# Embodied nervous systems

**Gregor Schöner** 

# Braitenberg vehicles

=embodied nervous systems with:

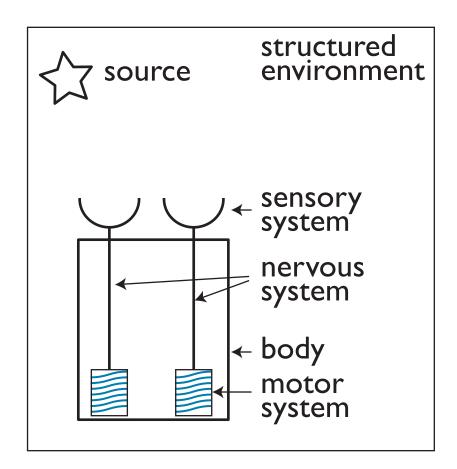


sensors

a nervous system

📕 a body

- + situated in a structured environment
- = emergent function



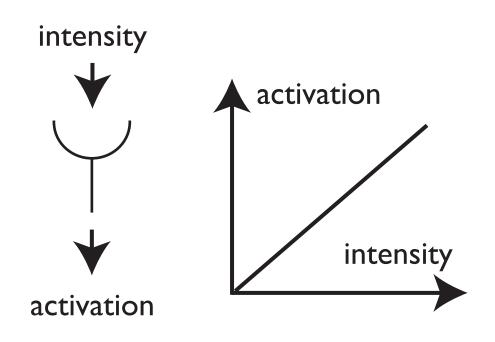
#### Sensors

defined by sensor characteristic =relationship between

#### the physical stimulus intensity

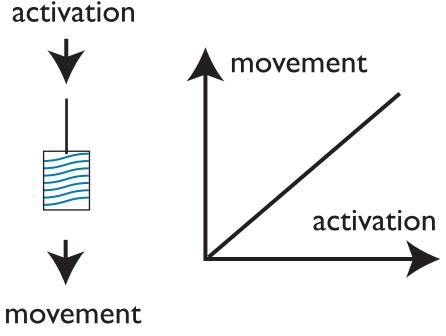
e.g., sound, luminance, chemical concentration, mechanical pressure....

and an activation variable



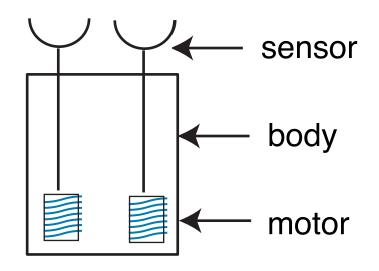
### Effectors

- defined by the motor characteristic =functional relationship between
- an activation level
- and a physical effect generated
  - for example: turning rate (rotations per minute rmp), force level, stiffness, ...)



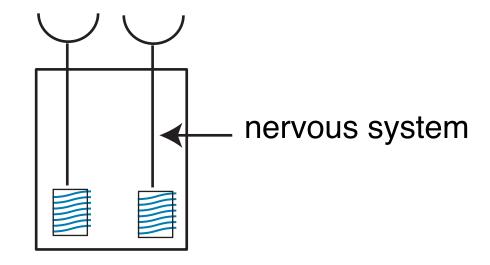
Body

#### the body links the sensors and effectors mechanically

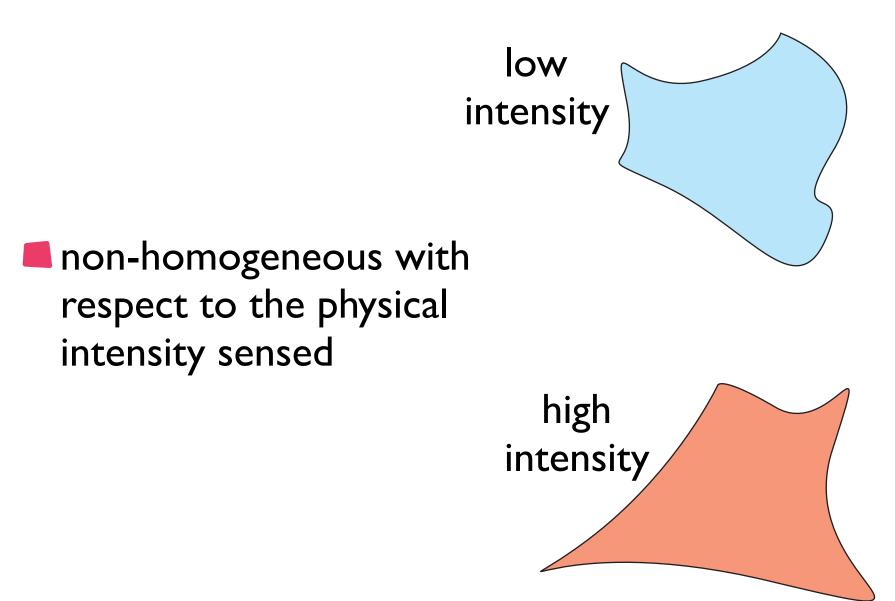


## Nervous system

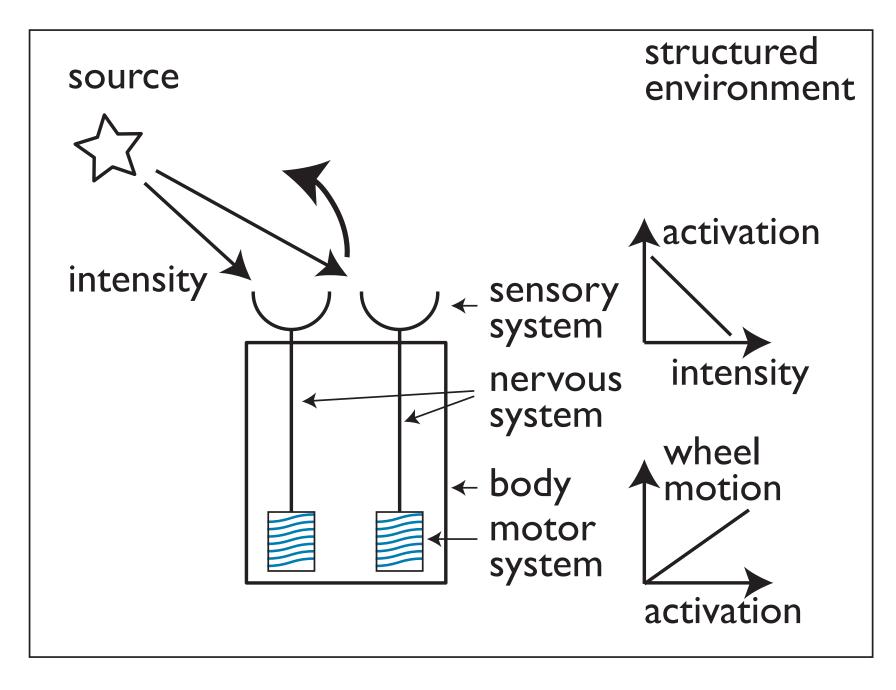
#### links sensors to effectors



#### Environment



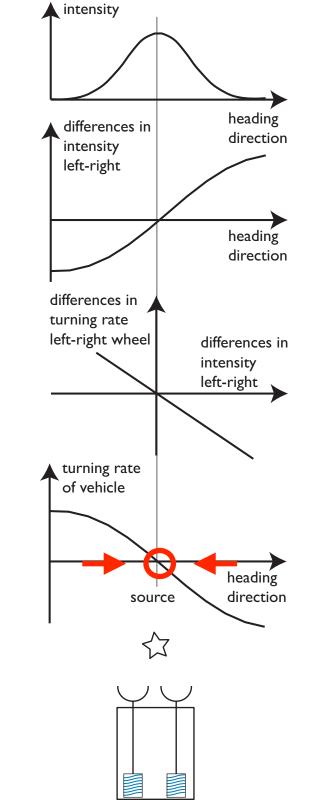
#### Emergent behavior: taxis

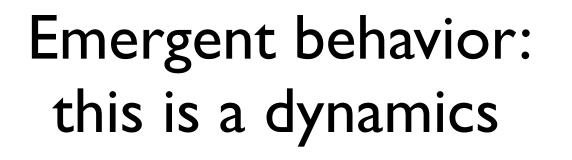


# Emergent behavior: this is a dynamics

feedforward nervous system

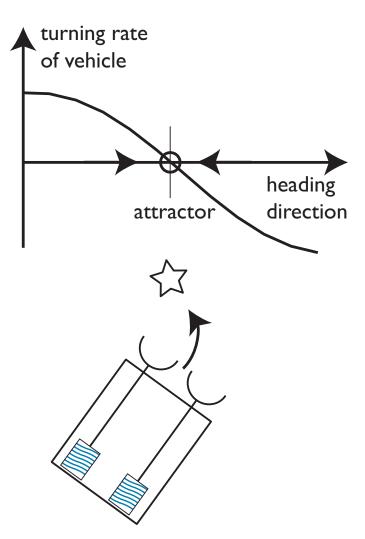
- + closed loop through environment
- => (behavioral) dynamics





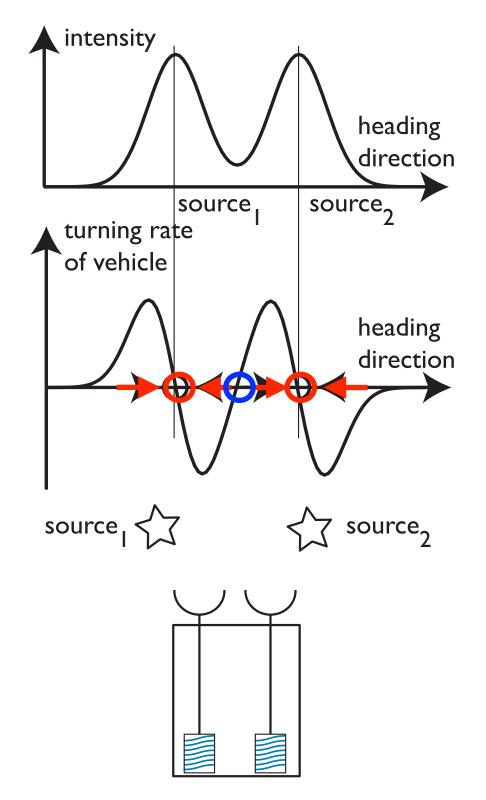
feedforward nervous system

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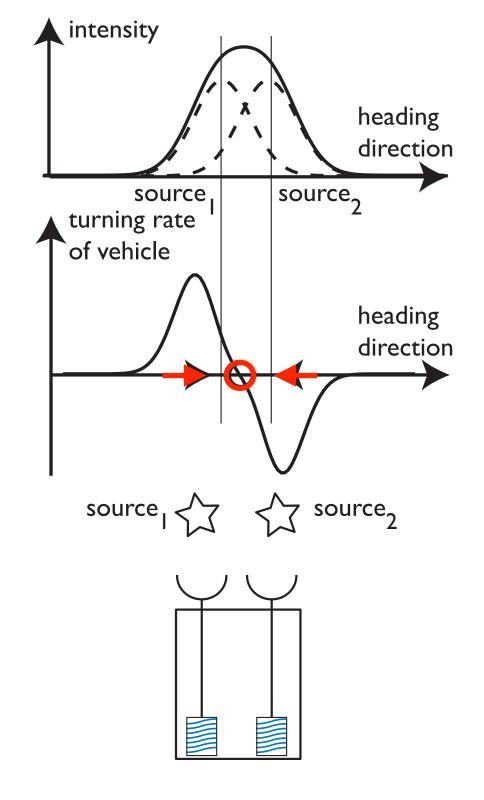
# Complex environment => complex dynamics

- bistable dynamics for bimodal intensity distribution
- => nonlinear dynamics makes selection decision



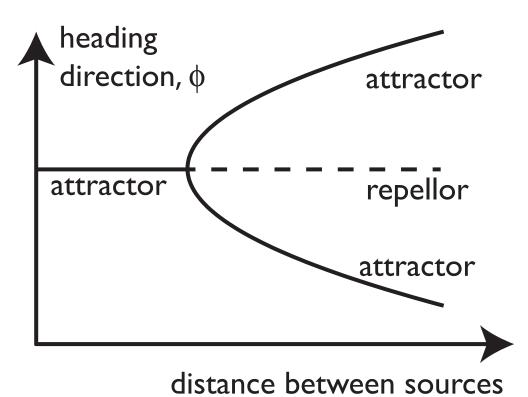
# Complex environment => complex dynamics

- transition to monostable for mono-modal distribution
- => instabilities lead to qualitative change of behavior



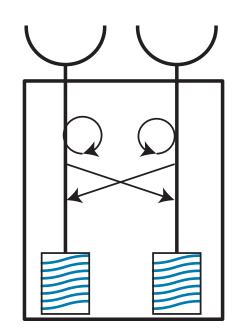
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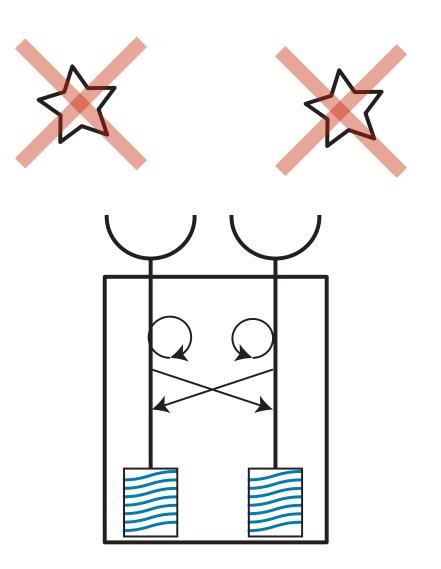


Beyond sensory-motor cognition...

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#### Beyond sensory-motor cognition...

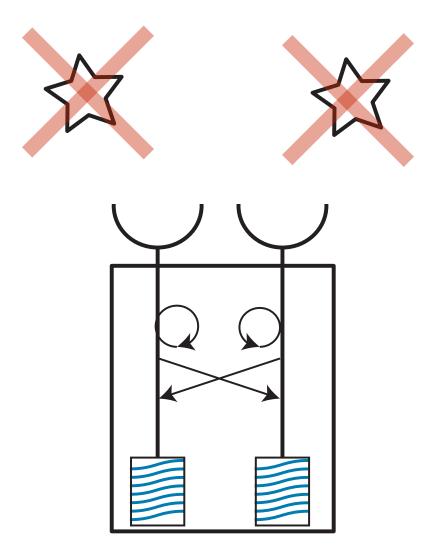


# Beyond sensory-motor cognition...

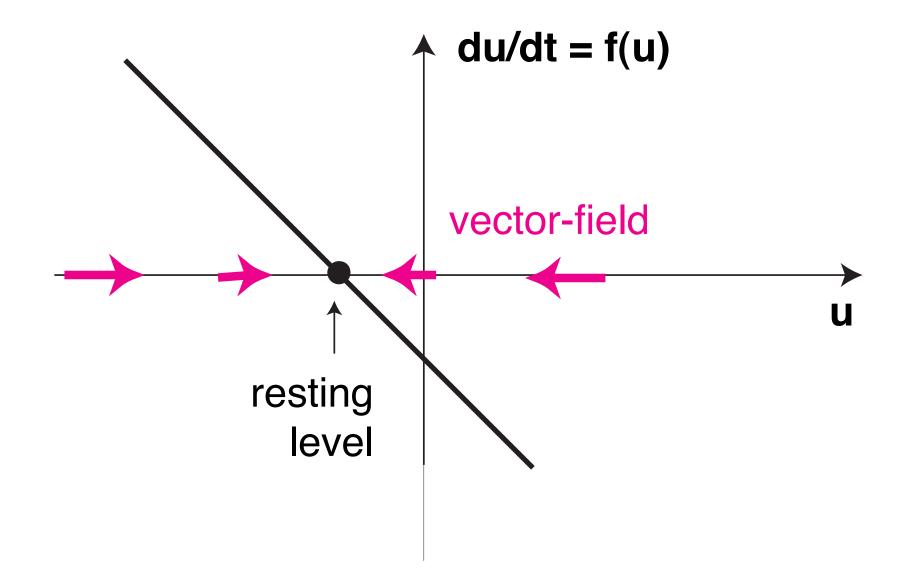
- if sensory information about source not always available on the sensory surface
- => working memory

=> activation

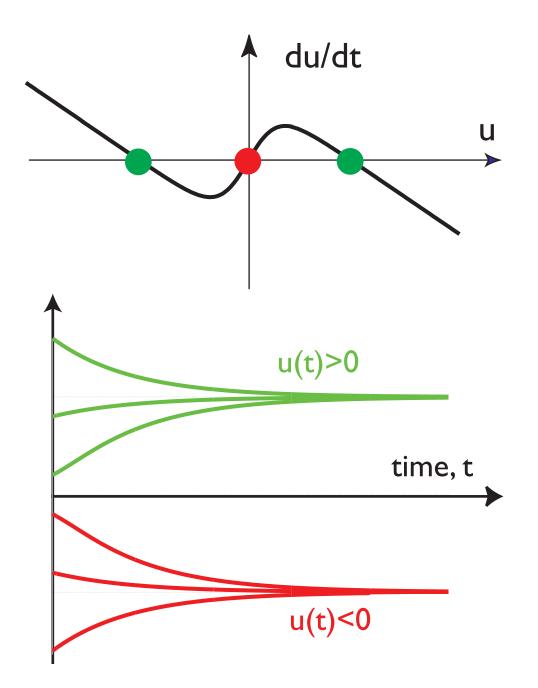
need "inner state" that is independent of body or sensors:



## Internal loops generate neural dynamics



## Internal loops generate neural dynamics



#### Outlook

neural dynamics

