## Neural Dynamics Part 2

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### Activation dynamics

activation, u(t), whose time course emerges from a neural dynamics

$$\frac{du(t)}{dt} = \dot{u}(t) = -u(t) + h \qquad (h < 0)$$

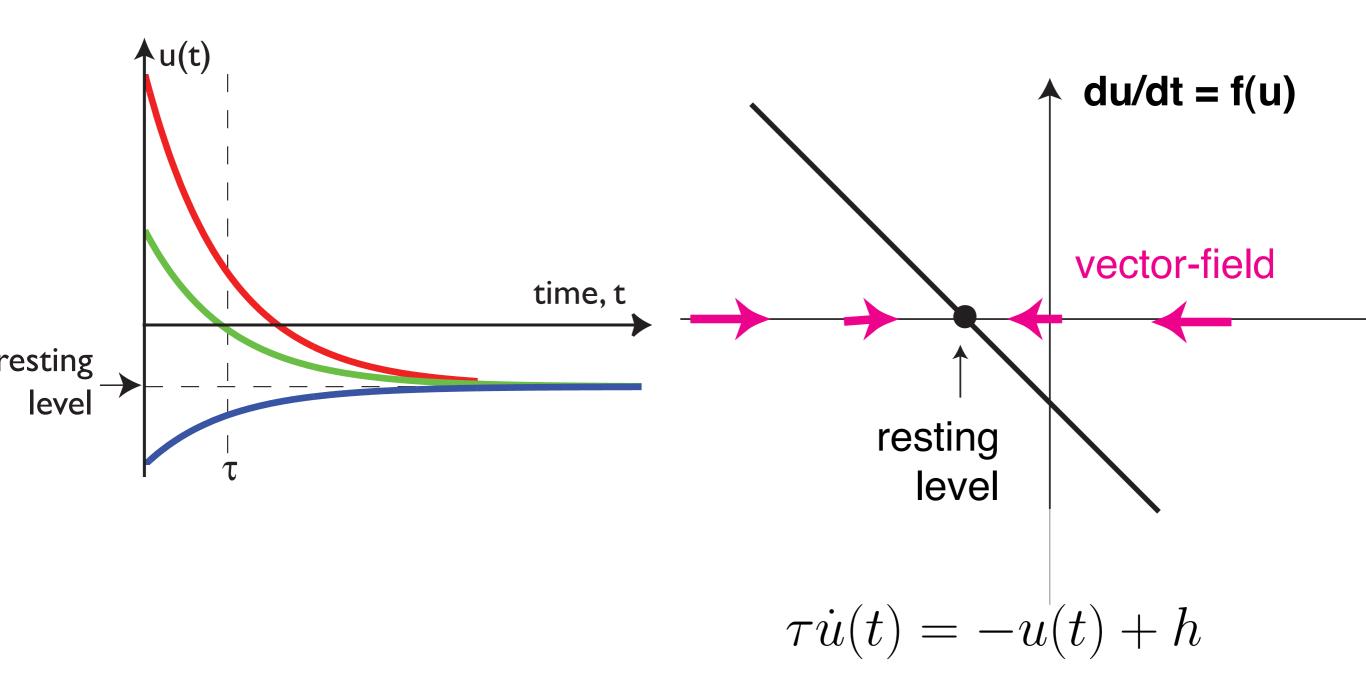
$$\frac{du/dt = f(u)}{\text{vector-field}}$$

$$\frac{du/dt = f(u)}{\text{u}}$$

### Neural dynamics

has a stable fixed point (attractor) at all times

to which activation relaxes



## Neuronal dynamics

$$\tau \dot{u}(t) = -u(t) + h + \text{ inputs(t)}$$

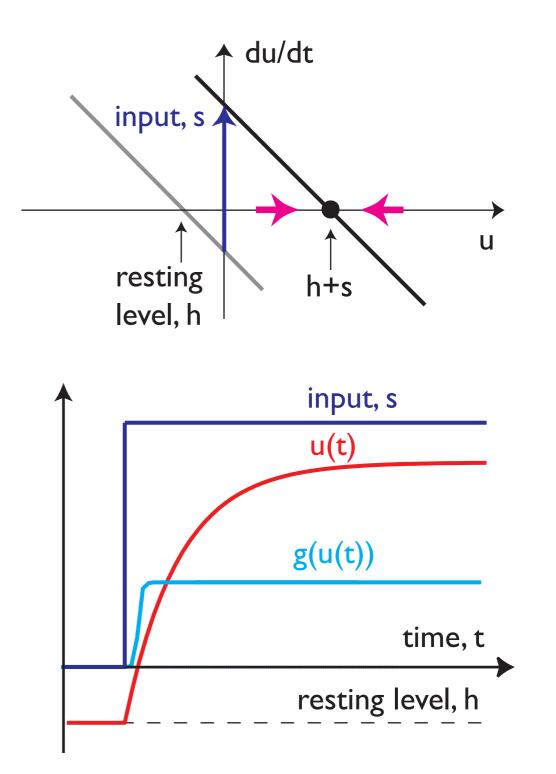
#### inputs are contributions to the rate of change

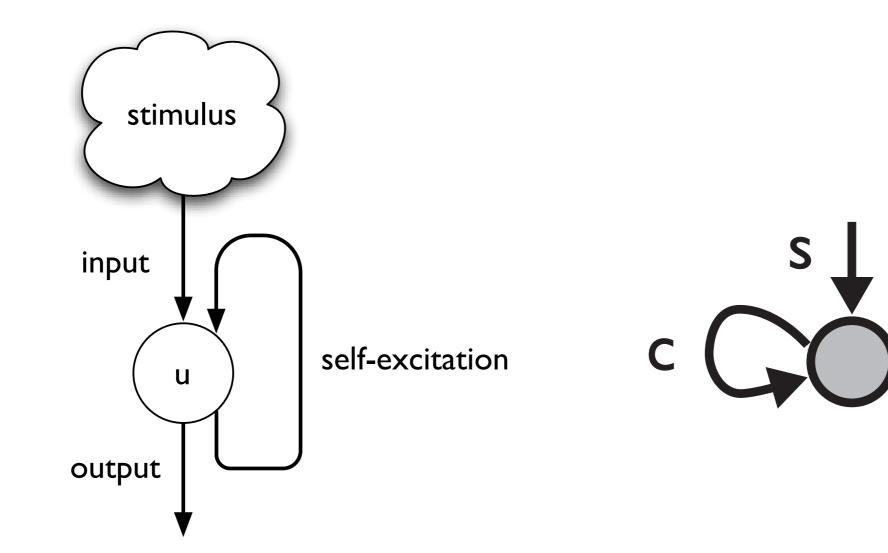
positive: excitatory

negative: inhibitory

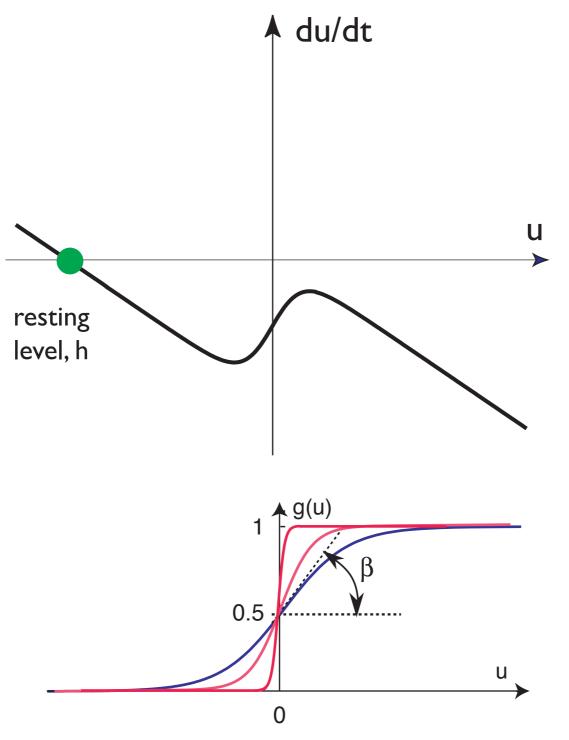
that shift the attractor

a shift which activation then tracks



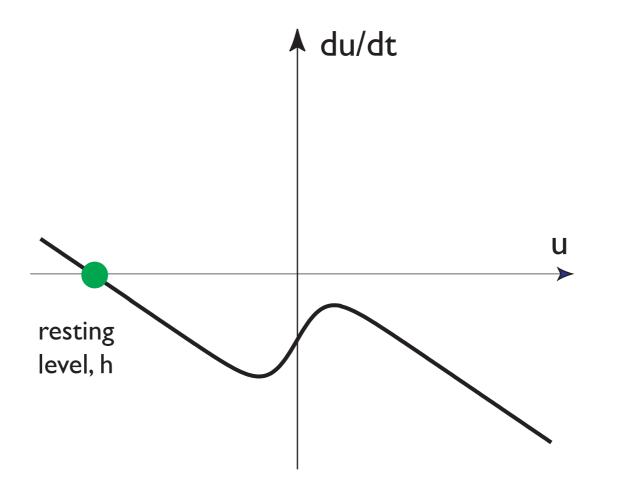


$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$



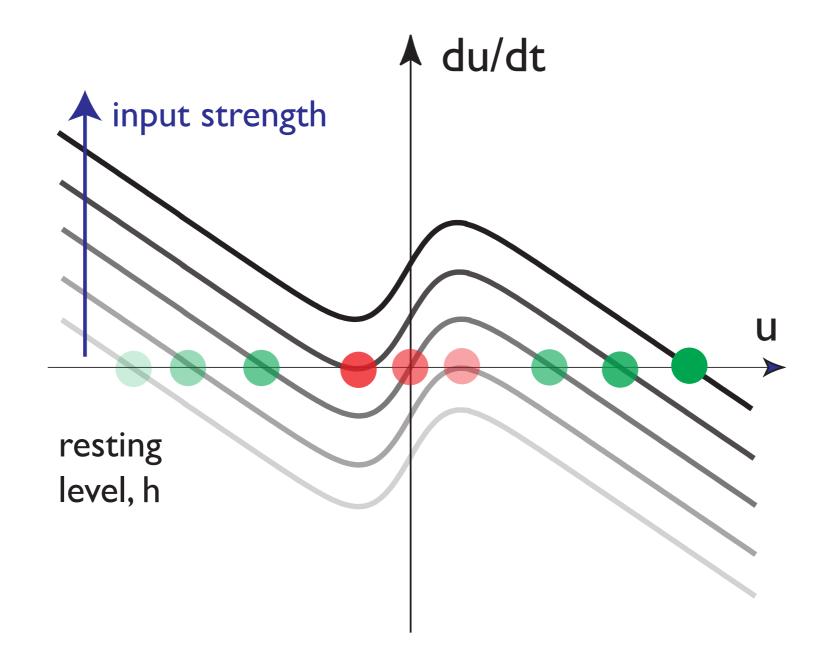
 $\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$ 

=> this is nonlinear dynamics!



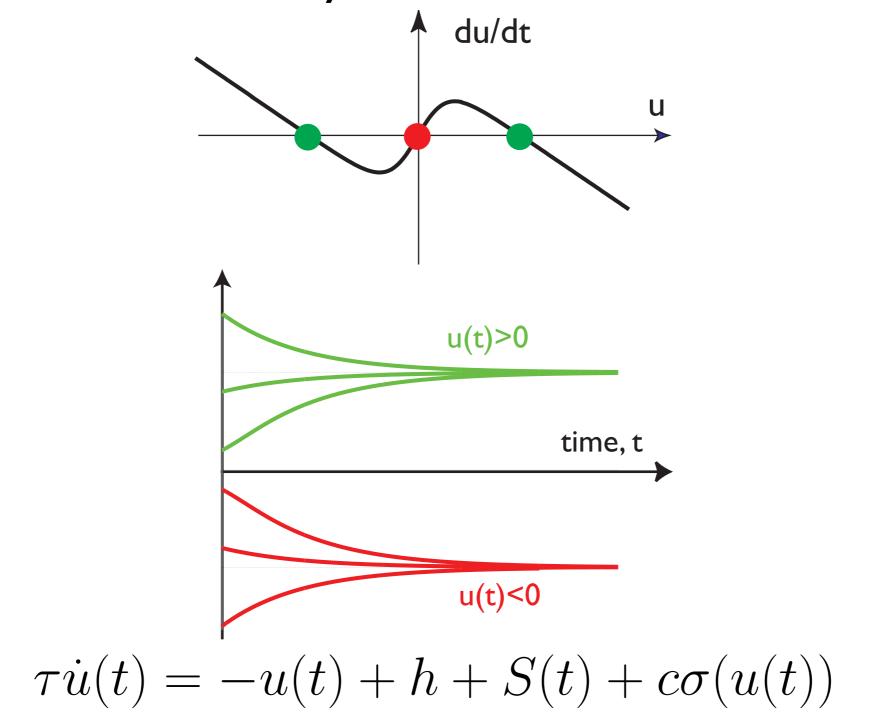
 $\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$ 

stimulus input

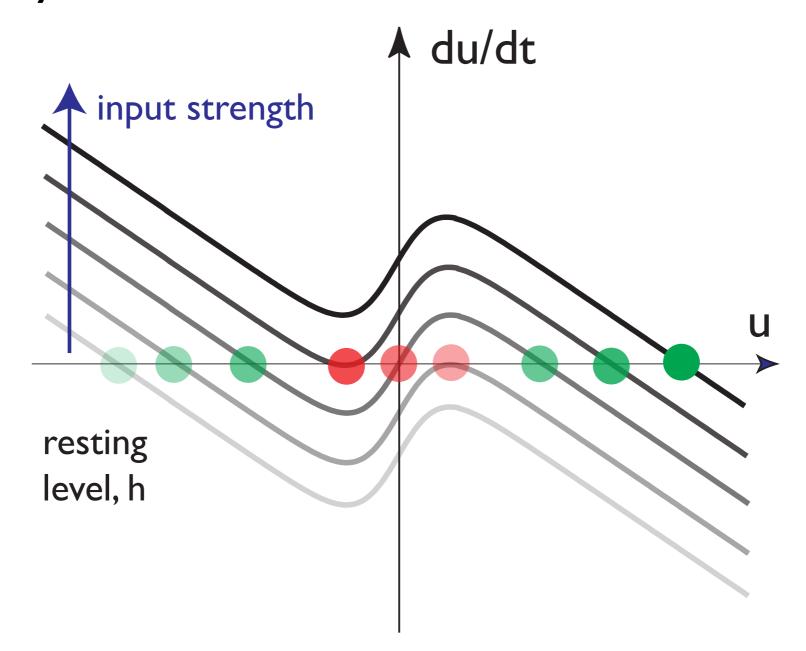


 $\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$ 

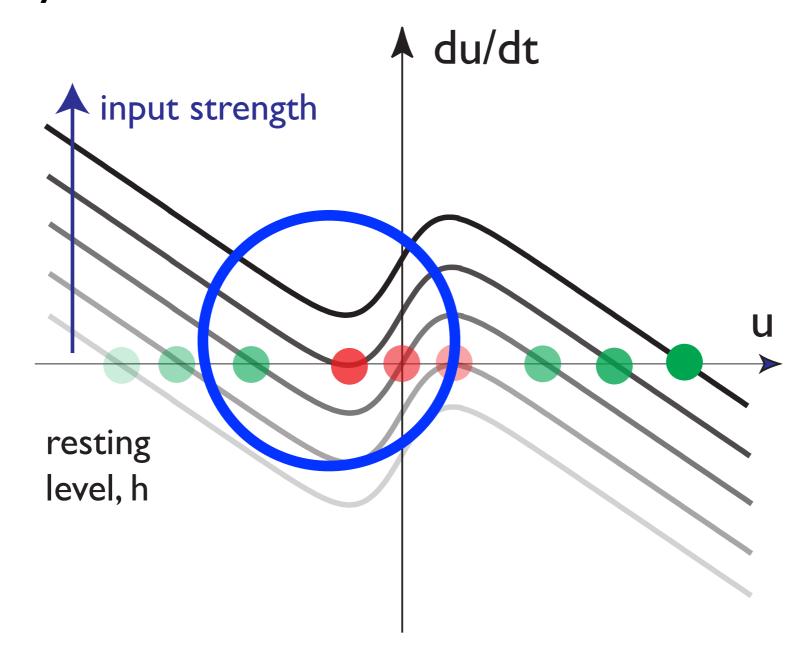
at intermediate stimulus strength: bistable=> essential nonlinearity



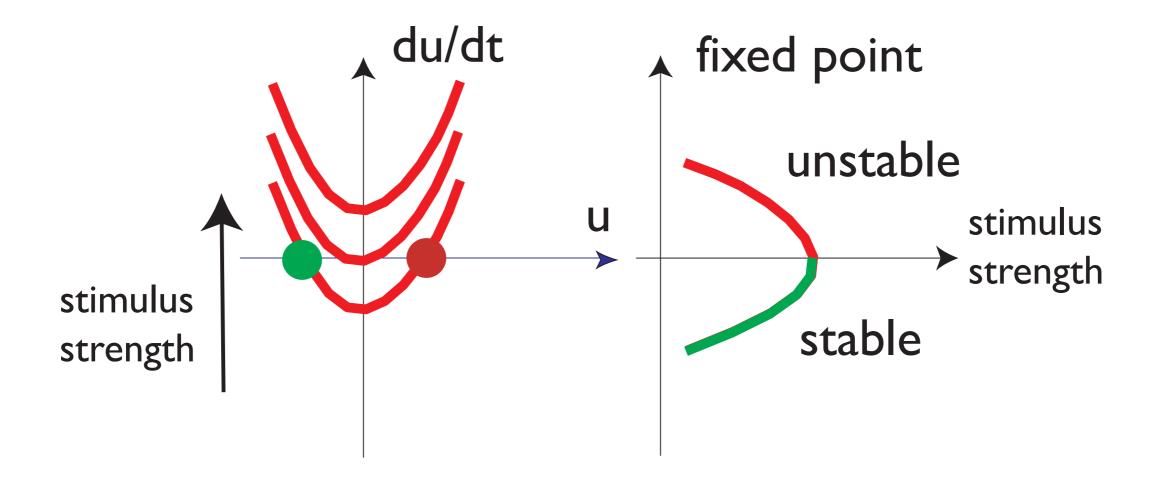
with varying input strength system goes through two instabilities: the detection and the reverse detection instability



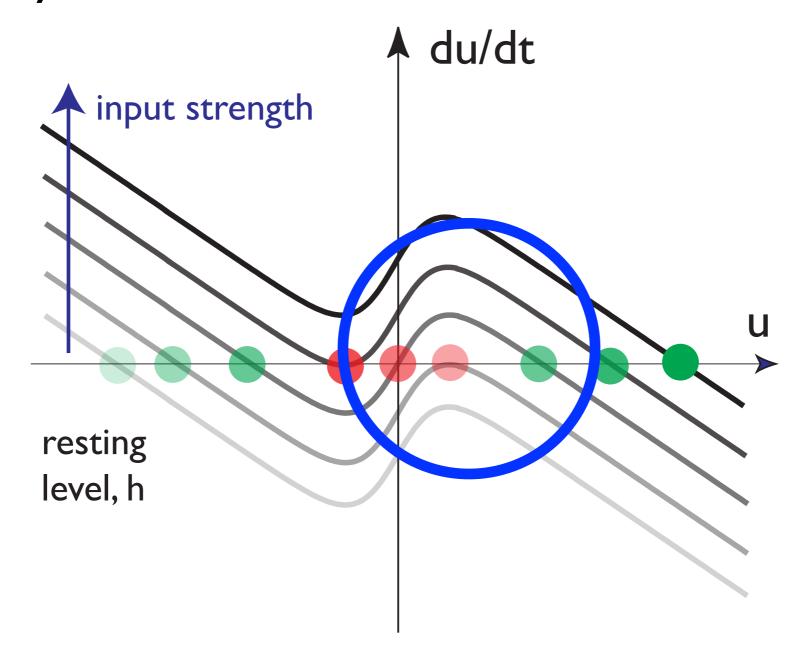
with varying input strength system goes through two instabilities: the detection and the reverse detection instability



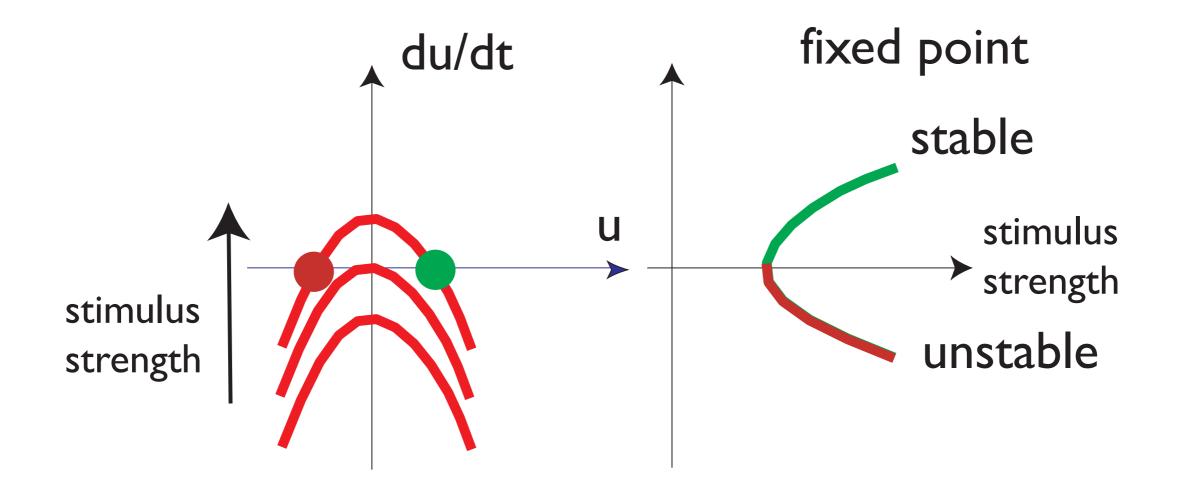
detection instability



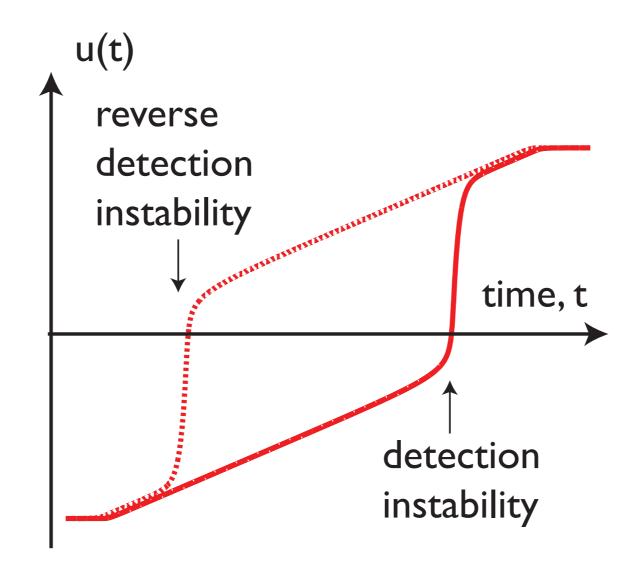
with varying input strength system goes through two instabilities: the detection and the reverse detection instability



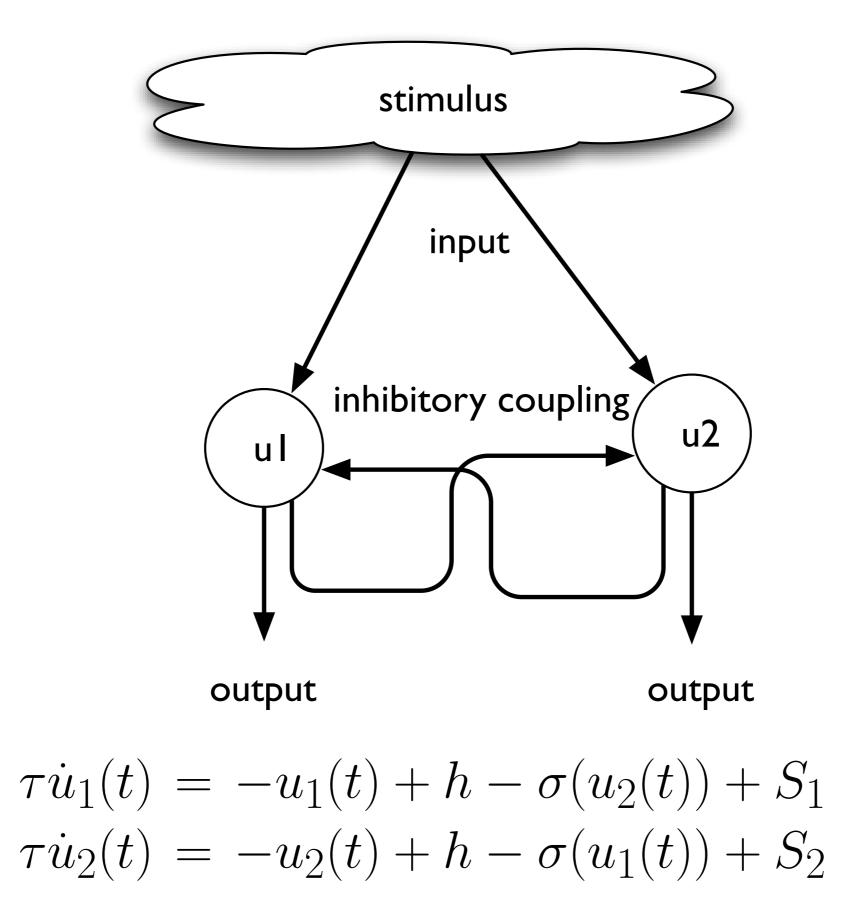
reverse detection instability



signature of instabilities: hysteresis





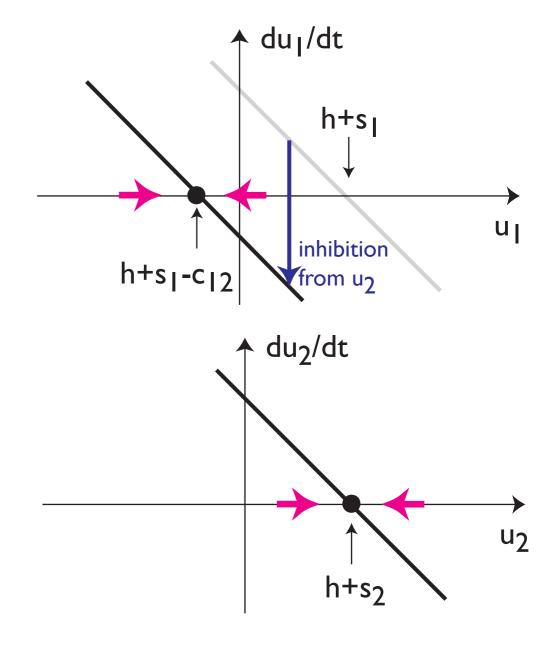


Interaction: the rate of change of activation at one site depends on the level of activation at the other site

mutual inhibition

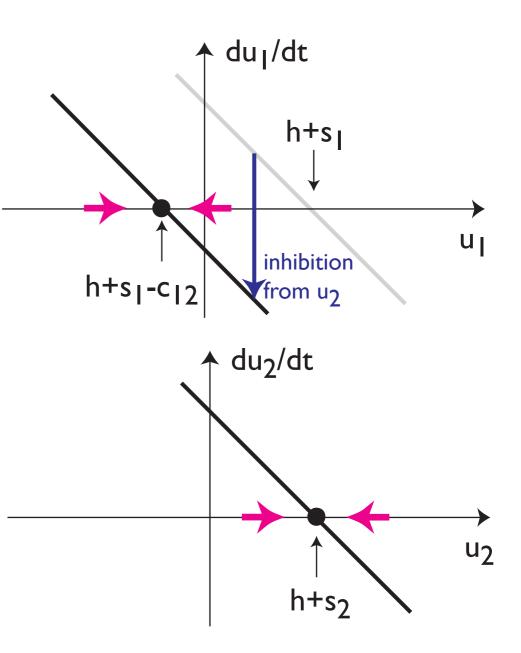
$$\tau \dot{u}_1(t) = -u_1(t) + h - \sigma(u_2(t)) + S_1$$
  
$$\tau \dot{u}_2(t) = -u_2(t) + h - \sigma(u_1(t)) + S_2$$
  
$$\uparrow$$
  
sigmoidal nonlinear

- to visualize, assume that u\_2 has been activated by input to positive level
- then u\_l is suppressed

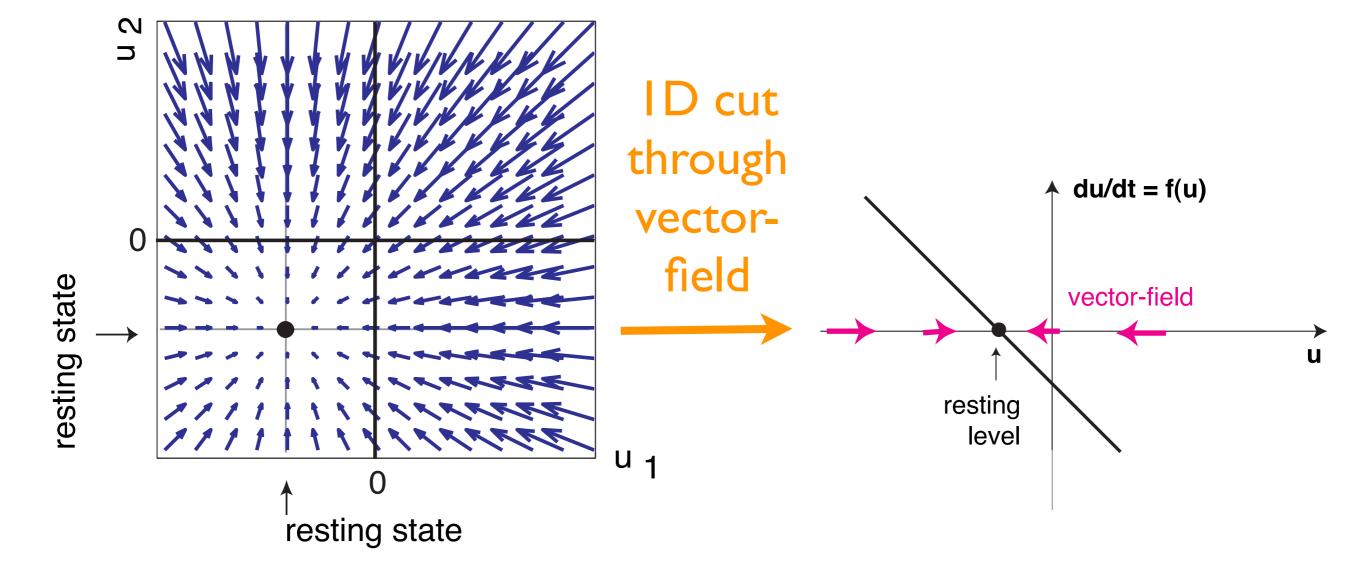


why would u\_2 be positive before u\_1 is? E.g., it grew faster than u\_1 because its inputs are stronger/inputs match better

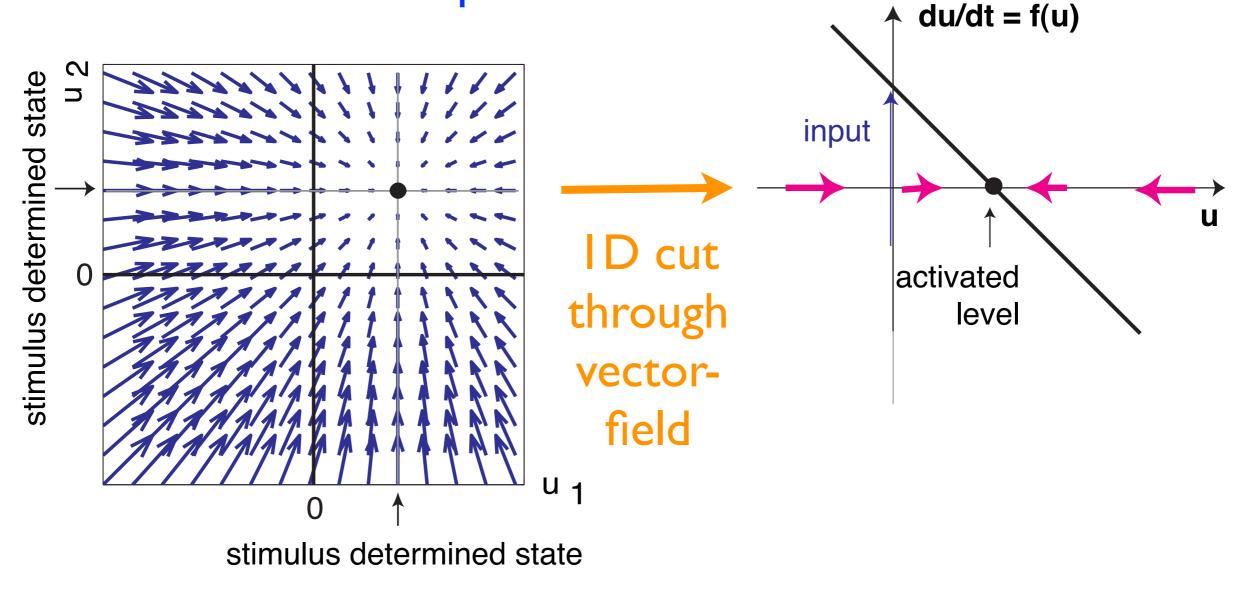
input advantage translates into time advantage which translates into competitive advantage



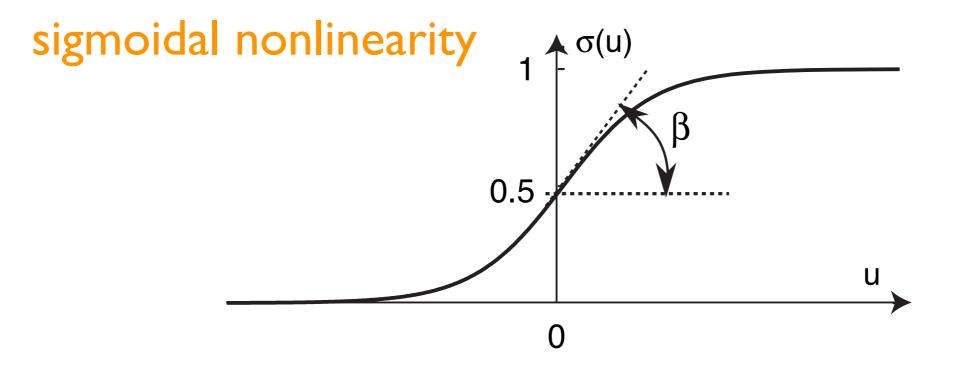




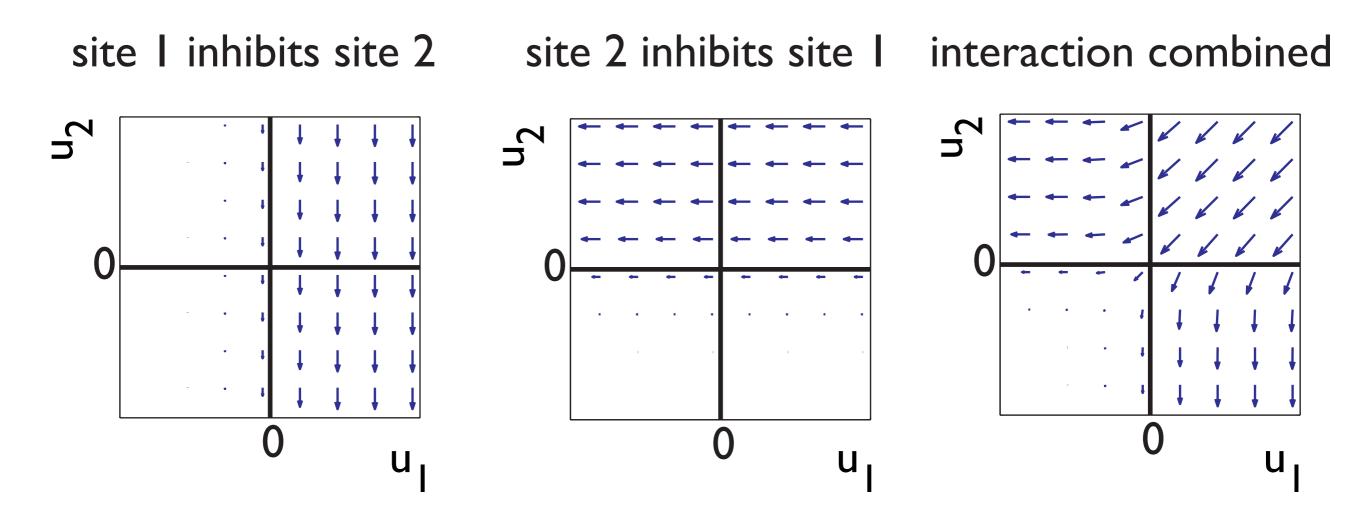
vector-field (without interaction) when both neurons receive input



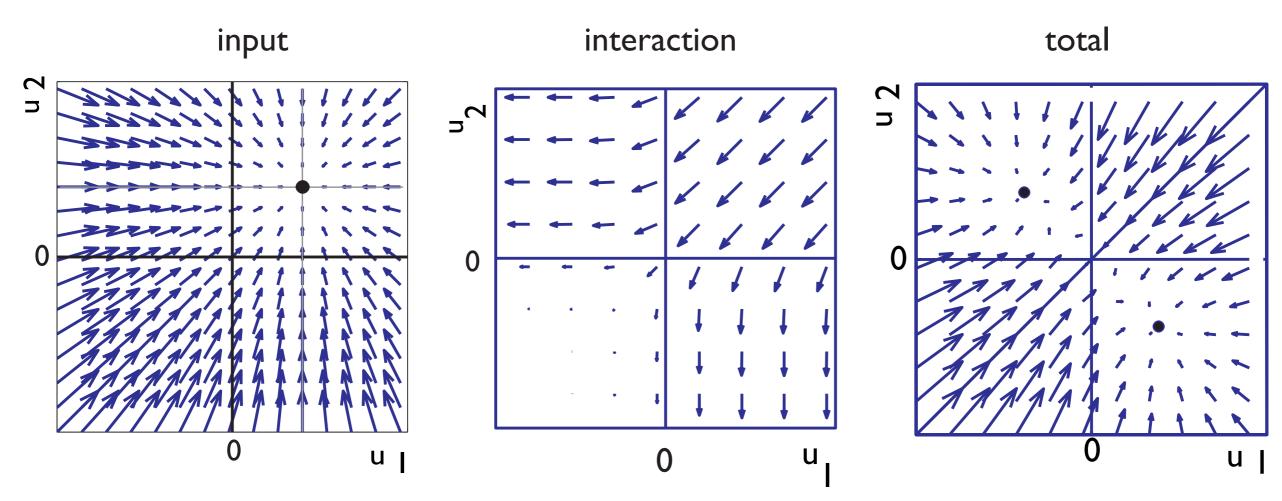
only activated neurons participate in interaction!

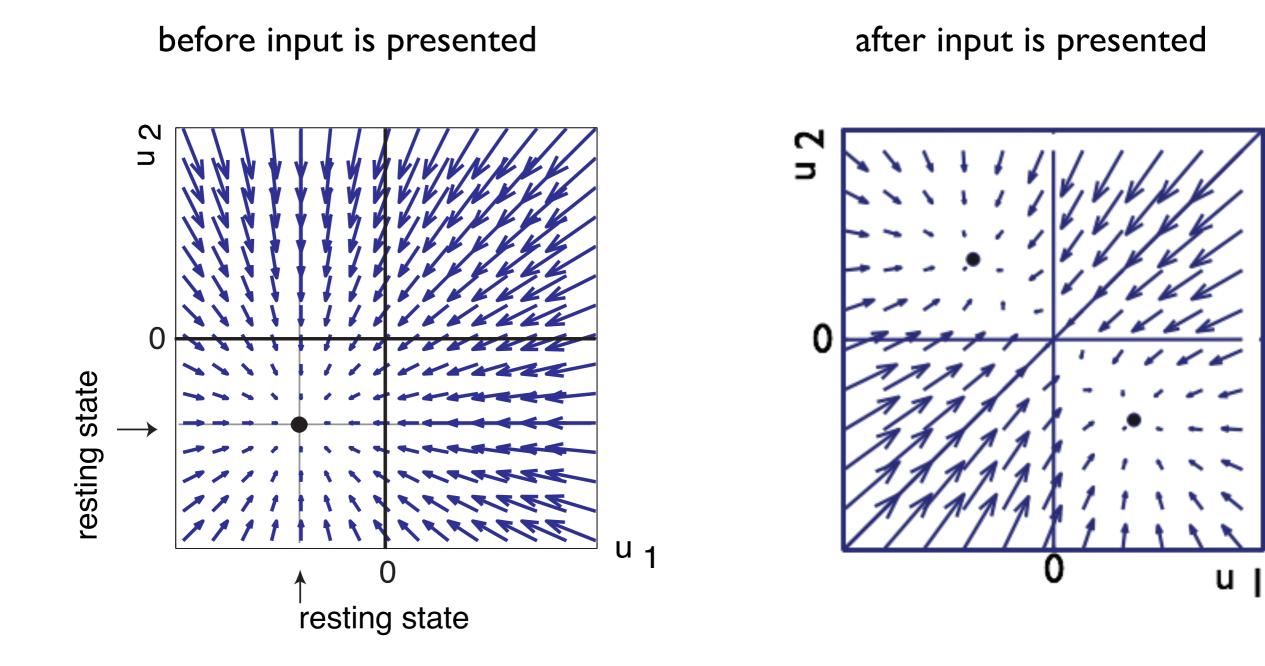


#### vector-field of mutual inhibition



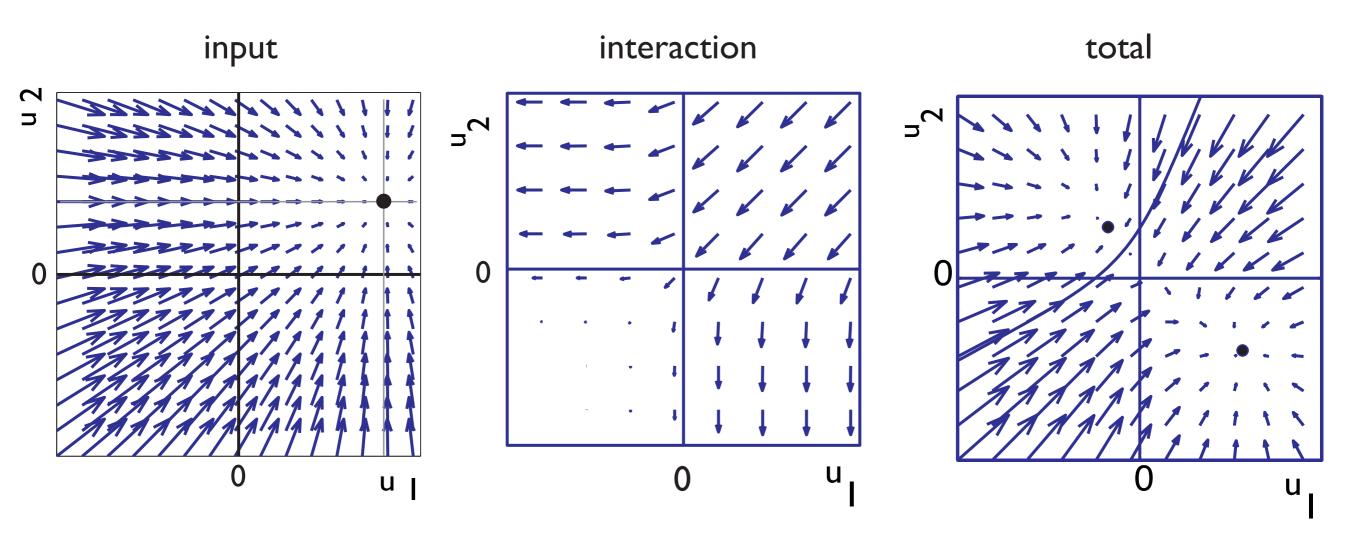
#### vector-field with strong mutual inhibition: bistable



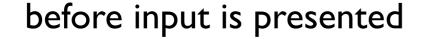


# Neuronal dynamics with competition =>biased competition

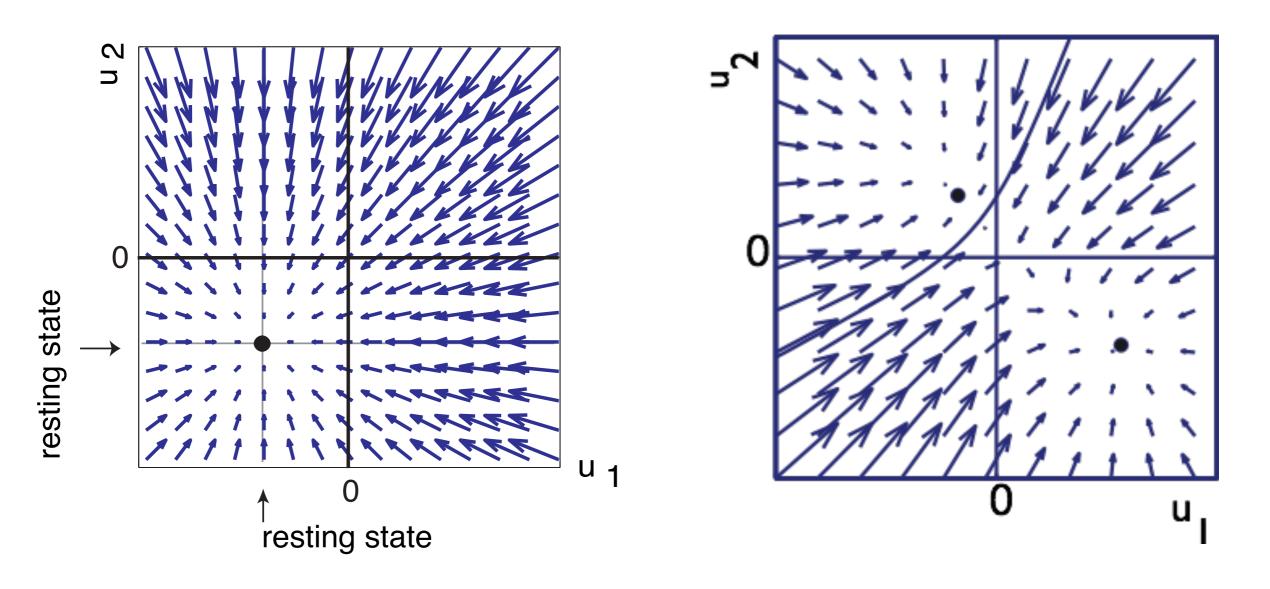
stronger input to site 1: attractor with activated u\_1 stronger, attractor with activated u\_2 weaker, may become unstable



## Neuronal dynamics with competition =>biased competition



after input is presented





### Outlook

- Where do activation variables come from? How does an activation variable come to "stand" for a behavior or percept ?
- How do discrete activation variables reflect continuous behaviors?

