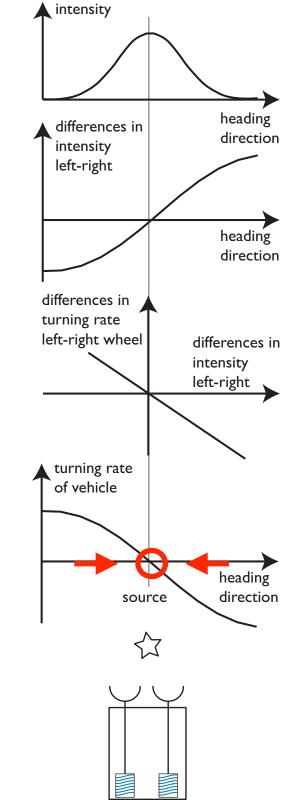


Emergent behavior: taxis



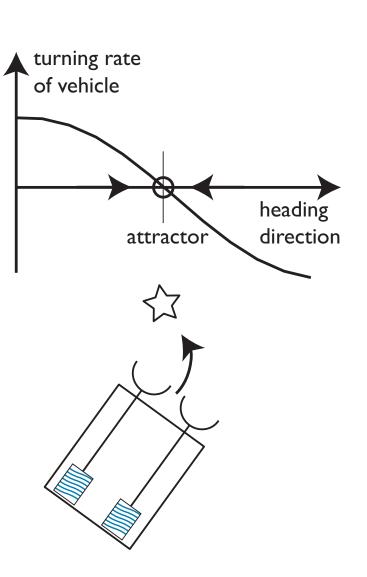
Emergent behavior: this is a dynamics

- feedforward nervous system
- + closed loop through environment
- => (behavioral) dynamics



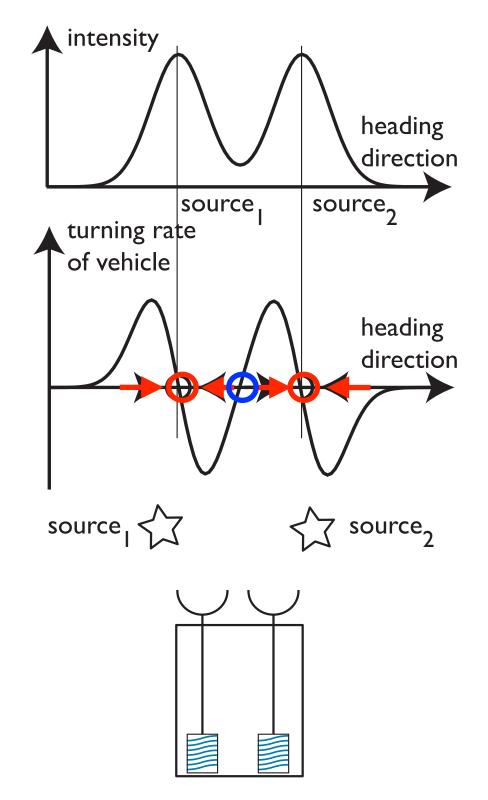
Emergent behavior: this is a dynamics

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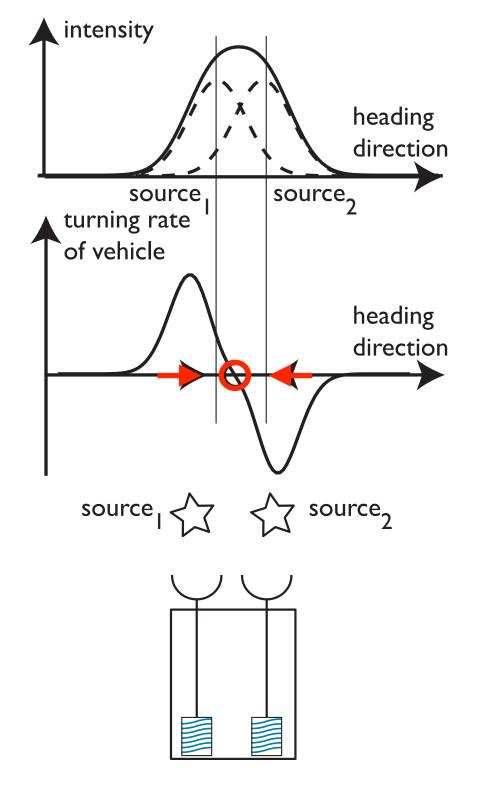
Complex environment => complex dynamics

- bistable dynamics for bimodal intensity distribution
- => nonlinear dynamics makes selection decision



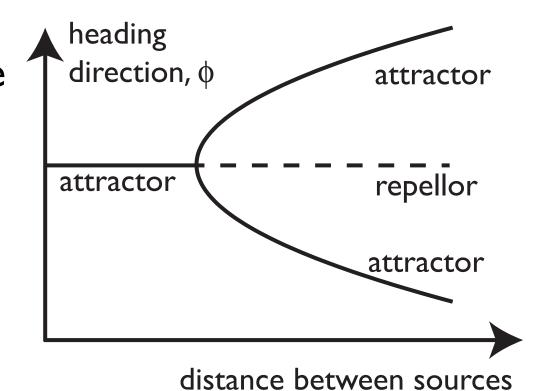
Complex environment => complex dynamics

- transition to monostable for mono-modal distribution
- => instabilities lead to qualitative change of behavior

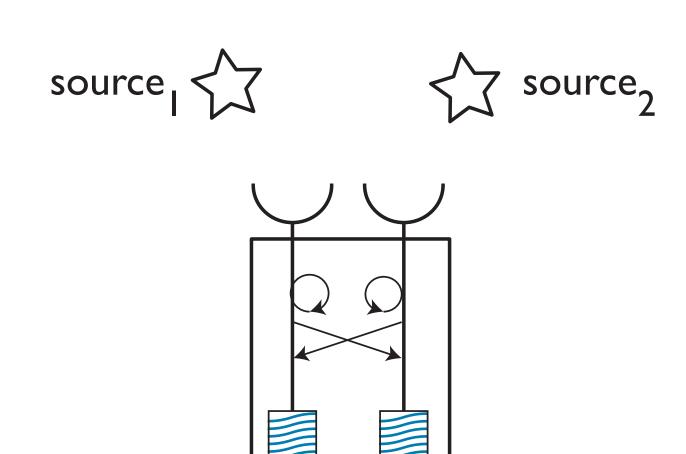


Complex environment => complex dynamics

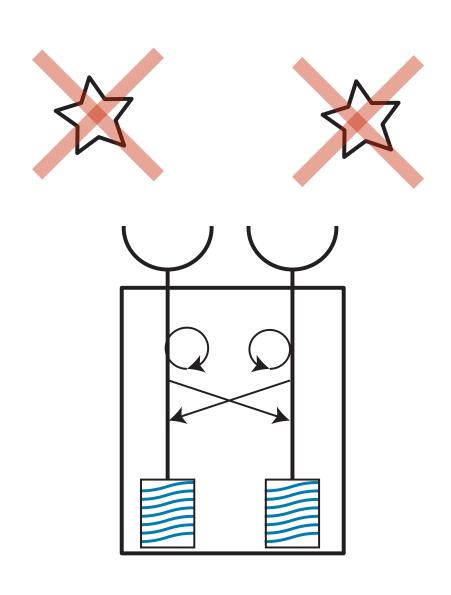
- transition to monostable for mono-modal distribution
- => instabilities lead to qualitative change of behavior



Beyond sensory-motor cognition...

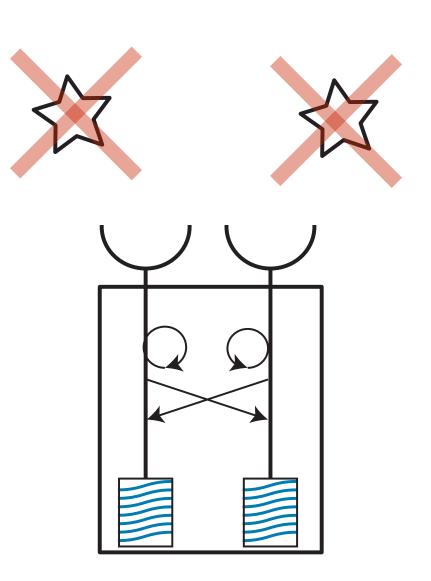


Beyond sensory-motor cognition...

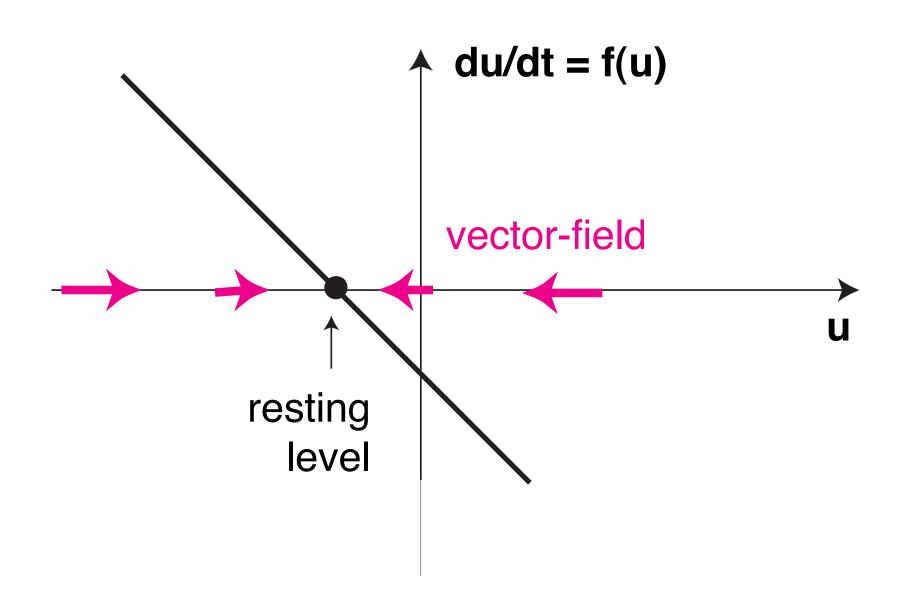


Beyond sensory-motor cognition...

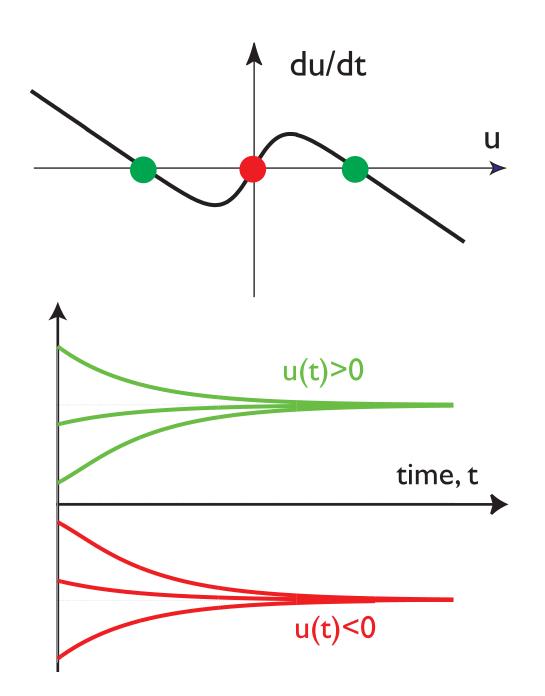
- if sensory information about source not always available on the sensory surface
- => working memory
- need "inner state" that is independent of body or sensors:
- => activation



Internal loops generate neural dynamics



Internal loops generate neural dynamics



Outlook

- neural dynamics
- DFT