# Hierarchical Slow Feature Analysis and Top-Down Processes

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#### Abstract

Top-down processes are thought to play an important role in the mammalian visual system, e.g., for interpreting ambiguous stimuli. Slow Feature Analysis (SFA) [4] on the other hand is proven to be an efficient algorithm for the bottom-up processing of visual stimuli [1, 2, 3]. Therefore it seems natural to combine bottom-up SFA with top-down processes. One major obstacle for this is the quadratic expansion step in our model. While we had limited success with top-down image reconstruction it seems that more fundamental changes are needed to solve the problems.

#### **Top-Down Image Reconstruction**

Due to the quadratic expansion there is no clear correspondence between the individual input and output components of a layer. As a first step towards resolving this issue we looked at the reconstruction problem: For a given output find a corresponding input that is similar to the training data.

## We combined the following techniques:

Gradient descent to minimize the quadratic error of the layer output.
Vector quantization to capture the distribution of the training set, providing starting points for the gradient descent.

### **Hierarchical Visual Model**

# Slow Feature Analysis (SFA)

Behaviorally relevant features of our environment generally change on a much slower timescale than the raw visual data. This inspired the slowness learning principle which has been turned into a well defined optimization problem [4] (fig 1.a):

Given a function space  $\mathcal{F}$  and a multi-dimensional input signal  $\mathbf{x}(t)$  find a set of instantaneous functions  $g_j(\mathbf{x}) \in \mathcal{F}$  such that the output signals  $y_j(t) := g_j(\mathbf{x}(t))$ 

minimize 
$$\Delta(y_j) := \langle \dot{y}_j^2 \rangle_t$$

under the constraints

$$\langle y_j 
angle_t = 0$$
 (zero mean),  
 $\langle y_j^2 
angle_t = 1$  (unit variance),  
 $\forall i < j : \langle y_i y_j 
angle_t = 0$  (decorrelation and order)

• Winner-take-all for overlapping receptive fields (based on the error).

# First Layer Reconstruction

The optimization for the lowest layer works reasonably well for synthetic stimuli (fig 2).



# **Second Layer Reconstruction**

On the second layer the reconstruction result is severely degraded (fig 3).

# **Invariant Object Recognition**

We train a hierarchical feed-forward model for invariant object recognition [2] (fig 1.c). Each network layer is based on the SFA algorithm and includes quadratic expansion.

**1.a** Slow Feature Analysis



#### 1.b Model Input Examples





#### 1.c Architecture of the Hierarchical Model based on SFA



# 3.a full image original Image (include linear step in optimization) original Image Image Image reconst. Image Image Image

At the third layer no sensible reconstruction was possible.

#### Conclusion

We conclude that our model is currently not able to adequately address top-down processes, due to the following problems:

• The quadratic polynomial function space leads to many local minima in the error function. In practise this is a huge problem, which is not

Most of the model software is now part of the "Modular Toolkit for Data Processing" (MDP) open source project [5].

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solved by the vector quantisation or any other technique we tried.

• The overlap of the receptive fields does lead to conflicts, which are not adequately resolved at higher layers by the winner-take-all approach.

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